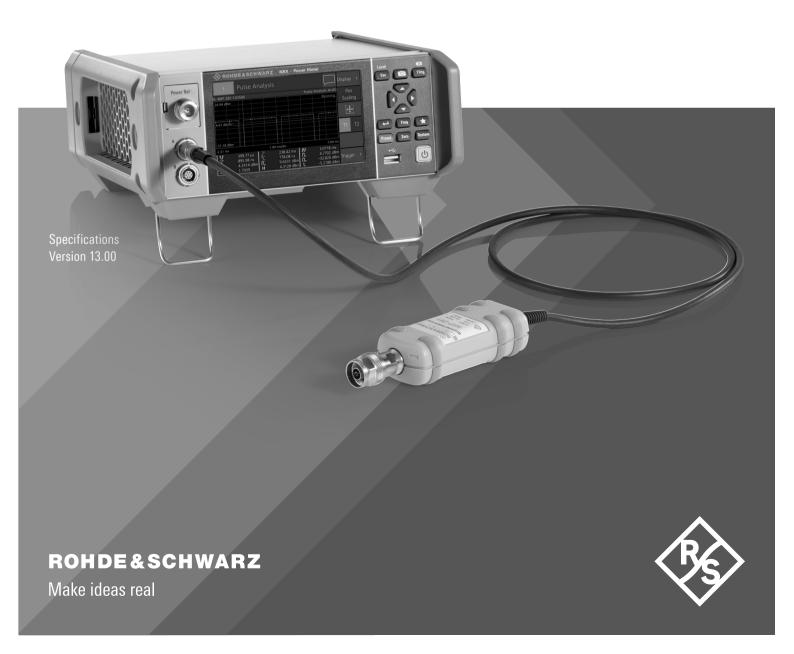
R&S®NRP-Zxx POWER SENSORS

Specifications



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Definitions

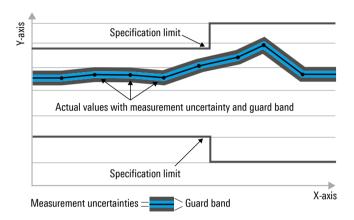
Genera

Product data applies under the following conditions:

- Three hours storage at ambient temperature followed by 30 minutes warm-up operation
- Specified environmental conditions met
- · Recommended calibration interval adhered to
- · All internal automatic adjustments performed, if applicable

Specifications with limits

Represent warranted product performance by means of a range of values for the specified parameter. These specifications are marked with limiting symbols such as <, ≤, >, ≥, ±, or descriptions such as maximum, limit of, minimum. Compliance is ensured by testing or is derived from the design. Test limits are narrowed by guard bands to take into account measurement uncertainties, drift and aging, if applicable.



Specifications without limits

Represent warranted product performance for the specified parameter. These specifications are not specially marked and represent values with no or negligible deviations from the given value (e.g. dimensions or resolution of a setting parameter). Compliance is ensured by design.

Typical data (typ.)

Characterizes product performance by means of representative information for the given parameter. When marked with <, > or as a range, it represents the performance met by approximately 80 % of the instruments at production time. Otherwise, it represents the mean value.

Nominal values (nom.)

Characterize product performance by means of a representative value for the given parameter (e.g. nominal impedance). In contrast to typical data, a statistical evaluation does not take place and the parameter is not tested during production.

Measured values (meas.)

Characterize expected product performance by means of measurement results gained from individual samples.

Uncertainties

Represent limits of measurement uncertainty for a given measurand. Uncertainty is defined with a coverage factor of 2 and has been calculated in line with the rules of the Guide to the Expression of Uncertainty in Measurement (GUM), taking into account environmental conditions, aging, wear and tear.

Device settings and GUI parameters are indicated as follows: "parameter: value".

Typical data as well as nominal and measured values are not warranted by Rohde & Schwarz.

In line with the 3GPP standard, chip rates are specified in million chips per second (Mcps), whereas bit rates and symbol rates are specified in billion bit per second (Gbps), million bit per second (Mbps), thousand bit per second (kbps), million symbols per second (Msps) or thousand symbols per second (ksps), and sample rates are specified in million samples per second (Msample/s). Gbps, Mcps, Mbps, ksps, ksps and Msample/s are not SI units.

Overview of the R&S®NRP-Zxx power sensors

Sensor type	Frequency range	Power range,	Connector type
R&S®		max. average power / peak envelope power	
Two-path diode po	ower sensors		
NRP-Z211	10 MHz to 8 GHz	1.0 nW to 100 mW (–60 dBm to +20 dBm) max. 400 mW (AVG) / 2 W (PK, 10 µs)	N
NRP-Z221	10 MHz to 18 GHz	1.0 nW to 100 mW (–60 dBm to +20 dBm) max. 400 mW (AVG) / 2 W (PK, 10 µs)	N
Level control sens	sors		
NRP-Z28	10 MHz to 18 GHz	200 pW to 100 mW (–67 dBm to +20 dBm) max. 700 mW (AVG) / 4 W (PK, 10 μs)	N
NRP-Z98	9 kHz to 6 GHz	200 pW to 100 mW (–67 dBm to +20 dBm) max. 700 mW (AVG) / 4 W (PK, 10 µs)	N
Power sensor mod	dules		
NRP-Z27	DC to 18 GHz	4 µW to 400 mW (-24 dBm to +26 dBm) max. 500 mW (AVG) / 30 W (PK, 1 µs)	N
NRP-Z37	DC to 26.5 GHz	4 µW to 400 mW (–24 dBm to +26 dBm) max. 500 mW (AVG) / 30 W (PK, 1 µs)	3.5 mm

Specifications in brief of the R&S®NRP-Zxx power sensors

Sensor type	Impedance matching (SV	WR)	Rise time Video BW	Zero offset (typ.)	Noise (typ.)	Uncertainty for measurements	power at +20 °C to +25 °C
R&S®				(-51- /		absolute	relative
Two-path di	ode power sensors	,					
NRP-Z211		< 1.13 < 1.20	< 10 µs			0.054 dB to 0.110 dB	0.022 dB to 0.112 dB
NRP-Z221	> 2.4 GHz to 8.0 GHz:	< 1.13 < 1.20 < 1.25	> 40 kHz	290 pW	180 pW	0.054 dB to 0.143 dB	0.022 dB to 0.142 dB
Level contro	ol sensors						1
NRP-Z28	> 2.4 GHz to 4.0 GHz: > 4.0 GHz to 8.0 GHz:	< 1.11 < 1.15 < 1.22 < 1.30	< 8 µs > 50 kHz	67 pW	42 pW	0.047 dB to 0.130 dB	0.022 dB to 0.110 dB
NRP-Z98	> 2.4 GHz to 4.0 GHz:	< 1.11 < 1.15 < 1.22	-	•		0.047 dB to 0.083 dB	0.022 dB to 0.066 dB
Power sens	or modules						
NRP-Z27	> 2.0 GHz to 4.2 GHz: > 4.2 GHz to 8.0 GHz:	< 1.15 < 1.18 < 1.23 < 1.25 < 1.35	-			0.070 dB to 0.112 dB	0.032 dB
NRP-Z37	> 2.0 GHz to 4.2 GHz: > 4.2 GHz to 8.0 GHz:		_	200 nW	120 nW	0.070 dB to 0.122 dB	0.032 dB

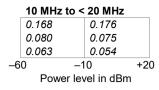
Two-path power sensors in R&S®Smart Sensor Technology

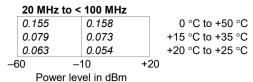
R&S®NRP-Z211/-Z221 two-path diode universal power sensors

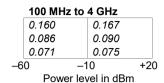
Specifications from 8 GHz to 18 GHz apply only to the R&S®NRP-Z221.

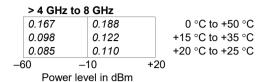
Frequency range	R&S®NRP-Z211	10 MHz to 8 GHz			
. , ,	R&S®NRP-Z221	10 MHz to 18 GHz			
Impedance matching (SWR)	10 MHz to 2.4 GHz	< 1.13 (1.11)			
	> 2.4 GHz to 8.0 GHz	< 1.20 (1.18)	(): +15 °C to +35 °C		
	> 8.0 GHz to 18.0 GHz	< 1.25 (1.23)			
Power measurement range	continuous average	1.0 nW to 100 mW (-60	dBm to +20 dBm)		
	burst average	1.0 µW to 100 mW (-30			
	timeslot/gate average	3.0 nW to 100 mW (-55	dBm to +20 dBm) 1		
	trace	50 nW to 100 mW (-43 d	Bm to +20 dBm) 2		
Maximum power	average power	0.4 W (+26 dBm), continu	uous		
	peak envelope power	2.0 W (+33 dBm) for max	c. 10 μs		
Measurement subranges	path 1	-60 dBm to -5 dBm			
	path 2	-33 dBm to +20 dBm			
Transition regions	with automatic path selection ³	(-10 ± 1) dBm to (-4 ± 1)) dBm		
Dynamic response	video bandwidth	> 40 kHz (50 kHz)			
	single-shot bandwidth	> 40 kHz (50 kHz) (): +15 °C to +3			
	rise time 10 %/90 %	< 10 µs (8 µs)			
Acquisition	sample rate (continuous)	133.358 kHz (default) or	119.467 kHz ⁴		
Triggering	internal				
	threshold level range	-33 dBm to +20 dBm			
	threshold level accuracy	identical to uncertainty for absolute power			
		measurements			
	threshold level hysteresis	0 dB to 10 dB			
	dropout ⁵	0 s to 10 s			
	external	see R&S®NRX base unit	or R&S®NRP-Z5 USB		
		sensor hub			
	slope (external, internal)	pos./neg.			
	delay	–5 ms to +100 s			
	hold-off	0 s to 10 s			
	resolution (delay, hold-off, dropout)	sample period (≈ 8 µs)			
	source	internal, external, immed	iate, bus, hold		
Zero offset	initial, without zeroing				
	path 1	< 1.88 [2.0] (0.6) nW			
	path 2	< 0.94 [1.0] (0.3) µW			
	after external zeroing ^{6, 7}	1 - 1 (7)			
	path 1	< 370 [390] (290) pW	(): typical at 1 GHz		
	path 2	< 180 [190] (145) nW	+15 °C to +35 °C		
Zero drift 8	path 1	< 140 [150] (0) pW			
Loro drift	path 2	< 60 [65] (0) nW	[]: 8 GHz to 18 GHz		
Measurement noise 9	path 1	< 230 [240] (180) pW			
mode and an entitioned	path 2	< 110 [116] (90) nW			
	patii Z	~ 110 [110] (90) 1100			

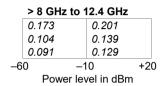
Uncertainty for absolute power measurements 10 in dB

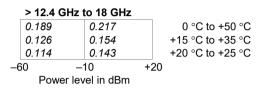




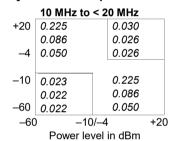


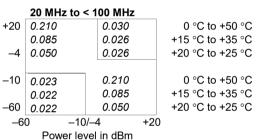


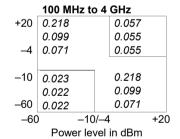




Uncertainty for relative power measurements ¹¹ in dB







	> 4 GHz to	8 GHz		
+20	0.237	0.101		0 °C to +50 °C
	0.132	0.100		+15 °C to +35 °C
-4	0.112	0.100		+20 °C to +25 °C
-10	0.024	0.237		0 °C to +50 °C
	0.022	0.132		+15 °C to +35 °C
-60	0.022	0.112		+20 °C to +25 °C
-6	0 –10)/–4	+20	
	Power le			

> 8 GHz to 12.4 GHz						
+20	0.253	0.124				
	0.155	0.123				
-4	0.136	0.123				
		1				
-10	0.024	0.253				
	0.022	0.155				
-60	0.022	0.136				
-60)	/–4	+20			
Power level in dBm						

	> 12.4 GH	z to 18 GHz		
+20	0.263	0.124		0 °C to +50 °C
	0.162	0.123		+15 °C to +35 °C
-4	0.142	0.123		+20 °C to +25 °C
		_		
-10	0.024	0.263		0 °C to +50 °C
	0.022	0.162		+15 °C to +35 °C
-60	0.022	0.142		+20 °C to +25 °C
-6	0 –1	0/–4	+20	
	Power le			

Additional characteristics of the R&S®NRP-Z211/-Z221 two-path diode power sensors

Sensor type	R&S®NRP-Z211/-Z221	two-path diode power sensor		
Measurand		power of incident wave		
		power of source (DUT) into 50 Ω 12		
RF connector	R&S®NRP-Z211/-Z221	N (male)		
RF attenuation ¹³	R&S®NRP-Z211/-Z221	not applicable		
Measurement functions	stationary and recurring waveforms	continuous average		
		burst average		
		timeslot/gate average		
		trace		
	single events	trace		
Continuous average function	measurand	mean power over recurring acquisition interval		
	aperture	10 μs to 300 ms (20 ms default)		
	window function	uniform or von Hann 14		
	duty cycle correction 15	0.001 % to 99.999 %		
	capacity of measurement buffer ¹⁶	1 to 1024 results		
Burst average function	measurand	mean power over burst portion of		
		recurring signal (trigger settings required)		
	detectable burst width			
	R&S®NRP-Z211/-Z221	25 μs to 50 ms		
	minimum gap between bursts	10 μs		
	dropout period ¹⁷ for burst end detection	0 s to 3 ms		
	exclusion periods ¹⁸			
	start	0 to burst width		
	end	0 s to 3 ms		
	resolution (dropout and exclusion periods)	sample period (≈ 8 µs)		
Timeslot/gate average function	measurand	mean power over individual		
		timeslots/gates of recurring signal		
	number of timeslots/gates	1 to 128 (consecutive)		
	nominal length	10 μs to 0.1 s		
	start of first timeslot/gate	at delayed trigger event		
	exclusion periods 18			
	start	0 to nominal length		
	end	0 s to 3 ms		
	resolution (nominal length and exclusion periods)	sample period (≈ 8 µs)		
Trace function	measurand	mean power over pixel length		
	acquisition			
	length (△)	100 µs to 300 ms		
	start (referenced to delayed trigger)	–5 ms to +100 s		
	result			
	pixels (M)	1 to 1024		
	resolution (△/M)			
	non recurring or internally triggered	≥ 10 µs		
	recurring and externally triggered	≥ 2.5 µs		

Averaging filter	modes	auto off (fixed averaging number)
Averaging inter	modes	auto on (continuously auto-adapted)
		auto once (automatically fixed once)
	auto off	auto once (automatically lixed once)
	supported measurement functions	all
	averaging number	2^N ; $N = 0$ to 16 (13 for trace function)
	auto on/once	2 , 77 - 0 to 10 (15 10) trace full clion)
	supported measurement functions	continuous average, burst average,
		timeslot/gate average
	normal operating mode	averaging number adapted to resolution setting and power to be measured
	fixed noise operating mode	averaging number adapted to specified noise content
	result output	, noise conton
	moving mode	continuous, independent of averaging
	moving mode	number
	rate	can be limited to 0.1 s ⁻¹
	repeat mode	only final result
Attenuation correction	function	corrects the measurement result by
		means of a fixed factor (dB offset)
	range	-200.000 dB to +200.000 dB
Embedding	function	incorporates a two-port device at the
•		sensor input so that the measurement
		plane is shifted to the input of this device
	parameters	S_{11} , S_{21} , S_{12} and S_{22} of device
	frequencies	1 to 1000
Gamma correction	function	removes the influence of impedance
		mismatch from the measurement result so
		that the power of the source (DUT) into
		50 Ω can be read
	parameters	magnitude and phase of reflection
		coefficient of source (DUT)
Frequency response correction	function	takes the frequency response of the
		sensor section and of the RF power
		attenuator into account (if applicable)
	parameter	center frequency of test signal
	residual uncertainty	see specification of calibration uncertainty
		and uncertainty for absolute and relative
		power measurements
Measurement times ¹⁹	continuous average	$2 \times (aperture + 145 \mu s) \times 2^{N} + t_{z}$
	buffered 16, without averaging	$2 \times (aperture + 166 \mu s) \times buffer size + t_z$
2 ^N : averaging number	timeslot/gate average	
T: set number of timeslots	signal period – $T \times w > 100 \mu s$	$\leq 2 \times \text{signal period} \times (2^N + \frac{1}{2}) + t_z$
w: nominal length of timeslot	all other cases	$\leq 4 \times \text{signal period} \times (2^N + \frac{1}{4}) + t_z$
		t_z : < 1.6 ms
Measurement speed	continuous average	
without averaging	single-triggered	550 s ⁻¹ (typ.)
aperture time = 10 μs	buffered ¹⁶	3000 s ⁻¹ (typ.)
Zeroing (duration)	depends on setting of averaging filter	
	auto on	4 s
	auto off, integration time 20	
	< 4 s	4 s
	4 s to 16 s	integration time

Measurement error due to	R&S®NRP-Z211/-Z221: all paths	n = 2	n = 3	n: multiple		
harmonics ²¹	–30 dBc	< 0.001 dB	< 0.003 dB	of carrier		
	–20 dBc	< 0.002 dB	< 0.010 dB	frequency		
	–10 dBc	< 0.010 dB	< 0.040 dB			
Measurement error due to	general	depends on CCDF and RF bandwidth of tes				
modulation 22		signal				
	WCDMA (3GPP test model 1-64)					
	worst case	-0.02 dB to +0	.07 dB			
	typical	-0.01 dB to +0	.03 dB			
Change of input reflection	R&S®NRP-Z211/-Z221					
coefficient with respect to	10 MHz to 2.4 GHz	< 0.02 (0.01)	(): +15 °C to	+35 °C		
power ²³	> 2.4 GHz	< 0.03 (0.02)	.02)			
Calibration uncertainty 24	R&S®NRP-Z211/-Z221	path 1	path 2			
	10 MHz to < 100 MHz	0.052 dB	0.053 dB			
	100 MHz to 4.0 GHz	0.061 dB	0.062 dB			
	> 4.0 GHz to 8.0 GHz	0.075 dB	0.076 dB			
	> 8.0 GHz to 12.4 GHz	0.080 dB	0.080 dB			
	> 12.4 GHz to 18.0 GHz	0.101 dB	0.102 dB			
Interface to host	power supply	+5 V/0.2 A (US	B high-power de	vice)		
	remote control	as a USB device	e (function) in fu	II-speed mode,		
		compatible with	USB 1.0/1.1/2.0) specifications		
	trigger input	differential (0 V				
	connector type	ODU Mini-Snar				
		six-pole cylindr	cal straight plug			
	permissible total cable length	≤ 10 m (see als	o tables on page	e 21)		
Dimensions (W × H × L)	R&S®NRP-Z211/-Z221	48 mm × 31 mr	n × 170 mm			
		(1.89 in × 1.22	in × 6.69 in)			
	length including connecting cable	approx. 1.6 m (62.99 in)				
Weight	R&S®NRP-Z211/-Z221	< 0.30 kg (0.66	lb)			

Level control sensors in R&S®Smart Sensor Technology

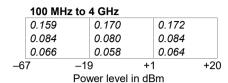
R&S®NRP-Z28 level control sensor

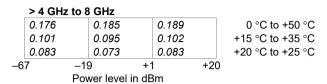
Frequency range		10 MHz to 1	I8 GHz	
Impedance matching (SWR) and		input	output	insertion loss 26
insertion loss		SWR	SWR ²⁵	(): typical
	10 MHz to 2.4 GHz	< 1.35	< 1.11	< 8.0 (7.0) dB
	> 2.4 GHz to 4.0 GHz	< 1.45	< 1.15	< 8.5 (7.5) dB
	> 4.0 GHz to 8.0 GHz	< 1.75	< 1.22	< 9.5 (8.5) dB
	> 8.0 GHz to 12.4 GHz	< 1.80	< 1.30	< 10.5 (9) dB
	> 12.4 GHz to 18.0 GHz	< 1.90	< 1.30	< 11.0 (10) dB
Power measurement range	continuous average	200 pW to 1	100 mW (–67 d	dBm to +20 dBm)
RF output	burst average			dBm to +20 dBm)
•	timeslot/gate average			dBm to +20 dBm) 1
	trace			3m to +20 dBm) 2
Maximum power	average power		,	,
RF input	10 MHz to 2.4 GHz	0.7 W (+28.	5 dBm)	
'	> 2.4 GHz to 8.0 GHz	0.9 W (+29.		continuous
	> 8.0 GHz to 12.4 GHz	1.1 W (+30.		
	> 12.4 GHz to 18.0 GHz	1.3 W (+31.		
	peak envelope power			ge power (for 10 µs)
Measurement subranges	path 1	-67 dBm to		5- 1-5 (.S. 10 MO)
goo	path 2	-46 dBm to		
	path 3	–26 dBm to		
Transition regions	with automatic path selection ³		2) dBm to (–13	- 1/ +2) dBm
Transition regions	With automatio path solociton	,	dBm to (+7 –	•
Dynamic response	video bandwidth	> 50 kHz (1		
Dynamic response	single-shot bandwidth	> 50 kHz (1		(): +15 °C to +35 °C
	rise time 10 %/90 %	< 8 µs (4 µs		(). * 10 0 10 * 00 0
Acquisition	sample rate (continuous)		z (default) or 1	19 467 kHz ⁴
Triggering	internal	100.000 Ki i	z (deladit) er i	10.407 KHZ
9909	threshold level range	-40 dBm to	+20 dBm	
	threshold level accuracy			absolute power
	an ochora lovel accuracy	identical to uncertainty for absolute power measurements		
	threshold level hysteresis	0 dB to 10 c		
	dropout ⁵	0 s to 10 s	<u> </u>	
	external		RX hase unit o	or R&S®NRP-Z5 USB
	- SALSTING.	sensor hub		
	slope (external, internal)	pos./neg.		
	delay	–5 ms to +1	00 s	
	hold-off	0 s to 10 s	-	
	resolution (delay, hold-off, dropout)	sample peri	od	
	source		ernal, immedia	ate bus hold
Zero offset	initial, without zeroing		,	,,
	path 1	< 505 [600]	(100) pW	
	path 2	< 52 [60] (1	· , .	
	path 3	< 5.2 [6] (1)	·	
	after external zeroing 6,7	0.2 [0] (1)	μ	(): typical at 1 GHz
	path 1	< 114 [132]	(67) pW	+15 °C to +35 °C
	path 2	< 11 [13] (6		1
	path 3	< 1.1 [1.3] ([]: 8 GHz to 18 GHz
Zero drift 8	path 1	< 39 [44] (0		1
=0.0 dilit	path 2	< 3.3 [3.8] (-
	path 3	< 0.33 [0.38		-
Measurement noise 9	path 1	< 72 [83] (4)		-
incasulellelle iloise	path 2	< 7 [8] (4) n		
	-			-
	path 3	< 0.7 [0.8] (υ.4) μνν	

Uncertainty for absolute power measurements 10 in dB

	10 MHz	: to <	20 MHz			
	0.174		0.175		0.175	
	0.075		0.070		0.071	
	0.056		0.047		0.048	
-6	7	-19	9	+1		+20
		Pοι	ver level	in dE	3m	

	20 MHz	to < 100 MHz			
	0.147	0.160	0.160		0 °C to +50 °C
	0.073	0.069	0.069		+15 °C to +35 °C
	0.056	0.047	0.048		+20 °C to +25 °C
-6	7	-19	+1	+20	
		Power level			





> 8 GHz to 12.4 GHz					
0.191	0.19	8 0.205	i		
0.114	0.10	4 0.117			
0.095	0.08	0.097	•		
-67	-19	+1	+20		
Power level in dBm					

	> 12.4 (GHz to 1				
	0.218	0.2	224	0.2	37	0 °C to +50 °C
	0.142	0.1	130	0.1	51	+15 °C to +35 °C
	0.124	0.1	105	0.1	30	+20 °C to +25 °C
-67	,	-19		+1	+20)

Uncertainty for relative power measurements ¹¹ in dB

	10 MHz to	< 20 MHz						
+20	0.226	0.229	0.027					
	0.084	0.080	0.022					
+7	0.046	0.044	0.022					
+1	0.226	0.027	0.229					
	0.083	0.022	0.080					
-13	0.045	0.022	0.044					
-19	0.023	0.226	0.226					
	0.022	0.083	0.084					
- 67	0.022	0.045	0.046					
-6	7 –19/-	–13 ±0/	+8 +20					
	Power level in dBm							

	20 MHz to < 100 MHz							
+20	0.206	0.215	0.027	0 °C to +50 °C				
	0.082	0.078	0.022	+15 °C to +35 °C				
+7	0.046	0.044	0.022	+20 °C to +25 °C				
+1	0.205	0.027	0.215	0 °C to +50 °C				
	0.081	0.022	0.078	+15 °C to +35 °C				
-13	0.044	0.022	0.044	+20 °C to +25 °C				
-19	0.023	0.205	0.206	0 °C to +50 °C				
	0.022	0.081	0.082	+15 °C to +35 °C				
-67	0.022	0.044	0.046	+20 °C to +25 °C				
_	67 –19	/–13 ±0	/+8	+20				
	Power level in dBm							

	100 MHz to	o 4 GHz						
+20	0.209	0.218	0.038					
	0.088	0.085	0.032					
+7	0.055	0.047	0.031					
+1	0.206	0.028	0.218					
	0.083	0.022	0.085					
-13	0.048	0.022	0.047					
-19	0.023	0.206	0.209					
	0.022	0.083	0.088					
-67	0.022	0.048	0.055					
-6	57 –19/-	_13 +1/	+7 +20					
	Power level in dRm							

	> 4 GHz to	8 GHz						
+20	0.215	0.223	0.049	0 °C to +50 °C				
	0.097	0.093	0.044	+15 °C to +35 °C				
+7	0.066	0.059	0.043	+20 °C to +25 °C				
+1	0.210	0.030	0.223	0 °C to +50 °C				
	0.088	0.022	0.093	+15 °C to +35 °C				
-13	0.054	0.022	0.059	+20 °C to +25 °C				
-19	0.024	0.210	0.215	0 °C to +50 °C				
	0.022	0.088	0.097	+15 °C to +35 °C				
-67	0.022	0.054	0.066	+20 °C to +25 °C				
-	67 –19	/–13 +	1/+7 +:	20				
	Power level in dBm							

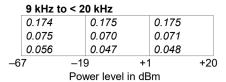
	> 8 GHz to	12.4 GHz						
+20	0.224	0.231	0.064					
	0.111	0.106	0.061					
+7	0.084	0.077	0.060					
+1	0.216	0.034	0.231					
	0.096	0.027	0.106					
-13	0.063	0.025	0.077					
-19	0.024	0.216	0.224					
	0.022	0.096	0.111					
-67	0.022	0.063	0.084					
-6	7 –19/-	-13 +1/	+7 +20					
	Power level in dBm							

	> 12.4 GHz to 18 GHz								
+20	0.244	0.245	0.086	0 °C to +50 °C					
	0.135	0.128	0.084	+15 °C to +35 °C					
+7	0.110	0.102	0.083	+20 °C to +25 °C					
+1	0.230	0.040	0.245	0 °C to +50 °C					
	0.112	0.034	0.128	+15 °C to +35 °C					
-13	0.079	0.033	0.102	+20 °C to +25 °C					
-19	0.024	0.230	0.244	0 °C to +50 °C					
	0.022	0.112	0.135	+15 °C to +35 °C					
-67	0.022	0.079	0.110	+20 °C to +25 °C					
_	67 –19)/–13 +1	/+7 -	+20					
	Power level in dBm								

R&S®NRP-Z98 level control sensor

Frequency range		9 kHz to 6 GHz			
Impedance matching (SWR) and insertion loss		input SWR	output SWR ²⁵	insertion loss ²⁶ (): typical	
	9 kHz to 2.4 GHz	< 1.35	< 1.11	< 8.0 (7.0) dB	
	> 2.4 GHz to 4.0 GHz	< 1.45	< 1.15	< 8.5 (7.5) dB	
	> 4.0 GHz to 6.0 GHz	< 1.75	< 1.22	< 9.5 (8.5) dB	
Power measurement range RF output	continuous average	200 pW to	100 mW (–67	dBm to +20 dBm)	
Maximum power	average power				
RF input	9 kHz to 2.4 GHz	0.7 W (+28	3.5 dBm)	continuous	
	> 2.4 GHz to 6.0 GHz	0.9 W (+29	9.5 dBm)		
	peak envelope power	7.5 dB abo	ove max. avera	age power (for 10 µs)	
Measurement subranges	path 1	-67 dBm t	o –14 dBm		
_	path 2	-46 dBm t	-46 dBm to +6 dBm		
	path 3	-26 dBm t	-26 dBm to +20 dBm		
Transition regions	with automatic path selection ³	(-19 - 1/+ 2) dBm to (-13 - 1/+ 2) dBm (+1 - 1/+ 2) dBm to (+7 - 1/+ 2) dBm		,	
Dynamic response	rise time 10 %/90 %	< 5 ms			
Acquisition	sample rate (continuous)	133.358 kl	Hz		
Zero offset	initial, without zeroing				
	path 1	< 505 (100)) pW	1	
	path 2	< 52 (10) r	١Ŵ		
	path 3	< 5.2 (1) µ	W		
	after external zeroing ^{6,7}				
	path 1	< 114 (67)	pW		
	path 2	< 11 (6) n\	N	(): typical at 1 GHz	
	path 3	< 1.1 (0.6)	μW	+15 °C to +35 °C	
Zero drift ⁸	path 1	< 39 (0) p\	V		
	path 2	< 3.3 (0) n	W		
	path 3	< 0.33 (0)	μW		
Measurement noise 9	path 1	< 72 (42) p	W		
	path 2	< 7 (4) nW	'		
	path 3	< 0.7 (0.4)	< 0.7 (0.4) µW		

Uncertainty for absolute power measurements 10 in dB



	20 kHz to < 100 MHz						
	0.147		0.160		0.160		
	0.073		0.069		0.069		+
	0.056		0.047		0.048		+
-6	7	-19	9	+1	1	+20	
		Pο	ver level	in dF	Rm		



	100 MHz	to 4 GHz			
	0.159	0.170)	0.172	
	0.084	0.080)	0.084	
	0.066	0.058	3	0.064	
-67	7	-19	+1		+20
		Power lev	el in dR	m	

	> 4 GH	z to 6 GHz			
	0.176	0.185	0.18	39	0 °C to +50 °C
	0.101	0.095	0.10	02	+15 °C to +35 °C
	0.083	0.073	0.08	33	+20 °C to +25 °C
– 6	7	-19	+1	+20	
		Power lev	el in dBm		

Uncertainty for relative power measurements 11 in dB

	9 kHz t	o < 20	kHz			
+20	0.226		0.229		0.027	
	0.084		0.080		0.022	
+7	0.046		0.044		0.022	
+1	0.226		0.027		0.229	
	0.083		0.022		0.080	
-13	0.045		0.022		0.044	
-19	0.023		0.226		0.226	
	0.022		0.083		0.084	
-67	0.022		0.045		0.046	
-6	7	-19/-	-13	+1/-	⊦ 7	+20
		Pow	er level ir	n dBm	1	

	20 kHz to	< 100 M	Hz			
+20	0.206	0.2	15 (0.027		0 °0
	0.082	0.0	78 (0.022		+15 °
+7	0.046	0.0	44 (0.022		+20 °
+1	0.205	0.0	27 (0.215		0 °
	0.081	0.0	22 (0.078		+15 °
-13	0.044	0.0	22 (0.044		+20 °
-19	0.023	0.2	05 (0.206		0 °
	0.022	0.0	81 (0.082		+15 °
-67	0.022	0.0	44 (0.046		+20 °
-6	7 -	-19/–13	+1/+7		+20	
		Power lev	el in dBm			

	0 °C to +50 °C +15 °C to +35 °C +20 °C to +25 °C
	0 °C to +50 °C +15 °C to +35 °C +20 °C to +25 °C
20	0 °C to +50 °C +15 °C to +35 °C +20 °C to +25 °C

	100 MH	z to 4	GHz			
+20	0.209		0.218		0.038	
	0.088		0.085		0.032	
+7	0.055		0.047		0.031	
+1	0.206		0.028		0.218	
	0.083		0.022		0.085	
-13	0.048		0.022		0.047	
-19	0.023		0.206		0.209	
	0.022		0.083		0.088	
-67	0.022		0.048		0.055	
-6	57	-19/-	13	+1/+7	+20)
		Powe	er level in	dBm		

	> 4 GHz t	o 6 GHz			
+20	0.215	0.2	23	0.049	
	0.097	0.0	93	0.044	
+7	0.066	0.0	59	0.043	
+1	0.210	0.0	30	0.223	
	0.088	0.0	22	0.093	
-13	0.054	0.0	22	0.059	
		_			
-19	0.024	0.2	10	0.215	
	0.022	0.0	88	0.097	
- 67	0.022	0.0	54	0.066	
-6	7 –	19/–13	+1/+7		+20
	F	Power leve	el in dBm		

0 °C to +50 °C +15 °C to +35 °C +20 °C to +25 °C
0 °C to +50 °C +15 °C to +35 °C +20 °C to +25 °C
0 °C to +50 °C +15 °C to +35 °C +20 °C to +25 °C

Additional characteristics of the R&S®NRP-Z28/-Z98 level control sensors

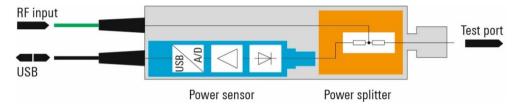
Shaded areas apply only to the R&S®NRP-Z28.

Sensor type		three-path diode power sensor combined with a
		resistive power splitter in a power leveling setup
		(see diagram at the end of this section)
Measurand		power available on a 50 Ω load
		power of wave emanating at RF output 12
RF connectors		N (male)
Measurement functions	stationary and recurring waveforms	continuous average
		burst average
		timeslot/gate average
		trace
	single events	trace
Continuous average function	measurand	mean power over recurring acquisition interval
	aperture	
	R&S®NRP-Z28	10 μs to 300 ms (20 ms default)
	R&S®NRP-Z98	1 ms to 300 ms (20 ms default)
	window function	uniform or von Hann 14
	duty cycle correction 15	0.001 % to 99.999 %
	capacity of measurement buffer 16	1 to 1024 results
Burst average function	measurand	mean power over burst portion of recurring
		signal (trigger settings required)
	detectable burst width	20 μs to 50 ms
	minimum gap between bursts	10 µs
	dropout period ¹⁷ for burst end	0 s to 3 ms
	detection	
	exclusion periods 18	
	start	0 to burst width
	end	0 s to 3 ms
	resolution (dropout and exclusion periods)	sample period (≈ 8 µs)
Timeslot/gate average function	measurand	mean power over individual timeslots/gates of recurring signal
	number of timeslots/gates	1 to 128 (consecutive)
	nominal length	10 μs to 0.1 s
	start of first timeslot/gate	at delayed trigger event
	exclusion periods 18	, , ,
	start	0 to nominal length
	end	0 s to 3 ms
	resolution (nominal length and	sample period (≈ 8 µs)
	exclusion periods)	
Trace function	measurand	mean power over pixel length
	acquisition	, , , , , , , , , , , , , , , , , , , ,
	length (△)	100 μs to 300 ms
	start (referenced to delayed trigger)	-5 ms to +100 s
	result	
	pixels (M)	1 to 1024
	resolution (△/M)	
	non recurring or internally	≥ 10 µs
	triggered	1.7
	recurring and externally	≥ 2.5 µs
	triggered	•

Shaded areas apply only to the R&S®NRP-Z28.

Averaging filter	modes	auto off (fixed averaging number)
Averaging inter	modes	auto off (fixed averaging number) auto on (continuously auto-adapted)
		auto once (automatically fixed once)
	auto off	auto once (automatically fixed once)
	supported measurement functions	all
	averaging number	2^N ; $N = 0$ to 16 (13 for trace function)
	auto on/once	2 , N = 0 to 10 (13 for trace function)
	supported measurement functions	continuous average, burst average, timeslot/gate average
	normal operating mode	averaging number adapted to resolution setting and power to be measured
	fixed noise operating mode	averaging number adapted to specified noise content
	result output	
	moving mode	continuous, independent of averaging number
	rate	can be limited to 0.1 s ⁻¹
	repeat mode	only final result
Attenuation correction	function	corrects the measurement result by means of a
		fixed factor (dB offset)
	range	-200.000 dB to +200.000 dB
Embedding	function	incorporates a two-port device at the
3		RF output so that the measurement plane is shifted to the output of this device
	parameters	S_{11} , S_{21} , S_{12} and S_{22} of device
	frequencies	1 to 1000
Gamma correction	function	removes the influence of impedance mismatch
		from the measurement result so that the power
		of the wave emanating at the RF output can be
		read
	parameters	magnitude and phase of reflection coefficient of DUT
Frequency response correction	function	takes the frequency response of the sensor section and of the power splitter into account
	parameter	center frequency of test signal
	residual uncertainty	see specification of calibration uncertainty and
		uncertainty for absolute and relative power measurements
Measurement time 19	continuous average	
2 ^{<i>N</i>} : averaging number	R&S®NRP-Z28	2 × (aperture + 145 μ s) × 2 ^N + t_z t_z : < 1.6 ms
T: set number of timeslots	R&S®NRP-Z98	$2 \times (aperture + 5 ms) \times 2^{N} - 3.4 ms + t_{d}$
w: nominal length of timeslot		t _d must be taken into account with activated auto
-		delay (1 ms to 20 ms depending on
		temperature) ²⁷
	buffered ¹⁶ , without averaging	$2 \times (\text{aperture} + 250 \mu\text{s}) \times \text{buffer size} + t_z$
	timeslot/gate average	
	signal period – T × w > 100 μs	$\leq 2 \times \text{signal period} \times (2^N + \frac{1}{2}) + t_z$
	all other cases	$\leq 4 \times \text{signal period} \times (2^N + \frac{1}{4}) + t_z$
Zeroing (duration)	depends on setting of averaging filter	, , -
,	auto on	4 s
	auto off, integration time ²⁰	
	< 4 s	4 s
	4 s to 16 s	integration time
	> 16 s	16 s
Measurement error due to		n=2 $n=3$ n : multiple
harmonics ²¹	-30 dBc	< 0.001 dB < 0.003 dB of carrier
		J. C.
namonics	-20 dBc	< 0.002 dB < 0.010 dB frequency

Measurement error due to modulation ²²	general	depends on C signal	CDF and RF bar	ndwidth of test
	WCDMA (3GPP test model 1-64)			
	worst case	-0.02 dB to +0	0.07 dB	
	typical	-0.01 dB to +0	0.03 dB	
Calibration uncertainty 24		path 1	path 2	path 3
(R&S®NRP-Z98 up to 6 GHz only)	< 100 MHz	0.056 dB	0.047 dB	0.048 dB
	100 MHz to 4.0 GHz	0.066 dB	0.057 dB	0.058 dB
	> 4.0 GHz to 8.0 GHz	0.083 dB	0.072 dB	0.072 dB
	> 8.0 GHz to 12.4 GHz	0.095 dB	0.077 dB	0.077 dB
	> 12.4 GHz to 18.0 GHz	0.124 dB	0.100 dB	0.101 dB
Interface to host	power supply	+5 V/0.2 A (U	SB high-power d	evice)
	remote control	as a USB dev	ice (function) in f	ull-speed mode,
		compatible with	th USB 1.0/1.1/2	.0 specifications
	trigger input	differential (0 '	V/+3.3 V)	
	connector type	ODU Mini-Sna	ap® L series,	
		six-pole cylind	rical straight plug	g
	permissible total cable length	≤ 10 m (see a	lso tables on pag	ge 21)
Dimensions	W×H×L	48 mm × 50 m	m × 250 mm	
		(1.89 in × 1.97	' in × 9.84 in)	
	length including connecting cable	approx. 1.75 r	n (68.89 in)	
Weight		< 0.7 kg (1.54	lb)	



Block diagram of the R&S®NRP-Z28/-Z98 level control sensors

Power sensor modules in R&S®Smart Sensor Technology

R&S®NRP-Z27/-Z37 power sensor modules

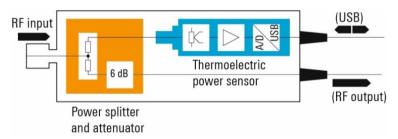
Specifications from 18 GHz to 26.5 GHz apply only to the R&S®NRP-Z37.

Frequency range	R&S®NRP-Z27	DC to 18 GHz		
	R&S®NRP-Z37	DC to 26.5 GHz		
Impedance matching (SWR)	RF input	R&S®NRP-Z27	R&S®	NRP-Z37
	DC to 2.0 GHz	< 1.15	< 1.15	5
	> 2.0 GHz to 4.2 GHz	< 1.18	< 1.18	3
	> 4.2 GHz to 8.0 GHz	< 1.23	< 1.23	3
	> 8.0 GHz to 12.4 GHz	< 1.25	< 1.25	5
	> 12.4 GHz to 18.0 GHz	< 1.35	< 1.30)
	> 18.0 GHz to 26.5 GHz	-	< 1.45	
	RF output	R&S®NRP-Z27	R&S®	NRP-Z37
	DC to 8.0 GHz	< 1.6	< 1.6	
	> 8.0 GHz to 26.5 GHz	< 2.0	< 2.0	
Power measurement range		4 μW to 400 mW		26 dBm),
		continuous, in a s	ingle range	
Maximum power	average power	0.5 W (+27 dBm),		
		1.0 W (+30 dBm)		nutes
	peak envelope power	30 W (45 dBm) fo		
Acquisition	sample rate	20.833 kHz (sigm		
Zero offset	after external zeroing 6, 7	< 400 nW (typ. 20	00 nW at 1 GHz	2)
Zero drift ⁸		< 160 nW		
Measurement noise ⁹		< 240 nW (typ. 12		
Uncertainty for absolute power			+15 °C to	0 °C to
measurements ²⁸			+35 °C	+50 °C
	with matched load on RF output (S)			
	DC to < 100 MHz		0.077 dB	0.103 dB
	100 MHz to 4.2 GHz		0.082 dB	0.106 dB
	> 4.2 GHz to 8.0 GHz		0.094 dB	0.119 dB
	> 8.0 GHz to 12.4 GHz		0.101 dB	0.130 dB
	> 12.4 GHz to 18.0 GHz		0.121 dB	0.151 dB
	> 18.0 GHz to 26.5 GHz		0.137 dB	0.190 dB
	with R&S®FSMR26 connected to R			
	DC to < 100 MHz		0.109 dB	0.128 dB
	100 MHz to 4.2 GHz		0.120 dB	0.138 dB
	> 4.2 GHz to 8.0 GHz		0.166 dB	0.181 dB
	> 8.0 GHz to 18.0 GHz		0.187 dB	0.207 dB
	> 18.0 GHz to 26.5 GHz		0.235 dB	0.269 dB
	with R&S®FSMR26 connected to R	F output and activated lo	oad interference	e correction
	DC to < 100 MHz		0.074 dB	0.101 dB
	100 MHz to 4.2 GHz	0.077 dB	0.083 dB	0.107 dB
	> 4.2 GHz to 8.0 GHz	0.092 dB	0.099 dB	0.123 dB
	> 8.0 GHz to 12.4 GHz	0.099 dB	0.107 dB	0.135 dB
	> 12.4 GHz to 18.0 GHz	0.122 dB	0.130 dB	0.159 dB
	> 18.0 GHz to 26.5 GHz	0.154 dB	0.167 dB	0.212 dB
Uncertainty for relative power measurements 29		0.032 dB		

Additional characteristics of the R&S®NRP-Z27/-Z37 power sensor modules

RS®NRP-Z27 RS®NRP-Z37 gnal output D 2.0 GHz GHz to 4.2 GHz GHz to 8.0 GHz GHz to 12.4 GHz GHz to 18.0 GHz O GHz to 26.5 GHz nary and recurring waveforms urand ure Ow function cycle correction 15 city of measurement buffer 16 iss off reraging number on/once ormal operating mode	section) power of incident wave power of source (DUT) into $50 \Omega^{12}$ N (male) 3.5 mm (male) 3.5 mm (male) < 14 (12.5) dB < 15 (13.5) dB < 16 (14.0) dB < 17 (14.5) dB < 18 (15.5) dB < 19 (16.5) dB continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann 14 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2^N ; $N = 0$ to 16
RS®NRP-Z27 RS®NRP-Z37 Rgnal output D 2.0 GHz GHz to 4.2 GHz GHz to 8.0 GHz GHz to 12.4 GHz GHz to 18.0 GHz GHz to 26.5 GHz Harry and recurring waveforms Rurand Rure Row function Roycle correction 15 Roity of measurement buffer 16 Ress Ress Ress Ress Ress Ress Ress Res	power of source (DUT) into 50 Ω ¹² N (male) 3.5 mm (male) 3.5 mm (male) < 14 (12.5) dB < 15 (13.5) dB < 16 (14.0) dB < 17 (14.5) dB < 18 (15.5) dB < 19 (16.5) dB continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann ¹⁴ 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2^N ; $N = 0$ to 16
RS®NRP-Z27 RS®NRP-Z37 Rgnal output D 2.0 GHz GHz to 4.2 GHz GHz to 8.0 GHz GHz to 12.4 GHz GHz to 18.0 GHz GHz to 26.5 GHz Harry and recurring waveforms Rurand Rure Row function Roycle correction 15 Roity of measurement buffer 16 Ress Ress Ress Ress Ress Ress Ress Res	N (male) 3.5 mm (male) 3.5 mm (male) < 14 (12.5) dB < 15 (13.5) dB < 16 (14.0) dB < 17 (14.5) dB < 18 (15.5) dB < 19 (16.5) dB continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann 14 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
RS®NRP-Z27 RS®NRP-Z37 Rgnal output D 2.0 GHz GHz to 4.2 GHz GHz to 8.0 GHz GHz to 12.4 GHz GHz to 18.0 GHz GHz to 26.5 GHz Harry and recurring waveforms Rurand Rure Row function Roycle correction 15 Roity of measurement buffer 16 Ress Ress Ress Ress Ress Ress Ress Res	3.5 mm (male) 3.5 mm (male) < 14 (12.5) dB < 15 (13.5) dB < 16 (14.0) dB < 17 (14.5) dB < 18 (15.5) dB < 19 (16.5) dB continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann 14 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
gnal output b 2.0 GHz GHz to 4.2 GHz GHz to 8.0 GHz GHz to 12.4 GHz GHz to 18.0 GHz GHz to 18.0 GHz GHz to 26.5 GHz nary and recurring waveforms urand ure bw function cycle correction 15 city of measurement buffer 16 es off reraging number con/once ormal operating mode	3.5 mm (male) 3.5 mm (male) < 14 (12.5) dB < 15 (13.5) dB < 16 (14.0) dB < 17 (14.5) dB < 18 (15.5) dB < 19 (16.5) dB continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann 14 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
gnal output b 2.0 GHz GHz to 4.2 GHz GHz to 8.0 GHz GHz to 12.4 GHz 4 GHz to 18.0 GHz 0 GHz to 26.5 GHz nary and recurring waveforms urand ure bw function cycle correction 15 city of measurement buffer 16 es off reraging number con/once ormal operating mode	3.5 mm (male) < 14 (12.5) dB < 15 (13.5) dB < 16 (14.0) dB < 17 (14.5) dB < 18 (15.5) dB < 19 (16.5) dB continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann 14 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
of 2.0 GHz GHz to 4.2 GHz GHz to 8.0 GHz GHz to 12.4 GHz GHz to 18.0 GHz GHz to 18.0 GHz GHz to 26.5 GHz GHz to 4.2 GH	 < 14 (12.5) dB < 15 (13.5) dB < 16 (14.0) dB < 17 (14.5) dB < 18 (15.5) dB < 19 (16.5) dB continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann ¹⁴ 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2^N; N = 0 to 16
GHz to 4.2 GHz GHz to 8.0 GHz GHz to 12.4 GHz 4 GHz to 18.0 GHz 0 GHz to 26.5 GHz nary and recurring waveforms urand ure ow function cycle correction 15 city of measurement buffer 16 es	<pre>< 15 (13.5) dB < 16 (14.0) dB < 17 (14.5) dB < 18 (15.5) dB < 19 (16.5) dB continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann 14 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2^N; N = 0 to 16</pre> (): typical
GHz to 8.0 GHz GHz to 12.4 GHz 4 GHz to 18.0 GHz 0 GHz to 26.5 GHz nary and recurring waveforms urand ure ow function cycle correction 15 city of measurement buffer 16 es	<pre>< 16 (14.0) dB < 17 (14.5) dB < 18 (15.5) dB < 19 (16.5) dB continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann 14 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2^N; N = 0 to 16</pre> <pre> (): typical (): typical </pre>
GHz to 12.4 GHz 4 GHz to 18.0 GHz 0 GHz to 26.5 GHz nary and recurring waveforms urand ure ow function cycle correction 15 city of measurement buffer 16 es off reraging number con/once ormal operating mode	<pre>< 17 (14.5) dB < 18 (15.5) dB < 19 (16.5) dB continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann 14 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2^N; N = 0 to 16 averaging number adapted to resolution setting</pre>
4 GHz to 18.0 GHz 0 GHz to 26.5 GHz nary and recurring waveforms urand ure ow function cycle correction 15 city of measurement buffer 16 es off reraging number con/once ormal operating mode	< 18 (15.5) dB < 19 (16.5) dB continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann ¹⁴ 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
O GHz to 26.5 GHz nary and recurring waveforms urand ure ow function cycle correction 15 city of measurement buffer 16 es off reraging number on/once ormal operating mode	< 19 (16.5) dB continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann ¹⁴ 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
nary and recurring waveforms furand fure ow function cycle correction 15 city of measurement buffer 16 es off fereraging number con/once ormal operating mode	continuous average mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann ¹⁴ 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
ourand ure ow function cycle correction 15 city of measurement buffer 16 es off reraging number con/once ormal operating mode	mean power over recurring acquisition interval 1 ms to 100 ms (20 ms default) uniform or von Hann ¹⁴ 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
oure ow function cycle correction 15 city of measurement buffer 16 es off feraging number on/once ormal operating mode	1 ms to 100 ms (20 ms default) uniform or von Hann ¹⁴ 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
ow function cycle correction 15 city of measurement buffer 16 es coff deraging number con/once ormal operating mode	uniform or von Hann ¹⁴ 0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
cycle correction 15 city of measurement buffer 16 es coff deraging number con/once ormal operating mode	0.001 % to 99.999 % 1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
city of measurement buffer ¹⁶ es off veraging number on/once ormal operating mode	1 to 1024 results auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
off reraging number on/once ormal operating mode	auto off (fixed averaging number) auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
off reraging number on/once ormal operating mode	auto on (continuously auto-adapted) auto once (automatically fixed once) 2 ^N ; N = 0 to 16 averaging number adapted to resolution setting
reraging number on/once ormal operating mode	auto once (automatically fixed once) $2^{N}; N = 0 \text{ to } 16$ averaging number adapted to resolution setting
reraging number on/once ormal operating mode	2^N ; $N = 0$ to 16 averaging number adapted to resolution setting
reraging number on/once ormal operating mode	averaging number adapted to resolution setting
on/once ormal operating mode	averaging number adapted to resolution setting
ormal operating mode	
	and power to be measured
ed noise operating mode	averaging number adapted to specified noise content
output	55.1.5.1.
oving mode	continuous, independent of averaging number
rate	can be limited to 0.1 s ⁻¹
peat mode	only final result
on	corrects the measurement result by means of a
5.1	fixed factor (dB offset)
;	-200.000 dB to +200.000 dB
on	removes the influence of impedance mismatch
	from the measurement result so that the power
	of the source (DUT) into 50 Ω can be read
neters	magnitude and phase of reflection coefficient of source (DUT)
on	takes the frequency response of the sensor
notor	section and of the power splitter into account
	center frequency of test signal
иаг инсегтатту	see specification of calibration uncertainty and
on	uncertainty for absolute power measurements removing the influence of the load on the RF
UH	signal output from the power measurement
	result
n	meter lual uncertainty tion

Measurement time 19		2 × (aperture + 450 μs) ×	$2^{N} + 4 \text{ ms} + t_{d}$				
2 ^N : averaging number		$t_{\rm d}$ (80 ms) must be taken in					
		auto delay 27 is active					
Zeroing (duration)	depends on setting of averaging filter	-					
	auto on	auto on 4 s					
	auto off, integration time ²⁰						
	< 4 s 4 s						
	4 s to 16 s	integration time					
	> 16 s	16 s					
Calibration uncertainty 30	DC to < 100 MHz	0.063 dB					
	100 MHz to 4.2 GHz	0.070 dB					
	> 4.2 GHz to 8.0 GHz	0.082 dB					
	> 8.0 GHz to 12.4 GHz	0.088 dB					
	> 12.4 GHz to 18.0 GHz	0.109 dB	0.109 dB				
	> 18.0 GHz to 26.5 GHz	0.118 dB					
Temperature effect 31	DC to 4.2 GHz	< 0.004 dB/K					
	> 4.2 GHz to 8.0 GHz	< 0.005 dB/K					
	> 8.0 GHz to 12.4 GHz	< 0.005 dB/K					
	> 12.4 GHz to 18.0 GHz	< 0.006 dB/K					
	> 18.0 GHz to 26.5 GHz	< 0.009 dB/K					
Linearity 32	for power levels < 100 mW (20 dBm)	< 0.020 dB					
Power coefficient 33		< (0.02 + 0.002 f/GHz) dB	W				
Load interference error 34	DC to 2.0 GHz	< 0.061 (0.003) dB	values in () after				
From RF signal output	> 2.0 GHz to 12.4 GHz	< 0.050 (0.012) dB	load interference				
	> 12.4 GHz to 18.0 GHz	< 0.043 (0.016) dB	correction				
	> 18.0 GHz to 26.5 GHz	< 0.043 (0.022) dB					
Interface to host	power supply	+5 V/0.1 A (USB low-power	er device)				
	remote control	as a USB device (function) in full-speed mode,				
		compatible with USB 1.0/2	1.1/2.0 specifications				
	trigger input	differential (0 V/+3.3 V)					
	connector type	ODU Mini-Snap® L series,					
		six-pole cylindrical straight plug					
	permissible cable length	≤ 10 m (see also tables or	n page 21)				
Dimensions	W×H×L	48 mm × 50 mm × 250 mr	m				
		(1.89 in × 1.97 in × 9.84 ir	1)				
	length including connecting cable	approx. 1.75 m (68.89 in)					
Weight		< 0.7 kg (1.54 lb)					



Block diagram of the R&S®NRP-Z27/-Z37 power sensor modules

Accessories for sensors

R&S®NRP-Z2 extension cables

	for connecting an R&S®NRP-Zxx power sensor to an R&S®NRX base unit other Rohde & Schwarz measuring instrument an R&S®NRP-Z4 USB adapter cable an R&S®NRP-Z5 USB sensor hub
type	ODU Mini-Snap® L series, size 1, six-pole receptacle
sensor side	
models .03/.05/.10	with in-line receptacle
model .15	with bulkhead receptacle for panel mounting
	< 5 mm wall thickness
host side	straight plug
model .03	1.5 m
models .05/.15	3.5 m
model .10	8.5 m
including power sensor and R&S®NRX base unit or R&S®NRP-Z4 USB adapter cable or R&S®NRP-Z5 USB sensor hub,	see tables below
	sensor side models .03/.05/.10 model .15 host side model .03 models .05/.15 model .10 including power sensor and R&S®NRX base unit or R&S®NRP-Z4 USB adapter cable or

Supported combinations with R&S®NRX base unit or other Rohde & Schwarz measuring instruments with ODU Mini-Snap® receptacle (e.g. R&S®FSMR, R&S®SMA200A, R&S®SMF100A)

R&S®NRP-Zxx		R&S®NRF	2-Z2 models			total	
power sensor		.03	.05/.15	.10		length in m	(shaded combination only
•	+	•	_	_	=	3.0	supported by R&S®NRX
•		_	•	_		5.0	base unit)
•		_	_	•		10.0	

Supported combinations with R&S®NRP-Z4 USB adapter cables

R&S®NRP-Zxx power sensor		R&S®NRF models	P-Z2		R&S®NI	RP-Z4 mc	odels			total length
		.03	.05/.15		.06	.04	.11	.02		in m
•		_	_		•	_	_	_		1.6
•		_	_		_	•	_	_		2.0
•	_	_	_		_	_	•	_	_	2.5
•	т	_	_	т	_	_	_	•	_	3.5
•		•	_		_	_	_	•		5.0
•		_	•		•	_	_	_		5.1
•		_	•		_	•	_	_		5.5
•		_	•		_	_	•	_		6.0
•		_	•		_	_	_	•		7.0

Supported combinations with R&S®NRP-Z5 USB sensor hub (cable between sensor and hub)

R&S®NRP-Zxx power sensor		R&S®NRF models	P- <u>Z2</u>		R&S®NRP-Z5 USB sensor hub	total length
	+	.03	.05/.15	+		in m
•		•	_		•	3.0
•		_	•		•	5.0

Supported combinations with R&S®NRP-Z5 USB sensor hub (cable between hub and host)

R&S®NRP-Z5 USB sensor hub		R&S®NRP models	-Z2	R&S®NF	RP-Z4 mo	dels		standard USB cable (max. length: 5 m)		total length
		.03	.05/.15	.06	.04	.11	.02			in m
•		•	_		_		_	_		3.0
•		_	•		_		_	_	_	5.0
•	T	_	_	•	_	_	_	_	=	0.1
•		_	_	_	•	_	_	_		0.5
•		_	_	_	_	•	_	_		1.0
•		_	_	_	_	_	•	_		2.0
•		_	_	_	_	_	_	•		5.0

R&S®NRP-Z4 USB adapter cable

Application		for connecting an R&S®NRP-Zxx power sensor to a USB host (PC or Rohde & Schwarz measuring instrument with type A receptacle)
Connectors	sensor side	ODU Mini-Snap [®] L series, size 1, six-pole receptacle
	models .02/.04/.06	with in-line receptacle
	model .11	with bulkhead receptacle for panel mounting < 5 mm wall thickness
	host side	USB type A plug
Dimensions (length)	model .02	approx. 2 m (78.74 in)
	model .04	approx. 0.5 m (19.69 in)
	model .06	approx. 0.15 m (5.91 in)
	model .11	approx. 1 m (39.37 in)

R&S®NRP-Z5 USB sensor hub

Application		for connecting up to four R&S®NRP-Zxx power sensors to • a USB host (PC or Rohde & Schwarz measuring instrument with type A receptacle) • a Rohde & Schwarz measuring instrument (other than the R&S®NRX) with circular sensor connector (ODU Mini-Snap® L series, size 1, six-pole receptacle)
Trigger input	maximum voltage	±8 V
	logic level	
	low	< 0.8 V
	high	> 2.0 V
	input impedance	approx. 10 kΩ
	minimum pulse width	35 ns (without R&S®NRP-Z2 extension cable)
Trigger output	high-level output voltage	< 5.3 V (no load), > 2.0 V (50 Ω)
	low-level output voltage	< 0.4 V at 5 mA sink current
Power supply	voltage/power	12 V to 24 V (DC)/24 W
	source	AC adapter supplied with the equipment or
		equivalent DC voltage source
		no supply from extra-low voltage supply systems
		or via secondary cables > 30 m (98.43 ft)
Connectors	sensors A to D	ODU Mini-Snap [®] L series, size 1, six-pole receptacle
	USB host	USB type B receptacle (certified USB 2.0 high- speed cable supplied with the equipment)
	for Rohde & Schwarz instrument	ODU Mini-Snap® L series, size 1, six-pole plug
	trigger input, trigger output	BNC receptacle
	power supply	receptacle for DC barrel connector, ∅ 5.5 mm × ∅ 2.1 mm × 9.5 mm; inner conductor is positive pole
Dimensions (W × H × L)	sensor hub	140.6 mm × 36.6 mm × 138 mm (5.54 in × 1.44 in × 5.43 in)
Weight	excluding accessories	< 0.55 kg (1.21 lb)
AC adapter	input voltage/frequency	100 V to 240 V/50 Hz to 60 Hz
•	tolerance	±10 % for voltage, ±3 Hz for frequency
	input connector	C14 receptacle, in line with IEC 60320
	output voltage/power	12 V (DC)/36 W
	length of secondary cable	approx. 0.72 m (28.35 in)
	dimensions (W × H × L)	120 mm × 52 mm × 31 mm
		(4.72 in × 2.05 in × 1.22 in)
	weight	< 0.3 kg (0.66 lb)

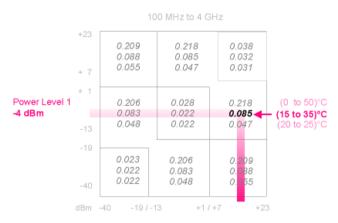
General data

Temperature loading 35	operating and permissible temperature	in line with IEC 60068
	range (in [] if different)	
	R&S®NRP-Z5 USB sensor hub,	0 °C to +50 °C
	R&S®NRP-Z4 USB adapter cables	
	R&S®NRP-Zxx power sensors,	0 °C to +50 °C [–10 °C to +55 °C]
	R&S®NRP-Z2 extension cables	
	storage temperature range	
	R&S®NRP-Z5 USB sensor hub	–40 °C to +70 °C
	R&S®NRP-Zxx power sensors,	
	R&S®NRP-Z2 extension cables and	
	R&S®NRP-Z4 USB adapter cables	
Climatic resistance		in line with EN 60068
	damp heat	+25 °C/+40 °C cyclic at 95 % relative
	·	humidity,
		with restrictions: noncondensing
Mechanical resistance	vibration	<u> </u>
	sinusoidal	5 Hz to 55 Hz, max. 2 g;
		55 Hz to 150 Hz, 0.5 g constant;
		in line with EN 60068
	random	10 Hz to 500 Hz, 1.9 g (RMS),
		in line with EN 60068
	shock	40 g shock spectrum,
		in line with EN 60068
	air pressure	
	operation	795 hPa (2000 m) to 1060 hPa
	transport	566 hPa (4500 m) to 1060 hPa
Electromagnetic compatibility		in line with EN 61326, EN 55011
Safety		in line with EN 61010-1, IEC 61010-1,
-		CAN/CSA-C22.2 No. 61010-1-04,
		UL STD. No. 61010-1
Calibration interval		2 years

Appendix

Reading the uncertainty of diode power sensors for relative power measurements

The example shows a level step of approx. 14 dB (-4 dBm \rightarrow +10 dBm) at 1.9 GHz and an ambient temperature of +28 °C for an R&S $^{\circ}$ NRP-Z21 power sensor.



Power Level 2: +10 dBm

Ordering information

Designation	Туре	Order No.
Two-path diode power sensors		
1 nW to 100 mW, 10 MHz to 8 GHz	R&S®NRP-Z211	1417.0409.02
1 nW to 100 mW, 10 MHz to 18 GHz	R&S®NRP-Z221	1417.0309.02
Level control sensors		
200 pW to 100 mW, 9 kHz to 6 GHz	R&S®NRP-Z98	1170.8508.02
200 pW to 100 mW, 10 MHz to 18 GHz	R&S®NRP-Z28	1170.8008.02
Power sensor modules		
4 μW to 400 mW, DC to 18 GHz	R&S®NRP-Z27	1169.4102.02
4 μW to 400 mW, DC to 26.5 GHz	R&S®NRP-Z37	1169.3206.02
Recommended extras		
R&S®NRPV virtual power meter (PC application),	R&S®NRPZ-K1	1418.9800.03
activation for one R&S®NRP-Zxx power sensor		
Sensor extension cable to 3 m	R&S®NRP-Z2	1146.6750.03
Sensor extension cable to 5 m	R&S®NRP-Z2	1146.6750.05
Sensor extension cable to 10 m	R&S®NRP-Z2	1146.6750.10
Sensor extension cable to 5 m	R&S®NRP-Z2	1146.6750.15
(with bulkhead receptacle for panel mounting)		
USB adapter cable (passive, length: 2.0 m)	R&S®NRP-Z4	1146.8001.02
USB adapter cable (passive, length: 0.5 m)	R&S®NRP-Z4	1146.8001.04
USB adapter cable (passive, length: 0.15 m)	R&S®NRP-Z4	1146.8001.06
USB adapter cable (passive, length: 1.0 m, with bulkhead receptacle for	R&S®NRP-Z4	1146.8001.11
panel mounting)		
USB sensor hub	R&S®NRP-Z5	1146.7740.02

Warranty		
R&S®NRX base unit, power sensors and R&S®NRP-Z5	3 years	
All other items ³⁶		1 year
Options		
Extended warranty, one year	R&S®WE1	Contact your local
Extended warranty, two years	R&S®WE2	Rohde & Schwarz
Extended warranty with calibration coverage, one year	R&S®CW1	sales office.
Extended warranty with calibration coverage, two years	R&S®CW2	
Extended warranty with accredited calibration coverage, one year	R&S®AW1	
Extended warranty with accredited calibration coverage, two years	R&S®AW2	

Extended warranty with a term of one and two years (WE1 and WE2)

Repairs carried out during the contract term are free of charge ³⁷. Necessary calibration and adjustments carried out during repairs are also covered.

Extended warranty with calibration (CW1 and CW2)

Enhance your extended warranty by adding calibration coverage at a package price. This package ensures that your Rohde & Schwarz product is regularly calibrated, inspected and maintained during the term of the contract. It includes all repairs ³⁷ and calibration at the recommended intervals as well as any calibration carried out during repairs or option upgrades.

Extended warranty with accredited calibration (AW1 and AW2)

Enhance your extended warranty by adding accredited calibration coverage at a package price. This package ensures that your Rohde & Schwarz product is regularly calibrated under accreditation, inspected and maintained during the term of the contract. It includes all repairs ³⁷ and accredited calibration at the recommended intervals as well as any accredited calibration carried out during repairs or option upgrades.

Endnotes

- 1 Specifications apply to timeslots/gates with a duration of 12.5 % referenced to the signal period (duty cycle 1:8). For other waveforms, the following equation applies: lower measurement limit = lower measurement limit for continuous average mode / √(duty cycle).
- ² With a resolution of 256 pixel.
- 3 Specifications apply to the default transition setting of 0 dB. The transition regions can be shifted by as much as -20 dB using an adequate offset.
- To prevent aliasing in the case of signals with discrete modulation frequencies between 100 kHz and 1 MHz.
- ⁵ Time span prior to triggering, where the trigger signal must be entirely below the threshold level in the case of a positive slope and vice versa in the case of a negative slope.
- ⁶ Specifications expressed as an expanded uncertainty with a confidence level of 95 % (two standard deviations). For calculating zero offsets at higher confidence levels, use the properties of the normal distribution (e.g. 99.7 % confidence level for three standard deviations).
- 7 Specifications apply to zeroing with a duration of 4 s. Zeroing for more than 4 s lowers uncertainty correspondingly (half values for 16 s).
- ⁸ Within one hour after zeroing, permissible temperature change ±1 °C, following a two-hour warm-up of the power sensor.
- Two standard deviations at 10.24 s integration time in continuous average mode, with aperture time set to default value. The integration time is defined as the total time used for signal acquisition, i.e. the product of twice the aperture time and the averaging number. Multiplying the noise specifications by √(10.24 s/integration time) yields the noise contribution at other integration times. Using a von Hann window function increases noise by a factor of 1.22.
- ¹⁰ Expanded uncertainty (k = 2) for absolute power measurements on CW signals with automatic path selection and the default transition setting of 0 dB. Specifications include calibration uncertainty, linearity and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset can be neglected for power levels above –30 dBm for the R&S®NRP-Z211/-Z221. The contribution of measurement noise depends on power and integration time and can be neglected below 0.01 dB.

Example: The uncertainty of a power measurement at 32 nW (–45 dBm) and 1.9 GHz is to be determined for an R&S®NRP-Z211. The ambient temperature is +29 °C and the averaging number is set to 32 in the continuous average mode with an aperture time of 20 ms.

Since path 1 is used for the measurement, the typical absolute uncertainty due to zero offset is 290 pW after external zeroing, which corresponds to a relative measurement uncertainty of

$$10 \times \lg \frac{32 \text{ nW} + 290 \text{ pW}}{32 \text{ nW}} = 0.039 \text{ dB}.$$

Using the formula in endnote 9, the absolute noise contribution of path 1 is typically 180 pW $\times \sqrt{(10.24 \text{ s}/(32 \times 2 \times 0.02 \text{ s}))}$ = 509 pW, which corresponds to a relative measurement uncertainty of

$$10 \times \lg \frac{32 \text{ nW} + 509 \text{ pW}}{32 \text{ nW}} = 0.069 \text{ dB}.$$

Combined with the uncertainty of 0.086 dB for absolute power measurements under the given conditions, the total expanded uncertainty is

$$\sqrt{0.039^2 + 0.069^2 + 0.086^2}$$
 dB = 0.117 dB.

The contribution of zero drift has been neglected in this case. It must be treated like zero offset if it is relevant for total uncertainty.

11 Expanded uncertainty (k = 2) for relative power measurements on CW signals of the same frequency with automatic path selection and a default transition setting of 0 dB. For reading the measurement uncertainty diagrams of universal, average and level control sensors, see the Appendix.

Specifications include calibration uncertainty (only if different paths are affected), linearity and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset can be neglected for power levels above –30 dBm for the R&S®NRP-Z211/-Z221. The contribution of measurement noise depends on power and integration time and can be neglected below 0.01 dB.

Example: The uncertainty of a power step from 1 mW (0 dBm) to 100 nW (-40 dBm) at 5.4 GHz is to be determined for an R&S®NRP-Z211. The ambient temperature is +20 °C and the averaging number is set to 16 for both measurements in the continuous average mode with an aperture time of 20 ms. For the calculation of total uncertainty, the relative contribution of noise, zero offset and zero drift must be taken into account for both measurements . In this example, all contributions at 0 dBm and the effect of zero drift have been neglected.

Since path 1 is used for the -40 dBm measurement, the typical absolute uncertainty due to zero offset is 290 pW after external zeroing, which corresponds to a relative measurement uncertainty of

$$10 \times \lg \frac{100 \text{ nW} + 290 \text{ pW}}{100 \text{ nW}} = 0.013 \text{ dB}.$$

Using the formula in endnote 9, the absolute noise contribution of path 1 is typically 180 pW × $\sqrt{(10.24 \text{ s}/(16 \times 2 \times 0.02 \text{ s}))}$ = 720 pW, which corresponds to a relative measurement uncertainty of

$$10 \times \lg \frac{100 \text{ nW} + 720 \text{ pW}}{100 \text{ nW}} = 0.031 \text{ dB}$$

Combined with the uncertainty of 0.132 dB for relative power measurements under the given conditions, the total expanded uncertainty is

$$\sqrt{0.013^2 + 0.031^2 + 0.132^2}$$
 dB = 0.136 dB.

- 12 Gamma correction activated.
- ¹³ Preceding sensor section (nominal value).
- 14 Preferably used with determined modulation when the aperture time cannot be matched to the modulation period. Compared to a uniform window, measurement noise is about 22 % higher.
- ¹⁵ For measuring the power of periodic bursts based on an average power measurement.

- To increase measurement speed, the power sensor can be operated in buffered mode. In this mode, measurement results are stored in a buffer of user-definable size and then output as a block of data when the buffer is full. To enhance measurement speed even further, the sensor can be set to record the entire series of measurements when triggered by a single event. In this case, the power sensor automatically starts a new measurement as soon as it has completed the previous one.
- 17 This parameter enables power measurements on modulated bursts. The parameter must be longer in duration than modulation-induced power drops within the burst.
- ¹⁸ To exclude unwanted portions of the signal from the measurement result.
- 19 Valid for Repeat mode, extending from the beginning to the end of all transfers via the USB interface of the power sensor. Measurement times under remote control of the R&S®NRX base unit via IEC/IEEE bus are approximately 2.5 ms longer, extending from the start of the measurement up to when the measurement result has been supplied to the output buffer of the R&S®NRX.
- ²⁰ Integration time is defined as the total time used for signal acquisition, i.e. taking into account the chosen aperture/acquisition time and the averaging number
- ²¹ Magnitude of measurement error referenced to an ideal thermal power sensor that measures the sum power of carrier and harmonics. For the R&S®NRP-Z211/-Z221, specifications apply to automatic path selection and power levels up to +16 dBm or, within a subrange, to 0.1 mW (–10 dBm) for path 1 and 40 mW (+16 dBm) for path 2. Above the mentioned power limit, specifications must be raised by a factor of 1.25 per 1 dB rise in power level. Within a subrange, measurement errors are proportional to the measured power in W.
- Measurement error referenced to a CW signal of equal power and frequency. For the R&S®NRP-Z211/-Z221, specifications apply to automatic path selection and power levels up to +16 dBm or, within a subrange, to 0.1 mW (-10 dBm) for path 1 and 39.8 mW (+16 dBm) for path 2 Above the mentioned power limit, specifications must be raised by a factor of 1.25 per 1 dB rise in power level. Within a subrange, measurement errors are proportional to the measured power in W.
- $^{23}\,$ Applies to the R&S®NRP-Z211/-Z221, referenced to 0 dBm.
- Expanded uncertainty (k = 2) for absolute power measurements on CW signals at the calibration level within a temperature range from +20 °C to +25 °C and at the calibration frequencies (10 MHz, 15 MHz, 20 MHz, 30 MHz, 50 MHz, 100 MHz; in steps of 250 MHz from 250 MHz to the upper frequency limit). Specifications include zero offset and measurement noise (up to a 2σ value of 0.004 dB). The calibration level for the R&S®NRP-Z211/-Z221 is -10 dBm for paths 1 and 2.
- ²⁵ Equivalent source SWR.
- ²⁶ Between RF input and RF output (test port).
- 27 With activated auto delay, the beginning of a measurement sequence is delayed so that settled readings are obtained even if the measurement command (remote trigger) coincides with a signal step up to ±10 dB.
- Expanded uncertainty (k = 2) for absolute power measurements up to 100 mW (+20 dBm) at the calibration frequencies (see endnote 30). Specifications include calibration uncertainty, linearity, temperature effect and interference from the wave reflected by the load on the RF output. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. If the measured power exceeds 100 mW, the power coefficient of the integrated power splitter must be taken into account (see endnote 33). As a rule of thumb, the contribution of zero offset can be neglected for power levels above –7 dBm if external zeroing has been applied. The contribution of measurement noise can be neglected below 0.01 dB.

Example: The power to be measured with an R&S®NRP-Z37 is 50 μW (–13 dBm) at 19 GHz; ambient temperature +29 °C; averaging number set to 64 in continuous average mode with an aperture time of 20 ms.

The maximum absolute uncertainty due to zero offset (after external zeroing) is 400 nW, which corresponds to a relative measurement uncertainty of

$$10 \times \lg \frac{50 \mu W + 400 \text{ nW}}{50 \mu W} = 0.035 \text{ dB}.$$

Using the formula in endnote 9, the maximum absolute noise contribution is 240 nW × $\sqrt{(10.24 \text{ s/}(64 \times 2 \times 0.02 \text{ s}))}$ = 480 nW, which corresponds to a relative measurement uncertainty of

$$10 \times \lg \frac{50 \mu W + 480 \text{ nW}}{50 \mu W} = 0.042 \text{ dB}.$$

Combined with the value of 0.137 dB specified for the uncertainty of absolute power measurements, the total expanded uncertainty is

$$\sqrt{0.035^2 + 0.042^2 + 0.137^2}$$
 dB = 0.148 dB.

- Expanded uncertainty (k = 2) for relative power measurements on CW signals of the same frequency. Specifications include linearity and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset can be neglected for power levels above –7 dBm if external zeroing has been applied. The contribution of measurement noise can be neglected below 0.01 dB. See also the example in endnote 9 for taking into account zero offset and noise with relative measurements.
- 30 Expanded uncertainty (k = 2) for absolute power measurements at the calibration level (0 dBm) within a temperature range from +20 °C to +25 °C and at the calibration frequencies. Specifications include zero offset and measurement noise (up to a 2σ value of 0.004 dB). The load on the RF signal output must be of a low-reflection type (SWR < 1.05) or load interference correction must be applied.</p>
 - Calibration frequencies: 0.1/0.5/1/3/5/10/50/100 MHz; in steps of 100 MHz from 100 MHz to the upper frequency limit.
- 31 Error of an absolute power measurement with respect to temperature, taking into account the power sensor section, the power splitter and the RF cable (temperature-dependent interference from the load on the RF signal output due to phase change).
- 32 Expanded uncertainty for relative power measurements on CW signals of the same frequency, referenced to the calibration level (0 dBm) and excluding zero offset, zero drift and measurement noise.
- 33 Maximum change of insertion loss of the power splitter with respect to input power, leading to an equivalent measurement error of the power sensor module and a change of the power available at the RF signal output. The power coefficient should be taken into account if the input power exceeds 100 mW (+20 dBm).

- ³⁴ Measurement error due to interference of the wave reflected by a mismatched load on the RF signal output. Specifications are indicated for a 0.1 reflection coefficient of the load. Since the load interference error is proportional to the amplitude of the reflected wave, half (twice) the values will be encountered for a reflection coefficient of 0.05 (0.2). The error introduced by an R&S®FSMR26 at the RF signal output does not exceed ±0.06 dB from DC to 2 GHz, ±0.10 dB up to 18 GHz, and ±0.14 dB up to 26.5 GHz.
 - Values in () represent residual error contribution after numeric load interference correction. This correction function requires the complex reflection coefficient of the load to be transferred to the power sensor module. The residual error contribution of an R&S®FSMR26 at the RF signal output does not exceed ±0.003 dB from DC to 2 GHz, ±0.04 dB up to 18 GHz, and ±0.07 dB up to 26.5 GHz.
- 35 The operating temperature range defines the span of ambient temperature in which the instrument complies with specifications. In the permissible temperature range, the instrument is still functioning but compliance with specifications is not warranted.
- ³⁶ For options installed, the remaining base unit warranty applies if longer than 1 year. Exception: all batteries have a 1 year warranty.
- ³⁷ Excluding defects caused by incorrect operation or handling and force majeure. Wear-and-tear parts are not included.

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