

R&S® EVSG1000 / EVSF1000 / EVSD1000 Release Notes

Firmware Version 01.51

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The software makes use of several valuable open source software packages. For information, see the "Open Source Acknowledgment" provided with the product.

The following abbreviations are used throughout this document: R&S®<Product Type> is abbreviated as R&S<Product Type>.

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1 Information on the current version and history

1.1 Version 01.51

Released 5.2023

Release 1.51 is a bugfix release which fixes a serious bug in the calculation of the “sum” modulation values when using ILS 2F analysis mode (see remark on Release 1.50).

It also fixes the ILS THD-calculation, which was incorrect in all former versions. It is now implemented as $THD = \text{sq.root}(V_2^2 + V_3^2 + V_4^2) / V_1$.

Compatibility

Version	Component
EVSG1000, EVSF1000, EVSD1000	Device
Rev 3.00 +	RX-Board
Rev 4.00 +	EVSG/EVSF Mainboard
Rev. 2.07 +	EVSD Mainboard
V 1.01	Keyboard Controller
V 1.11+	Startup-Controller

Firmware package contents

Version	Contents
01.45f	EVsx1000 Software
00.50.00	RX FPGA
00.09.09	GBAS FPGA

Modified functionality

Functions

Calculated “sum” modulation values were distorted (CR424)

The application crashed occasional during shutdown (CR423)

ILS THD calculation did not take the fundamental into account. This was wrong in all former versions of the firmware. (CR425)

Known issues

Known Issues

THD calculation for NDB is not using the fundamental. While this bug was fixed for ILS (see above) it is still present for NDB. (CR430)

The “known issues” from R01.50 are not fixed.

1.2 Version 01.50 – do not use

Released 2.2023

Release 1.50 is the first release that supports the EVSD1000 drone based measurement receiver. The EVSD shares most of its hardware with the EVSG and EVSF, just in a much lighter housing, specialized for drone application. Therefore the software is shared between the three devices.

While the measurements are the same as Release 1.40, there are additional interfacing possibilities for GNSS and Wi-Fi. They are specially intended for the EVSD, but the existing EVSG and EVSF may also benefit.

Besides of this there are important improvements and bug fixes.

After the release of R1.50 it was found that the calculation of the “sum” DDM/SDM values in 2F mode is distorted when there is a small offset (<100Hz) between demodulator placement and real carrier frequency. It is highly recommended not to use this version and update to the fixed version 1.51.

Compatibility

Version	Component
EVSG1000, EVSF1000, EVSD1000	Device
Rev 3.00 +	RX-Board
Rev 4.00 +	EVSG/EVSF Mainboard
Rev. 2.07 +	EVSD Mainboard
V 1.01	Keyboard Controller
V 1.11+	Startup-Controller

Firmware package contents

Version	Contents
01.45b	EVSx1000 Software
00.49.12	RX FPGA
00.09.09	GBAS FPGA

New functionality

Functions

Support for R&S EVSD1000 VHF/UHF NAV/DRONE ANALYZER

Support for R&S EVSG1-Z5 Data link module (Wi-Fi)

DJI M300 Drone together with R&S EVSD1-Z20 provides GNSS location data to the EVSD

GNSS/GPS receivers can be connected by LAN (TCP/IP)

Modified functionality

Functions

Datrecorder export to USB now uses the selected units for DDM, SDM, level and CRS/CLR (CR410)

Datrecorder Listview was slow, especially when the device is very cold or warm. (CR409)

Bargraph Color-Indications are now according to datasheet limits (CR405)

Bugfix: GBAS constellation view failed whenever level variation within the burst is > 4dB (CR389, CR397)

GBAS auto-ranging is now intentionally slower and accepts overload conditions, as long as the signal itself is not clipped. This reserves more dynamic to receive slots with small signals while slots with large signals are present (CR390, CR373)

Bugfix: VOR ID decoding got weak with small signal levels (CR381)

GBAS data export to USB: Performance is improved by factor 2, and there are no longer separate files for each slot. Instead the slot data is exported in a single text file. (CR380, CR379)

ID decoding: the "ID statistic" mode delivers the most probable ID code, based on former transmissions. This avoids confusion of flight inspection systems, because single decoding's on weak signals may be wrong (CR378)

Hardkeys SINGLE and RECORD no longer have autorepeat (CR377)

Keyboard-Beep did not work for UNDO and REDO (CR375)

Bugfix: Some units show a HW-Error on the first mainboard test-voltage, resulting in an UNCAL condition (CR374)

Bugfix: when the EVSG1000 was switched off immediately after recording data, the data was occasionally lost (CR369)

Bugfix: GBAS data recording: the GPS/GNSS time information showed an error of 10,5s every 1h 11minutes because of a variable overflow (CR368,CR353)

In GBAS constellation diagram the first 5 symbols were missing (CR367)

GBAS data-logging did not work at all in R1.40. When re-loading or exporting a list, the files did not have reasonable content (CR358)

New remote command GETUNCAL to query the UNCAL condition (CR357)

When the internal SD card is broken or absent, SW update or data recording is no longer possible. This was a problem for the underlying root filesystem, resulting in an unbootable device (CR337/356)

ILS 1F/2F autotune: In SW releases < 1.40, the autotune RETUNED a signal when the frequency changed. In R1.40 the autotune LOCKED the frequency forever if a valid ILS signal was detected. Both strategies have advantages and disadvantages, therefore the setting is now configurable (CR330)

GNSS/GPS positions are exported in degrees-minutes-seconds. For compatibility reasons, this remains the default, but an additional export mode "decimal" is now available (CR140)

TCP/IP port 8090 offers a bi-directional access to a connected GPS/GNSS receiver. It's possible to see the incoming messages, or to send configuration data to the GPS/GNSS receiver.

Known issues

Known Issues

Datrecorder: the time column is named "GPS-Time" and shows the time information as it comes from a GNSS/GPS receiver. This is inaccurate, because the receiver sends a "UTC-Time", while the term "GPS-Time" is a GPS-internal reference with a certain offset to UTC. This will not be corrected to maintain compatibility

The Wi-Fi Country Code can be selected, but it does not seem to have any effect (CR416)

EVSD: When a battery and external power supply is present the status shows "charging suspended". This is misleading, as the EVSD has no charger capabilities. (CR 414)

When the PPS-input is used to sync the GBAS frames, the polarity is different from EVSG: while the EVSG/EVSG uses a rising edge, the EVSD uses a falling edge (CR422)

1.3 Version 01.40

Released 8.2020

Release 1.40 offers the new option "EVSG K7 LF Analysis", which makes use of the LF In connector of the EVSG and EVSF (for EVSF option B4 is required).

It is now possible to analyze LLZ, GP and VOR signals in baseband, which is needed to check test outputs on ground installations. LLZ and GP can also be analyzed on a "Low IF" carrier, for example on 8 kHz.

In addition the K7 enables a new measurement mode for NDB, to analyze level and ID characteristics of NDB installations.

Besides of the new features there are major bugfixes and improvements. Most notable are improvements in autoranging (Attmode "AUTO"): the number of ranges is increased from 3 to 6, so level adaption is more precise and the receiver is more immune to effects like cross modulation. Thanks to a higher resolution in signal procession spikes that appeared whenever the autorange switched from one range to another could be largely eliminated.

Important remarks

Release 1.40 performs an improved selftest that may locate internal hardware issues which remained undiscovered in earlier versions. In these cases the EVSG/EVSF will indicate UNCAL after the update. If the UNCAL remains after an autocalibration, please contact Rohde&Schwarz Service.

Please be aware that Release 1.40 will not be able to read and visualize old data recordings. There is simply no access to old recordings. A "factory preset" will delete these recordings and free disk space.

Please export old data recordings before performing the software update.

Compatibility

Version	Component
EVSG1000, EVSF1000	Device
Rev 3.00 + (*)	RX-Board
Rev 4.00 + (*)	Mainboard
V 1.01	Keyboard Controller
V 1.11 +	Startup-Controller

(*) NDB will work on all units, however existing units offer a limited performance (see datasheet).

If you need full performance on an existing EVSG/EVSF unit, please contact R&S service.

Firmware package contents

Version	Contents
01.39m	EVSG1000 Software
00.49.10	RX FPGA
00.09.07	GBAS FPGA

New functionality

Functions

EVSG1-K7 LF-Analysis: Measurements on LLZ, GP and VOR baseband signals as well as NDB analysis

LLZ/GP Autotune: Its now indicated if the algorithm is searching for a signal, or checking the signals validity, or finally locks on a frequency. When its locked, the frequency is no longer retuned. This

increases stability in difficult receiving circumstances, but requires attention if the transmitter changes its frequency during operation. (CR260)

A new flag "VALID" is generated in LLZ, GP and VOR. A signal is rated as VALID when its S/N and modulation values are inside typical limits. In this case,, the DDM or bearing value is printed in green. Please note that this only indicates that the signal appears to be an ILS or VOR signal; this does not mean that the signal is suitable for navigation, as this depends on other circumstances as well (position, distance,...) (CR261)

Improved selftest capability: Internal autocalibration values are checked carefully for integrity, and whenever they are out of limit the device throws an error message and indicates an UNCAL condition. (CR 3)

Autoranging has produced spikes in measurements whenever the range was switched. An improved signal processing with higher internal resolution switches ranges without producing spikes. However there might be a small remaining spike only when changing from NORM to LOW NOISE. (CR236).

Hostname is built from device name and serial number. This is only done when performing a "factory preset" (CR267)

A password for the VNC server can be activated. It is always "instrument", so it does not add much security, but it helps for security scanners who rate open VNC as security issue (CR263)

AF Spectrum / Time domain: RF level is displayed in status area (CR239)

Trigger functionality also for remote data streams (CR154)

VOR Subcarrier signal can be visualized in AF Spectrum and AF Time Domain (CR94)

Modified functionality

Functions

Setup Inventory shows 2 serial numbers, the "base unit" and the "K" number. Only the "K"-number is relevant, therefore its now shown at the first position (CR332)

VOR Bearing filter is renamed to "Multipath filter". However the functionality is not modified (CR319)

AGC also for "Demod Out": makes sure the signal appears with a constant level, not depending on the RF level. It's also possible to have the demodulated signal with or without DC.

Upcoming devices will show the inventory data of the rear-connector board. (CR274)

Remote command "FACTORY_PRESET" is used to reset all parameters to default, which is a common task when the EVSG/EVSF is controlled by a software. It was found that occasionally the execution was delayed by about 20s. So if meanwhile the control software makes settings, they got erased unexpectedly. This release fixes this bug and makes sure that the READY indication only comes when the command is internally executed (CR268)

Autotune LLZ/GP 2F: improved search algorithm that takes ICAO frequency limits into account (CR258)

EVSG without K1: CRS and CLR view was not working without K1, however the K1 only enables the simultaneous measurement CRS|CLR. CRS and CLR now work without K1 (CR257)

Remote data stream: show reasonable and ascending index (CR255)

In R1.30 the EVSG did forget Errorlog entries → fixed (CR248)

Copy screenshots to USB: indication when the operation is finished (CR218)

GPS Undulation value (from NMEA GGA-message) delivered in data recorder and remote stream. This enables the user to calculate the altitude in WGS84. (CR77)

Known issues

Known-Issues

Online Help: Enter the User manual and go BACK to the overview. Then use rotary wheel → application crashes and needs to restart. Issue is present on this and all former versions. Use ESC key to leave the online help. (CR334)

ID decoding: when the code is slower than ICAO timings (>160ms for dot), decoding is not possible and might result in false results. However a maximum of 170ms is tolerated. (CR322)

When an ethernet cable is connected to a running EVSG/EVSF, it does not reliably detect the cable. No address is obtained from a DHCP server, and no connection is possible. Toggling the DHCP setting helps. This issue was never observed when the Ethernet cable is already plugged in while the device boots (CR299)

Trigger input and PPS sync needs more explanation.

Autoranging needs to take RF Overload into account. (CR235)

Export GPS position as floating point values for easier calculation (CR140)

1.4 Version 01.30

Released 7.2019

Release 1.30 introduces the new option "EVSG1-K25 I/Q data streaming" as an extension to the existing "EVSG-K21 data recording". It enables the EVSG1000 / EVSF1000 to stream and record I/Q samples of the signal with a bandwidth of 100 kHz while doing "normal" measurements in parallel. The recorded signal may be used for further analysis, or can be reproduced by a vector signal generator. It is also possible to get I/Q data as an infinite stream over network.

The VOR analysis mode (EVSG-K2) offers now more fine adjustment for bandwidth and filtering. It was found that measurements at low RF levels ($\leq -100\text{dBm}$) work best with measurement time $\geq 500\text{ms}$, FM BW at 1 kHz and "Bearing Filter" is set to "narrow". However these settings are not default and need to be set explicitly when required, for example in flight inspection.

Beside of that Release 1.30 comes with lots of optimizations and bug-fixes to increase performance and stability.

Compatibility

Version	Component
EVSG1000, EVSF1000	Device
Rev 3.00 +	RX-Board
Rev 4.00 +	Mainboard
V 1.01	Keyboard Controller
V 1.11 +	Startup-Controller

REMARK:

Please be aware that Release 1.30 will not be able to read and visualize old data recordings. There is simply no access to old recordings. A "factory preset" will delete these recordings.

Please save old data recordings before performing the software update.

Firmware package contents

Version	Contents
01.26f	EVsx1000 Software
00.43.00	RX FPGA
00.09.01	GBAS FPGA

New functionality**Functions**

EVSG1-K25 I/Q-data streaming: Record I/Q data internally and export to USB memory stick

EVSG1-K25 I/Q-data streaming: Stream I/Q data over network

EVSG-K4/K5 (GBAS and SCAT): Measurements are now possible without PPS signal. While this is very handy especially for field measurements, only the PPS signal can guarantee the correct slot order and meaningful values for "Sync Seq. Start"

EVSG-K4/K5 (GBAS and SCAT): Automatic RF Attenuator Mode (like in ILS mode etc.)

EVSG-K4/K5 (GBAS and SCAT): Counting of valid and failed messages

EVSG-K2 (VOR analysis): Configuration of AM30Hz and FM Bandwidth

EVSG-K2 (VOR analysis): Selectable bandwidth for FM and AM30 components and bearing calculation

EVSG-K2 (VOR analysis)-mode: Configuration of a frequency offset

EVSG-K6 (COM analysis): Simultaneous measurement of 1000Hz and 1200Hz test tones

ILS LLZ,GP,MB, VOR,COM: "Zoom-View" shows the most important values with big font

EVSF1-B4 (Slide in option): Support for "Demod Out", "Trigger_in" and "Audio-Out"

Support for multiple VNC clients

Modified functionality

Functions

Bugfix Data streaming: When connections were not properly terminated the EVSG/EVSF froze. This happened e.g. if the client crashes or is disconnected (CR219)

Bugfix: The GBAS decoder was out of memory after several days or hours of operation, depending on the signal content and active view. This caused application crashes and reboots (CR222)

Bugfix: When ILS-LLZ was in 2F and an autocal was started, the generated autocal values were faulty sometimes. This led to level inaccuracy of up to 50 dB (CR 184)

Bugfix: The EVSx was unable to decode VOR ID when 5% modulation depth is used. Limits were changed.

Improved timing when switching from "Low Noise" to "Norm" (and back) to reduce switching spikes (CR224)

Fixed a configuration flaw of the controller PC which may cause crashes, especially on high temperatures.

GBAS Burst view: Possible crashes when zoomed and an "OVERLOAD" occurs → fixed (CR223)

The ENTER key does no longer terminate data input. It takes the value, but the data input box remains active. This behavior is similar to other R&S-equipment.

ILS-LLZ: Frequency range is now limited from 70 MHz to 200 MHz, while ILS-GP is limited from 200 MHz to 410 MHz. This avoids the use LLZ mode to measure GP and vice versa

Data Recording: "Clear all Lists" deletes all lists of the current RX board and mode.

GPS: With no GPS the data is now filled with dashes. Former versions showed Zeroes.

Marker positions in RF/IF/AF-Spectrum and TD are stored when the device is switched off

Bugfix: "ID period" showed useless values before 2 ID were received (CR128)

Bugfix: EVSF did not store its error log when switched OFF (CR152)

Bugfix: GBAS Frame- and Burst View: Graphic showed increased noise floor because of limited internal resolution (CR157)

GBAS Burst View: Values are now shown with green/red background to indicate their status, like in Frame view (CR160)

GBAS: The valid/invalid classification is now based on the message-CRCs. It was based on the success of the FEC before, which does not necessarily indicate the signal is correct (CR 182)

VOR: The EVS300 compatible dataset ("FULL") now also provides the 60 Hz distortion value (CR 187)

BUGFIX: GBAS: Sometimes recorded messages were not decoded properly (CR 192)

Bugfix: EVSG/EVSF: Sometimes the settings were not correctly saved when the device was switched OFF (CR 203)

Bugfix: When the Energy Saver was activated and the display off, the missing display voltage was reported as failure and the UNCAL indication gets active (CR 204)

The VNC-server did not recover when the IP address changes. This was especially unpleasant when operating an EVSF. It was solved by using a more robust VNC server (CR205)

More Remote commands for many settings

Warning when the data export would overwrite an existing file (CR210)

ILS LLZ and GP: Residual FM with ICAO filtering also available in 2F (CR215)

Known issues

Known-Issues

LF IN / BASEBAND IN still does not support measurements. However an implementation is present and shall be ready in the next release

Missing configuration for GPS output: Export position as floating point number, Height as WGS84

I/Q data export: After 34 minutes the I/Q file is larger than 2GB and cannot be exported to a FAT-formatted USB stick. The EVSG/EVSF cannot handle NTFS formatted media. The only way is to use a stick formatted with a Linux-filesystem (ext2/3/4). On MS Windows, a tool like "ext2explorer" may help to import the data.

For longtime I/Q recording it is recommended to stream I/Q data over network which does not have any limitations

1.5 Version 01.20

Released 12.2018

This Release introduces the software options "EVSG-K4 GBAS" and "EVSG-K5 SCAT-I" for GBAS and SCAT-I signal analysis available for both EVSG1000 and EVSF1000. It offers physical measurements like signal level and timings along with several graphical visualizations. Message content decoding is implemented for all common message types, but is also configurable and expandable for future developments.

Residual FM measurements according to the ICAO standards were added to the ILS analysis available in the base firmware of EVSG1000 and EVSF1000 (no option necessary).

Compatibility

Version	Component
EVSG1000, EVSF1000	Device
Rev 3.00 +	RX-Board
Rev 4.00 +	Mainboard
V 1.01	Keyboard Controller
V 1.11 +	Startup-Controller

REMARK:

Please be aware that Release 1.20 will not be able to read and visualize old data recordings. There is simply no access to old recordings. A "factory preset" will delete these recordings.

Please save old data recordings before performing the software update.

Firmware package contents

Version	Contents
01.17k	EVsx1000 Software
00.36.02	RX FPGA
00.06.16	GBAS FPGA

New functionality

Functions

"EVSG-K4 GBAS analysis" and "EVSG-K5 SCAT-I analysis"

GBAS/SCAT-I Sequence, frame and burst view

GBAS/SCAT-I time domain visualization

GBAS/SCAT-I constellation diagram

GBAS/SCAT-I data recording

GBAS/SCAT-I message decoding

GBAS/SCAT-I external message definitions to configure the decoding

ILS residual FM 90Hz/150Hz with ICAO filtering. It's also possible to use narrow filters to improve 90Hz/150Hz separation.

Support for GPS-receivers with USB interface - see note in chapter 4.2

Modified functionality

Functions

Negative values for GPS undulation are now correct (CR159)

Audio output level is increased by factor 2 (CR155)

Adjustable trigger offset time for ILS/VOR/MB/COM/TD (-180ms ... 1000ms) (CR153, CR151)

Corrected VOR AM voice modulation (CR 143)

Taking the selected DDM and SDM unit into account in exported recordings and streams

Possibility to use the PPS input as trigger for ILS/VOR/MB/COM. Since the EVSF without option EVSF1-B4 has no dedicated trigger input, this is the only way to handle a hardware trigger. (CR137)

Fine-adjustment of PPS and trigger timings. Measurements should be more accurate, so there may be slight differences compared to measurements with older EVSG/EVSF software.

Known issues

Known-Issues

LF IN / BASEBAND IN does not support measurements

Online Help not context sensitive

A heatsink is required to operate RF/IF/AF spectrum and TD analysis with full performance (see chapter 4)

When autocalibration is performed with non-zero level correction, level measurements afterwards will be wrong. It is recommended to reset device settings before autocalibration.

GBAS/SCAT-I: An external PPS source is needed to receive and decode GBAS signals. The possibility to go without PPS is planned for future developments.

GBAS/SCAT-I: No automatic gain control. However the EVSG/EVSF still handles bursts with more than 40dB level difference due to its high dynamic

GBAS/SCAT-I: GBAS-decoding is based on XML definitions of the message types. It is also possible to use user defined XML definitions. However there are only basic possibilities to handle those files.

GBAS/SCAT-I: The status of the received bursts ("green" or "red") does not include the message CRCs. Data decoding on bursts with invalid CRC will probably result in invalid data.

1.6 Version 01.10

Released 5.2018

This is the first major extension of the EVSG / EVSF Software. It contains new features as well as improvements. There is an overhauled user manual, also available as online help with this update.

Compatibility

Version	Component
EVSG1000, EVSF1000	Device
Rev 3.00 +	RX-Board
Rev 4.00 +	Mainboard
V 1.01	Keyboard Controller
V 1.11, V1.12	Startup-Controller

REMARK:

Please be aware that Release 1.10 will not be able to read old data recordings. There is no access to old recordings except that a "factory preset" will delete them. So if there are data recordings, they shall be exported before the update.

Firmware package contents

Version	Contents
01.10k	EVSx1000 Software
00.30.11	RX FPGA

New functionality

Functions

RF Spectrum: Spectrum Analyzer Mode for frequency spans from 0.1 MHz to full span (70 MHz .. 410 MHz)

This Mode is activated with EVSG-K10, which also covers the IF-Spectrum for smaller spans

ILS LLZ/GP: Distortion value 90+150 Hz and residual FM

VOR: Distortion K2 of 30 Hz and K2,K3,K4,K5 of 9960 Hz

RF/AF/IF Spectrum: Average and Max-Hold

UNDO / REDO keys to revert to old settings

Optioncodes can be read from XML files on USB

Modified functionality

Functions

The GPS delay +/- sign was inverted compared to EVS300 → corrected (CR 120)

The shortcut from 2F ILS LLZ/GP to AF-spectrum/TD leads to the channel frequency, which was useless. Now there is a possibility to choose CRS or CLR. (CR 56)

Overload Indication for RF/IF/AF/TD modes (CR 116)

Shortcut from LLZ to GP and back is located on the frequency page. It keeps the channel number and sets the according frequency. (CR 109)

The ILS LLZ/GP autotune in 2F was searching for one signal above and one signal below the channel frequency. Because in GP it is OK to have both signals above or below, the autotune now searches for the 2 best signals from -25 kHz .. +25 kHz, no matter where they are. (CR 107)

AF-Spectrum: the reference value 0dB was 6dB too high → corrected (CR 103)

AF-Spectrum: The RF carrier was visible at 0 Hz. It is now suppressed, however some remains may still be seen (CR 102)

After a software update all settings will be set to default. This ensures that changed defaults are active after updates. (CR 97)

AF/IF-Spectrum: The selectable resolution bandwidths were inaccurate. The new values may be odd, but they are correct (CR 96)

Many graphical improvements on RF/IF/AF spectrum to align the usage to the current generation of R&S® spectrum analyzers

Frequency Offset values in kHz now with 3 post comma digits (CR 82)

The so called "Factory Presets" in Rel. 1.00 sets all operational settings to default, but network settings and data recordings were left unchanged. Now there is a choice between the "normal" preset, which works as before, and a real "factory preset" which also clears data and network settings. (CR 81)

It may happen that battery charging is stopped for temperature conditions. This is now indicated as "Ch.susp." (CR 76)

Errors on self-test voltages (BITE) were indicated, but not stored in the errorlog → corrected (CR 68)

VOR did not work well if the 30 Hz frequency deviates more than 0.5 Hz → corrected (CR64,65)

There is a remote command "help" which delivers an up-to-date list of remote commands with a short description. This should be preferred over all legacy documentation. The current manual shall also be based on that list. (CR 60)

Remote commands "AUTOCALSTATUS" and the "FULL" list selection made compatible to the EVS300 output (CR 59,58,57)

ILS phase 90/90 and 150/150 did not work well with averaging (Meastime > 10 ms) → corrected (CR55)

Possibility to read NRP power values by remote (CR54)

The level value showed some overshoot behaviour on fast level changes → corrected (CR 27)

ID modulation value was unstable → corrected (CR 22)

Screenshots can be exported in inverted greyscale for better print results (CR 11)

In Rel 1.00, the FULL and ALL stream selection did not respect unit settings (e.g. DDM in PCT or μA ,...) Now the settings are used, also to improve compatibility to EVS300 which also used the settings. (CR 59)

Improved navigation in the online help

Known issues

Known-Issues

LF IN / BASEBAND IN still not supported for measurements

Online Help not context sensitive

A heatsink is required to operate RF/IF/AF spectrum and TD analysis with full performance (see chapter 4)

1.7 Version 01.01

Released 11.2017

This release patches two issues that slipped into the first Software Release. Both issues and their patches do not affect the measurement performance or the remote control behavior.

Compatibility

Version	Component
EVSG1000, EVSF1000	Device
Rev 3.00 +	RX-Board
Rev 4.00 +	Mainboard
V 1.01	Keyboard Controller
V 1.11	Startup-Controller

Firmware package contents

Version	Contents
01.00h	EVSx1000 Software
00.18.03	RX FPGA

New functionality

Functions

No new functionality

Modified functionality

Functions

EVSG: under some circumstances the device booted, but the display remains black. A patch was necessary to ensure the correct startup of the display controller. (CR 23)

EVSF: When using a static IP address it shall be entered with a USB keyboard by pressing "INSERT". Unfortunately the entered IP was not set, so the default IP remains active. (CR 36)

Known issues

Known-Issues

The issues described in R1.00 are not solved by R1.01

1.8 Version 01.00

Released 10.2017

Initial version for EVSG1000 and EVSF1000

Compatibility

Version	Component
EVSG1000, EVSF1000	Device
Rev 3.00 +	RX-Board
Rev 4.00 +	Mainboard
V 1.01	Keyboard Controller
V 1.11	Startup-Controller

Firmware package contents

Version	Contents
01.00g	EVSx1000 Software
00.18.03	RX FPGA

New functionality

Functions
ILS LLZ and GS: 1F, 2F and Wideband analysis DDM, SDM AM depth and modulation frequencies of each signal component Distortion measurement K2, K3, K4, THD, AM 90+150 Hz Detailed ID analysis and decoding Independent analysis of Course and Clearance (EVSG-K1)
ILS MB (EVSG-K3): Analysis of pulsed 400Hz, 1300Hz and 3000Hz signals Detailed ID analysis
VOR (EVSG-K2): Bearing and Analysis of all signal components Detailed ID analysis and decoding
COM (EVSG-K6): Support for installations with 1 or 2 transmitters Independent analysis of each transmitter Analysis of 1 kHz test tones
IF Spectrum Analysis (EVSG-K10) for frequency spans up to 100kHz
AF Spectrum Analysis (EVSG-K11) up to 50 kHz
AF Timedomain measurements (EVSG-K12)
TCP/IP Remote control, compatible with EVS300

Data Recording (EVSG-K21) for LLZ, GS, MB, VOR and COM

GPS support (EVSG-K20) with PPS sync

Spectrum Preview for LLZ, GS, MB, VOR and COM

VNC Remote operations

Power Sensor support (EVSG-K24)

Modified functionality

Functions

Nothing yet

Known issues

Known-Issues

RF Spectrum Analysis (swept spectrum) not yet implemented

LF IN / BASEBAND IN not yet supported for measurements

Only basic functionality for Spectrum and Scope modes

VOR distortion and residual FM not yet implemented

VOR ID needs a measurement time > 100ms to be stable

Online Help contains the full user manual, but is not context sensitive and hard to navigate

2 Modifications to the documentation

This chapter is about issues in the user manual which do not match with the released software.

Release 1.50 comes with an updated user manual. There are no known issues.

3 Firmware Update

3.1 Validity Information

Device	Order Number
EVSG1000	1329.8009.02
EVSF1000	1330.0008.02
EVSD1000	1330.0350.02

3.2 Updating the Firmware

The update is distributed as a single file with ending ".evs". Place this file in the main directory of a USB stick and apply the stick to the EVSx1000.

Go to Setup → Inventory (use the VNC access on EVSF1000/EVSD1000).

Move the cursor to "SW Update" and press ENTER.

A list with files appears, select the required update file and press ENTER. The update procedure shall run for max. 30 s without errors.

Reboot the device to get the update working.

4 Additional Information

4.1 Heatsink Requirement

It was found that the graphical modes (RF/IF/AF spectrum and TD analysis) do some heavy calculation which cause the controllers CPU to get hot. Depending on the environmental temperature the CPU needs to decrease its speed. The device will still operate, and there is no risk of any hardware damage. However the performance may be limited.

A heatsink is mounted in all devices starting from 5.2018. Older devices will get the heatsink retrofit free of cost as soon as they appear in R&S Service.

4.2 GPS-Receiver on USB-Port

Recent GPS-Receivers may offer a USB-interface. There is no real standard for USB-GPS, so most of them use an internal RS232-USB-converter, which opens a virtual COM-port on the connected PC or device.

The Linux-System on the EVSx1000 supports an impressive number of those chips, so many USB-GPS will work with both devices.

Nevertheless Rohde&Schwarz does not guarantee that all types of USB-GPS-Receivers are supported. It is advisable to run tests before buying expensive GPS equipment or using them for operational purposes.

5 Customer support

Technical support – where and when you need it

For quick, expert help with any Rohde & Schwarz product, contact our customer support center. A team of highly qualified engineers provides support and works with you to find a solution to your query on any aspect of the operation, programming or applications of Rohde & Schwarz products.

Contact information

Contact our customer support center at www.rohde-schwarz.com/support or follow this QR code:



Figure 5-1: QR code to the Rohde & Schwarz support page