**ROHDE & SCHWARZ** Make ideas real



### AREG800A AUTOMOTIVE RADAR ECHO GENERATOR

Accelerate your radar testing with the most advanced solution

Product Brochure | Version 05.00



# YOUR **CHALLENGE**

Developers of new automotive radar sensors, radar based advanced driver assistance systems (ADAS) and autonomous driving (AD) features face demanding challenges during each step of the development process.

Individual test scenarios or even the entire test philosophy can change during development when new unpredictable test cases emerge. Moreover, there is an increasing variety of radar sensors, growing modularity and a higher number of ADAS functions. These issues, as well as shorter sensor development cycles for upcoming vehicles, are making test procedures more complex. These conditions require a test concept and a test environment that are dynamic, flexible and scalable.

Currently available test equipment can only simulate a very limited set of test cases and scenarios. The lack of RF stimulation solutions for radar sensors is a huge challenge today. As a result, radar sensors and ADAS functions cannot be consistently and reproducibly tested/verified in either the sensor and ADAS feature development phases or during the vehicle homologation phase on the test rig.

### Open standard control interface

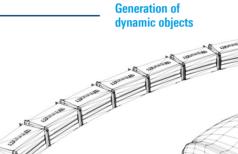
The AREG800A is controlled in open-loop and closedloop test environments through a robust, open, real-time interface in line with the open simulation interface (OSI) specification.

### A new level of possibilities

The AREG800A meets current and future test requirements and can easily be tailored to individual needs thanks to its flexible, software defined configuration concept.

The AREG800A generates multiple complex artificial objects with variable distance, radial velocity and RCS. It supports up to 5 GHz of instantaneous bandwidth. The AREG800A is a smart instrument suitable for dynamic and complex object generation in all automotive radar bands. The frequency ranges offered by the AREG800A are 0.7 GHz to 5.7 GHz, 24 GHz to 24.25 GHz, 24 GHz to 44 GHz and 76 GHz to 81 GHz, ensuring compatibility with future ISAC sensors and all automotive radars, including future short-range radar sensors and their applications, e.g. for collision avoidance systems.

### 



Tailored to your needs

The flexible AREG800A design covers all applications fulfilling all the requirements along the whole automotive radar testing life cycle, from early radar sensor R&D to advanced HiL/ViL ADAS/AD test cases and radar mass production testing. Thanks to its field-upgradeable concept, extra features can be added easily by installing software keycodes on site. There is no need for service appointments, and service turnaround time is avoided.



Scalable soluti

The AREG800A is the key enabler for testing automotive radar sensors and ADAS/AD features. Complex artificial objects can be generated with variable distance, radial velocity, size (RCS), azimuth or elevation angles. An instantaneous bandwidth of 5 GHz covers the typical frequency range of current and future automotive radar sensors. The capability to simultaneously generate a large number of dynamic artificial objects makes it possible for the first time to run realistic and reproducible tests in lab environments. Flexibility at its best The AREG800A meets all requirements for demanding automotive radar echo generation applications:

- Produce state-of-the-art 4D imaging radar sensors with high demands on the radar test equipment
- Simulate angular echo distribution or multiple echoes from a sinale direction
- Usage even in comprehensive and dynamic EMC environments Complies with the Radio Equipment Directive and to exploit the maximum EiRP
- testing using the AREG800A brings safe ADAS/AD on the road
- Automotive radar interference mitigation algorithm performance ► High sensitivity radar signal analysis measurements allowed

### Bring road reality to your lab

The AREG800A combined with the R&S®QAT100 advanced antenna array and R&S<sup>®</sup>AREG8-xx mmWave remote frontends lets users tackle major autonomous driving challenges. Road tests for ADAS/ AD feature development and validation can be transferred from the road to the test rig in a realistic manner. This streamlines R&D, testing and validation times, optimizes time to market for new radar sensors and ADAS/AD functions and reduces costs for R&D and testina.

### Realistic ADAS/AD scenario generation

objects

Seamless integration of AREG800A

thanks to an open and standardized

control interface

A single AREG800A connected to an R&S®QAT100 advanced antenna array can generate echoes from up to eight different angular directions. Individual objects can be generated from all eight directions simultaneously (one per direction). Objects can have variable dynamic distance, velocity or object size (RCS). It is now possible for the first time to simulate realistic driving scenarios for automotive radar sensors during ADAS/AD tests.



### and support

### Worldwide service and support

The Rohde&Schwarz service network in over 70 countries ensures optimum on-site support with minimal turnaround times.

# **OUR SOLUTIONS**

The AREG800A automotive radar echo generator is an innovative and versatile solution for testing automotive radar sensors. It supports test cases requiring single/dual antenna frontends such as the R&S®AREG8-81S 81S/D (with 4 GHz instantaneous RF bandwidth), R&S®AREG8-81WS/WD (with 5 GHz instantaneous RF bandwidth), or multiple integrated antennas such as the R&S®QAT100 advanced antenna array with 4 GHz instantaneous RF bandwidth.

Thanks to the full harmonization of the AREG800A with the R&S®QAT100 advanced antenna array, all test requirements for the most advanced radar scenario simulations are covered.

### Discover the ultimate automotive radar testing solution

- Simulate objects with dynamic distance variation during early R&D, chipset development and radar sensor validation
- Use hardware-in-the-loop (HiL) test cases during ADAS/AD feature and algorithm development
- Use vehicle-in-the-loop (ViL) test cases with realistic driving sce-narios on the roller dyno for vehicle certification and homologation

## **DISCOVER THE ULTIMATE AUTOMOTIVE RADAR TESTING** SOLUTION

### Generate dynamic artificial objects

- ▶ Generate multiple complex artificial objects with individually variable distance, radial velocity and object size (RCS) for advanced automotive radar test cases
- Combine with the R&S®QAT100 advanced antenna array to generate artificial objects with individual angular directions for ADAS/AD scenario based testing
- Standard artificial object distances ranging from < 17 m to 3000 m
- ▶ Minimum object distance can be reduced to < 4 m with an optional internal analog stepped delay line, e.g. for autonomous emergency braking (AEB) tests
- ▶ For FMCW radars, the minimum object distance can be digitally reduced down to the air gap value of the radar under test using a patented and unique software feature suitable for extremely short object distance generation
- Designed for scenario generation: simulate up to eight artificial objects with individual distance, object size, radial velocity and direction expressed in azimuth/ elevation angle when used in combination with the R&S®QAT100
- Simulate up to 32 objects with individual distance, object size and radial velocity using four AREG800A mmWave remote frontends

### Easy and intuitive operation

- Intuitive graphical user interface with touchscreen controls for manual operation and monitoring the entire test setup
- Easy, straightforward test setup configuration directly on the AREG800A itself; no need for a PC
- ▶ Built-in SCPI macro recorder with code generator for easy integration into existing test software
- Linux based operating system provides maximum software stability for 24/7 test operation
- Scenario preview for fast debugging and overview

### Scalability and flexibility

6

- Offers flexible, easy and sustainable test-setup adaption to new requirements and test cases, thanks to a configuration concept based mainly on keycode-activated software options
- Incorporates simultaneous control for up to four conventional mmWave remote frontends or up to eight R&S®OAT100 advanced antenna arrays for simple extension of test capabilities
- Calibrated IF input and output interfaces to connect additional test and measurement equipment for automotive radar measurement tasks (for example, testing for robustness against interfering signals using a connected signal generator, or signal monitoring using a connected signal and spectrum analyzer)

### **Real-time interface**

- Built-in real-time interface for hardware-in-the-loop and vehicle-in-the-loop test setups
- ▶ Open simulation interface (OSI) supported as an open, generic interface for environmental perception of ADAS/AD features with scenario update rates of < 0.15 ms
- ► Synchronization of multiple R&S®QAT100 advanced antenna arrays and AREG800A automotive radar echo generators to generate dense scenarios with a large number of individual artificial objects
- Synchronous parallel over-the-air simulation of multiple automotive radar sensors to test advanced ADAS/AD features involving multiple radar sensors, and sensor data fusion

### Frontends for every test case

The AREG800A perfectly addresses the industry's need for a versatile radar echo generator. With its RF frontend portfolio, the AREG800A can be tailored exactly to your application-specific testing needs:

- ► The innovative R&S®QAT100 advanced antenna array for generating artificial objects from varying angular directions enables ADAS/AD feature and scenario based test cases in the 76 GHz to 81 GHz frequency band
- Conventional millimeterwave (mmWave) remote frontends in all automotive radar bands for benchtop sensor validation. All mmWave remote frontends are available in a single antenna configuration for optimized MIMO testing or in a two antenna configuration with high

RX/TX isolation to minimize ringaround

- ► All supported RF frontends are connected by cable to the base unit and fully controlled by the AREG800A, enabling easy, user-friendly operation; the test setup works as a one-box solution
- ► Frontend switching supports hot swapping between different radar bands for maximum flexibility in the test setup



# FLEXIBILITY AT ITS BEST FOR SENSOR VALIDATION IN R&D

Highest test case flexibility thanks to remote frontends Performance-optimized T&M equipment is required for validating and optimizing future automotive radar sensors. Test cases typically include a wide range of RF parameters that need to be checked for final acceptance tests. As the core of radar test and validation setups, the AREG800A provides R&D engineers with a versatile, future-proof radar tester for evaluating all relevant sensor parameters. Its modular concept and support for conventional mmWave remote frontends (R&S®AREG8-81S/D. R&S®AREG8-24S/D, R&S®AREG8-81WS/WD, etc.) make it easily adaptable to the testing requirements of different sensor products and OEMs. Separate frontends for 24 GHz to 24.25 GHz and 76 GHz to 81 GHz permit hot swapping between different radar bands. If a radar sensor specification requires more advanced test cases - angular artificial object separability performance tests for a radar sensor under test (RUT), for example - the AREG800A combined with the R&S®QAT100 is the right solution for the challenge.

### Validation of cutting-edge 4D imaging radar sensors

The AREG800A combined with the R&S®ATS1500C antenna measurement chamber forms a harmonized solution for accurate automotive radar validation and calibration under far-field conditions as a reliable basis for ADAS/ AD features. The AREG800A easily integrates with the chamber. With conventional mmWave remote frontends in single antenna configuration, DUTs can be tested under far-field conditions.

The R&S®ATS1500C was specially developed for testing the latest automotive radar sensors. Based on the compact antenna test range (CATR) principle, it provides measurements under far-field conditions in a compact footprint, even for premium MIMO sensors. The AREG800A and conventional R&S®AREG mmWave remote frontends are perfect for this use case.

AREG800A and R&S®ATS1500C: A perfect team for the development of 4D imaging radars.



### Generation of dynamic artificial objects for every application

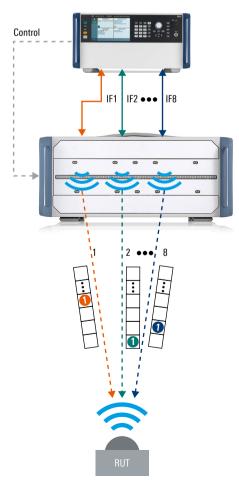
The AREG800A automotive radar echo generator can be operated with the R&S®QAT100 advanced antenna array or conventional mmWave remote frontends.

A single AREG800A connected to an R&S®OAT100 antenna can generate echoes from up to eight different angular directions. Individual objects can be generated from all eight directions simultaneously (one per direction) or from one direction after the other; an ideal solution for advanced scenario generation, like the test cases defined by Euro NCAP. When the AREG800A is used in combination with the mmWave remote frontends, up to four mmWave remote frontends can be connected to a single base unit with up to eight individual artificial objects per mmWave remote frontend.

Individual artificial objects can have variable, dynamic distance, velocity and object size (RCS).

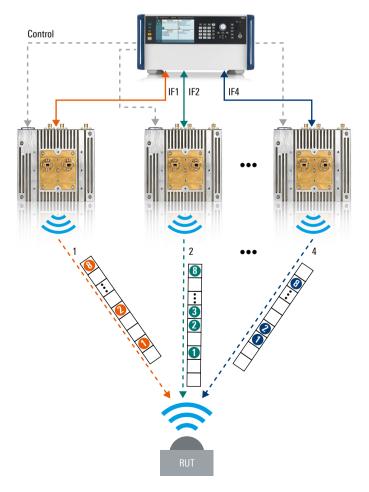
### AREG800A combined with R&S®0AT100

Up to eight independent angular directions with a maximum of one individual artificial object per direction.



#### AREG800A combined with mmWave remote frontends

Up to four mmWave remote frontends can be connected to a single base unit, with up to eight individual artificial objects generated per frontend.



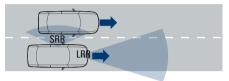
# **BRING ROAD REALITY TO YOUR LAB** WITH REALISTIC HIL TESTING

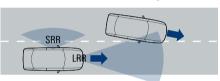
When testing new ADAS/AD features, the first steps are performed in hardware-in-the-loop/closed-loop setups where the radar sensor and associated ADAS electronic control unit (ECU) are stimulated based on simulated driving scenarios.

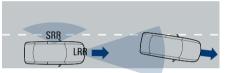
Reliable closed-loop sensor tests require driving scenario parameters calculated by the scenario simulator to be correctly synchronized for the test subsystems. As the core element of a closed-loop test system, the AREG800A has a built-in real-time control interface that can process artificial object data provided by the driving scenario simulator. With scenario update rates faster than 0.15 ms and OSI support, the AREG800A perfectly addresses the requirements of closed-loop test systems for realistic and reproducible scenario generation.

ADAS/AD functions such as recognizing when a vehicle cuts in rely on fusing data from several radar sensors covering the front, side and back of the vehicle. The AREG800A in combination with the R&S<sup>®</sup>QAT100 is ideal for testing such highly complex scenarios. The AREG800A enables synchronous parallel stimulation of multiple automotive radar sensors for testing challenging ADAS/AD functions.



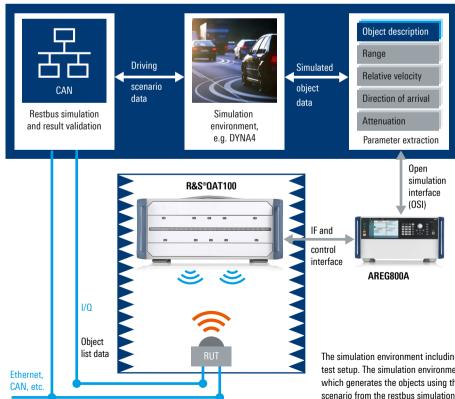






LRR: Long-range radar SRR: Short-range radar

### Example of a closed-loop test setup based on the AREG800A, with angular artificial object directions generated by the R&S®0AT100



The simulation environment including restbus simulation closes the loop between the RUT and the test setup. The simulation environment streams the simulated artificial object data to the AREG800A, which generates the objects using the R&S®0AT100. The RUT gets the data necessary for the scenario from the restbus simulation and transmits its object list back to the simulation environment and to the result validation.

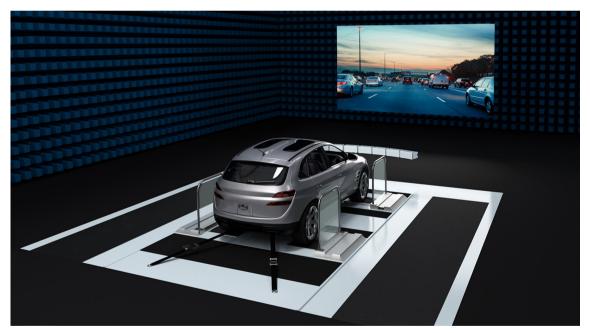
CAN signals from restbus simulation

# TEST LIKE IT IS REAL – FROM ROAD TO RIG FOR VIL TESTING

The AREG800A combined with the R&S®QAT100 as part of the AVL DRIVINGCUBE<sup>™</sup> opens a completely new range of possibilities for testing radar based ADAS and AD features to ensure correct operation in vehicle-in-the-loop (ViL) test beds. Using a ready-to-drive vehicle mounted on a test bed increases efficiency and safety in scenario based testing during validation and certification of ADAS/ AD features.

Reducing the number of accidents and severe injuries is one of the major goals of autonomous driving. Advanced driver assistance functions are just an intermediate step on the journey towards fully autonomous self-driving cars. Some functions, like adaptive cruise control (ACC), increase driver comfort or compensate for driver inattention. Other functions, like autonomous emergency braking (AEB), are relevant for Euro NCAP testing and are therefore extensively tested.

When the AREG800A and the R&S®OAT100 are integrated into the DRIVINGCUBE<sup>™</sup> solution from AVL, defined Euro NCAP test cases can be executed with maximum reproducibility, thanks to the complete absence of mechanical moving components. The test setup is unaffected by the strong vibration that typically occurs on ViL test beds. No matter what your ViL testing challenge is, the flexible, scalable AREG800A and R&S®OAT100 concept always provides a suitable solution. Multiple R&S®OAT100 arrays can be combined to cover larger fields of view.



Rohde & Schwarz combined with AVL: A successful partnership provides a game changing ViL solution

#### Scenario testing for ADAS and AD in line with Euro NCAP

Scenario	Covered by Rohde&Schwarz solution
Autonomous emergency braking (AEB) – city	yes
Autonomous emergency braking (AEB) – pedestrian	yes
Autonomous emergency braking (AEB) – cyclist	yes
Autonomous emergency braking (AEB) – interurban	yes
Lane support	yes
Adaptive cruise control (ACC)	yes

## ROAD SAFETY – PRODUCE HIGH QUALITY 4D IMAGING RADAR SENSORS

### Testing state-of-the-art automotive radar sensors in tier 1 production

The AREG800A combined with its conventional mmWave remote frontends is a versatile tester for automotive radar sensors. It can be tailored to all manufacturing processes, including initial sensor calibration, with test cases such as antenna pattern measurement and functional testing. It ensures continuous product quality control and reliable identification of faulty sensors.

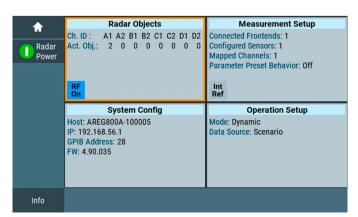
The ability to generate multiple artificial objects with dynamic distance, radial velocity and object size (RCS) ensures maximum test case flexibility. Production test engineers benefit from a robust, flexible and future-proof solution.

Connecting a signal and spectrum analyzer to the IF output interface of the AREG800A makes it possible to measure the relevant indicators for radar sensor quality, such as occupied bandwidth and equivalent isotropically radiated power (EIRP), for the radar sensor under test.

### Radar sensor validation in OEM automotive assembly lines

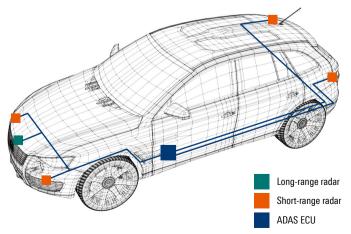
To ensure customer satisfaction and reduce aftersales service expense for the OEM, radar based ADAS sensors need to work as intended when a vehicle leaves the production line. After final integration of the automotive radar sensors into the car bumpers, conducting a function test and initializing the ADAS sensors are extremely important steps during final in-depth testing at the end of the vehicle assembly line.

Cars typically have one long-range radar (LRR) sensor for adaptive cruise control and multiple short-range radar (SRR) sensors for collision avoidance systems. All long-range radar sensors and short-range radar sensors installed in a car need to be examined. OEMs crosscheck correct sensor installation and overall functionality. With the AREG800A, these tests can be optimized because multiple synchronized frontends can be used with a single base unit. Synchronous sensor testing saves test time, reduces overall costs and minimizes the footprint in production.



The simple, intuitive graphical user interface and built-in AREG800A touchscreen make it easy to monitor the status of the production test system.

The AREG800A enables testing optimized for time, cost and footprint for all SRRs and LRRs installed on a single vehicle in OEM assembly lines.



## PERFECTLY TAILORED TO YOUR TEST APPLICATIONS ALONG THE AUTOMOTIVE RADAR ECO CHAIN

### Seamless radar sensor validation in line with the V model

V models are often used in the automotive industry to optimize development project scheduling. Thanks to the flexibility of the AREG800A and the variety of applications that can be addressed with it, tailored reference solutions. They range from component development to vehicle validation:

#### ► Component level:

Artificial object generation with dynamic distance, object size and radial velocity during chipset development for tier 2 suppliers and radar sensor R&D for tier 1 suppliers

### System level test:

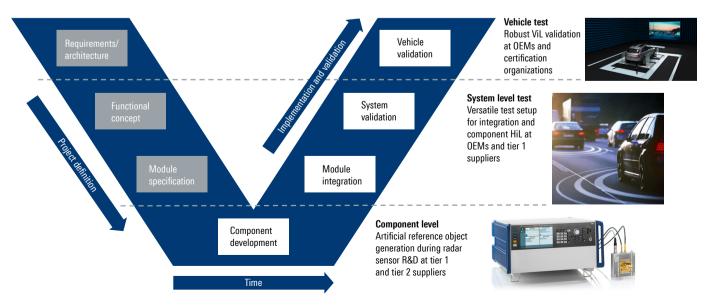
Hardware-in-the-loop (HiL) test cases; during radar sensor module integration and full system validation of ADAS/AD features at tier 1 suppliers and OEMs

### Vehicle test:

Vehicle-in-the-loop (ViL) test cases with realistic driving scenarios on the roller dyno for vehicle certification and homologation at both the OEM and certification organizations

### The V model for automotive radar and ADAS/AD development

The AREG800A addresses all radar sensor tests during component R&D and ADAS/AD implementation and validation.



# **SPECIFICATIONS IN BRIEF**

Specifications in brief

Echo generator type     dynamic artificial dystage generation       Echo generator type     approximation concept       Esho generation concept     approximation concept       Supported remote frontends     R85*AFEG9 245/24D/E15/81D/E1WS/DIWD       Concentration frontends     R85*AFEG9 245/24D/E15/81D/E1WS/DIWD       Concentration frontends     R85*AFEG9 245/24D/E15/81D/E1WS/DIWD       Concentration frontends     R85*AFEG9 245/24D/E15/81D/E1WS/DIWD       Concentration frontends     R85*AFEG9 245/24D/E15/81D/E1WS/DIWD       Maximum number of remote frontends     R85*AFEG9 245/24D/E15/81D/E1WS/DIWD       Maximum number of remote frontends     R85*AFEG9 245/24D/E1S/81D/E1WS/DIWD       Maximum number of remote frontends     R85*AFEG9 245/24D/E1S/81D/E1WS/DIWD       Maximum number of remote frontends     R85*AFEG9 245/24D/E1S/81D/E1WS/E1WD       R85*AFEG9 245/24D/E1S/E1WE/E1WS/E1WD	Specifications in brief		
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Maximum number of remote frontends pri AFEG800A base unit     R8S*AFEG8-245/24D/815/81D/81WS/81W0     up to 8 R8S*0AT100 up to 8 external frontends, 4 for TX and 4 for (4 pairs)       Frequency range     Instantaneous RF bandwidth     R8S*AFEG8-989 with R8S*AFEG8-K527     2 GHz       Instantaneous RF bandwidth     R8S*AFEG8-989 with R8S*AFEG8-K527     2 GHz       R8S*AFEG8-989 with R8S*AFEG8-K527     2 GHz       R8S*AFEG8-898 With R8S*AFEG8-K527     2 GHz       R8S*AFEG8-898     5 GHz       R8S*AFEG8-898     5 GHz       R8S*AFEG8-898     7 GHz to 81 GHz       With R8S*AFEG8-815/91D/91WS/81WD     76 GHz to 81 GHz       R8S*AFEG8-898     < 17 m + air gap (meas.)		R&S°QATTUU	antenna array
par AREG800A base unit     H85*0AT100     up to 8 B85*0AT100       R85*0AT100     up to 8 B85*0AT100       the sectional innivere remote instructional minivere remote instructional minivere remote instructional minivere remote instructional minivere remote instructional minister remote instructional ministere remote instructional minister remote instructional minist		R&S <sup>®</sup> FE44S	external frontends
B&S*FE44S     up to 8 external frontends, 4 for TX and 4 for (4 pirs)       Frequency range       Instantaneous RF bandwidth     R85*AREG8-B9     1 GHz       R85*AREG8-B9 with R85*AREG8-K527     2 GHz       R85*AREG8-B3 With R85*AREG8-K527     2 GHz       R85*AREG8-B3 With R85*AREG8-S125*AD     24 GHz to 24.25 GHz       with R85*AREG8-B315*ADD-81W5/N81WD     76 GHz to 81 GHz       Artificial object     with R85*AREG8-B315*ADD-81W5/N81WD       Minimum artificial object distance     R85*AREG8-B9 with R85*AREG8-B63     < 17 m + air gap (meas.)		R&S®AREG8-24S/-24D/-81S/-81D/-81WS/-81WD	up to 4 conventional mmWave remote frontend
Prequency range     Instantaneous RF bandwidth     RSS*AREG8-B9     I GHz       Instantaneous RF bandwidth     RSS*AREG8-B9 with RSS*AREG8-K527     2 GHz       RSS*AREG8-B9 with RSS*AREG8-K527     2 GHz       RSS*AREG8-B9 with RSS*AREG8-K527     2 GHz       RSS*AREG8-St28     5 GHz       RSS*AREG8-St28     2 GHz       RSS*AREG8-St28     2 GHz       RSS*AREG8-St28     2 GHz       RSS*AREG8-St28     2 GHz       RSS*AREG8-B9     7 G Hz to 24.25 GHz       RSS*AREG8-S0     2 GHz to 34 GHz       RSS*AREG8-B9     7 M + air gap (meas.)       RSS*AREG8-B9 with RSS*AREG8-B63     < 4 m + air gap (meas.)		R&S®QAT100	1
Instantaneous RF bandwidthR8S*AREG8-B9In R8S*AREG8-K527I GH2R S8*AREG8-B9With R8S*AREG8-K527GH2R S8*AREG8-K528GH2R F frequency bandsWith R8S*AREG8-K527GH2With R8S*AREG8-K528GH2With R8S*AREG8-K528GH2With R8S*AREG8-K528GH2With R8S*AREG8-K528GH2 to 24.55 GH2With R8S*AREG8-B3/S-101/61WS/81WDGH2 to 24.55 GH2Attificial object distanceR8S*AREG8-B9Minimum artificial object distanceR8S*AREG8-B9R8S*AREG8-B9 with R8S*AREG8-B83<4 m + air gap (meas.)		R&S°FE44S	
R8S*AREG8-B9 with R8S*AREG8-K527     2 GHz       R8S*AREG8-B9 with R8S*AREG8-K527 and R8S*AREG8-K528     5 GHz       RF frequency bands     with R8S*AREG8-24S/-24D     24 GHz to 24.25 GHz       with R8S*AREG8-B1S/-B1D/-B1WS/-B1WD     76 GHz to 81 GHz     24 GHz to 24.25 GHz       with R8S*AREG8-B1S/-B1D/-B1WS/-B1WD     76 GHz to 81 GHz     24 GHz to 24.25 GHz       with R8S*AREG8-B1S/-B1D/-B1WS/-B1WD     76 GHz to 81 GHz     24 GHz to 24.25 GHz       Artificial object distance     R8S*AREG8-B1S/-B1D/-B1WS/-B1WD     76 GHz to 81 GHz       Minimum artificial object distance     R8S*AREG8-B9     <17 m + air gap (meas.)			
R8S*AREG8-B9 with R8S*AREG8-K527 and R8S*AREG8-K528     5 GHz       RF frequency bands     with R8S*AREG8-24S7/24D     24 GHz to 24.25 GHz       with R8S*AREG8-24S7/24D     76 GHz to 81 GHz       with R8S*AREG8-81S/81D/81WS/81WD     76 GHz to 81 GHz       R8S*REG8-81S/81D/81WS/81WD     76 GHz to 81 GHz       R8S*REG8-B9     71 m + air gap (meas.)       Artificial object     R8S*AREG8-B9     <17 m + air gap (meas.)	Instantaneous RF bandwidth		
R8S*AREG8-K528         5 GHz           RF frequency bands         with R8S*AREG8-245/-24D         24 GHz to 24.25 GHz           with R8S*AREG8-815/-81D/-811WS/-811WD         76 GHz to 81 GHz           with R8S*AREG8-815/-81D/-811WS/-811WD         76 GHz to 81 GHz           R8S*AREG8-89         24 GHz to 44 GHz           Artificial object         885*AREG8-89 with R8S*AREG8-863         <4 m + air gap (meas.)			2 GHz
with R&S*AREG8-81S/-81D/-81WS/-81WD76 GHz to 81 GHzwith R&S*QAT10076 GHz to 81 GHzR&S*FE44S24 GHz to 44 GHzArtificial objectsMinimum artificial object distanceR&S*AREG8-B9R&S*AREG8-B9 with R&S*AREG8-B63< 4 m + air gap (meas.)			5 GHz
with R&S*QAT10076 GHz to 81 GHzR&S*FE44S24 GHz to 44 GHzArtificial objectsMinimum artificial object distanceR&S*AREG8-B9 with R&S*AREG8-B63< 17 m + air gap (meas.)	RF frequency bands	with R&S®AREG8-24S/-24D	24 GHz to 24.25 GHz
Rds"FE4dS24 GHz to 44 GHzArtificial object distanceRds"AREG8-B9v17 m + air gap (meas.)Minimum artificial object distanceRds"AREG8-B9 with Rds"AREG8-B63 and Rds"AREG8-B9 With Rds"AREG8-B63 and Rds"AREG-DBP1/-DBP2/-DBP2 with Rds"AREG-DBP1/-DBP2/-DBP3 with Rds"AREG-DBP1/-DBP2/-DBP3 with Rds"AREG-MP2/-PBPair gap to 3000 m (meas.) f FMCW, rds"artificial object distance < 4 m to 3000 m (distance, RCS, Doppler (up to 4 objects between 17 m and 3000 m) (distance, RCS, DopplerMaximum number of artificial object distance > 17 m to 3000 m + air gapup to 8 with individual azimuth/elevation, distance, RCS, DopplerMaximum number of artificial object distance > 17 m to 3000 m + air gapup to 8 with individual azimuth/elevation, distance, RCS, DopplerMaximum number of artificial object distance > 17 m to 3000 m + air gapup to 8 with individual azimuth/elevation, distance, RCS, DopplerMaximum number of artificial object distance > 17 m to 3000 m + air gapup to 32 (up to 8 per frontend (up to 4 objects between 17 m and 3000 m) distance, RCS, DopplerMaximum number of artificial object distance > 17 m to 3000		with R&S®AREG8-81S/-81D/-81WS/-81WD	76 GHz to 81 GHz
Artificial objects       R&S*AREG8-B9       < 17 m + air gap (meas.)		with R&S®QAT100	76 GHz to 81 GHz
Minimum artificial object distanceR&S*AREG8-B9< 17 m + air gap (meas.)R&S*AREG8-B9 with R&S*AREG8-B63< 4 m + air gap (meas.)		R&S®FE44S	24 GHz to 44 GHz
R&S*AREG8-B9 with R&S*AREG8-B63< 4 m + air gap (meas.)R&S*AREG8-B9 with R&S*AREG8-B63 and R&S*AREG8-B9 with R&S*AREG8-B63 and R&S*AREG8-B9 with R&S*AREG8-K814> air gap (meas.)Covered distance range of artificial objectsR&S*AREG8-B9 with R&S*AREG8-B63< 17 m to 3000 m (meas.)	Artificial objects		
R&S*AREG8-B9 with R&S*AREG8-B63 and R&S*AREG8-B9 with R&S*AREG8-B63 and R&S*AREG8-B9 with R&S*AREG8-B3       ≥ air gap (meas.)         Covered distance range of artificial objects       R&S*AREG8-B9       < 17 m to 3000 m (meas.)	Minimum artificial object distance	R&S®AREG8-B9	< 17 m + air gap (meas.)
R&S*AREG8-K814≥ air gap (meas.)R&S*AREG8-B9 with R&S*AREG8-B3< 17 m to 3000 m (meas.)			< 4 m + air gap (meas.)
Covered distance range of artificial objectsR&S*AREG8-B9< 17 m to 3000 m (meas.)R&S*AREG8-B9 with R&S*AREG8-B63< 4 m to 3000 m (meas.)			≥ air gap (meas.)
R&S*AREG8-B9 with R&S*AREG8-B63< 4 m to 3000 m (meas.)R&S*AREG8-B9 with R&S*AREG8-B9 with R&S*AREG8-B63 and R&S*AREG8-B9 with R&S*AREG8-K814≥ air gap to 3000 m (meas.)R&S*AREG8-B9 with R&S*AREG8-K814≥ air gap to 3000 m (meas.)R&S*AREG8-DBP1/-DBP2/-DBP3 with R&S*AREG-MFP/-BFP≥ air gap to 350 m (meas.) for FMCW, < 17 m to 350 m (meas.) for non FMCW		R&S®AREG8-B9 with R&S®AREG8-K814	
R&S*AREG8-B9 with R&S*AREG8-B63 and RS*AREG8-K814       ≥ air gap to 3000 m (meas.)         R&S*AREG8-B9 with R&S*AREG8-K814       ≥ air gap to 3000 m (meas.)         R&S*AREG-DBP1/-DBP2/-DBP3 with RS*AREG-DBP1/-DBP2/-DBP3 with RS*AREG-MFP/-BFP       ≥ air gap to 350 m (meas.) for FMCW, < 17 m to 350 m (meas.) for ron FMCW	Covered distance range of artificial objects	R&S®AREG8-B9	< 17 m to 3000 m (meas.)
R&S*AREG8-K814> air gap to 3000 m (meas.)R&S*AREG8-B9 with R&S*AREG8-K814> air gap to 3000 m (meas.)R&S*AREG-DBP1/-DBP2/-DBP3 with RS*AREG-MFP/-BFP> air gap to 350 m (meas.) for FMCW, < 17 m to 350 m (meas.) for ron FMCW			< 4 m to 3000 m (meas.)
R&S*AREG-DBP1/-DBP2/-DBP3 with R&S*AREG-MFP/-BFP       > air gap to 350 m (meas.) for FMCW,         Maximum number of artificial objects per AREG800A       with R&S*QAT100         artificial object distance < 4 m to 3000 m			≥ air gap to 3000 m (meas.)
R&S®AREG-MFP/-BFP       < 17 m to 350 m (meas.) for non FMCW		R&S®AREG8-B9 with R&S®AREG8-K814	
per AREG800Awith R&S*CUAT 100artificial object distance < 4 m to 3000 m + air gapup to 8 with individual azimuth/elevation, distance, RCS, Doppler (up to 4 objects between 4 m and 17 m and up to 4 objects between 17 m and 3000 m)artificial object distance > 17 m to 3000 m + air gapup to 8 with individual azimuth/elevation, distance, RCS, Dopplerartificial object distance > 17 m to 3000 m + air gapup to 8 with individual azimuth/elevation, distance, RCS, Dopplerwith R&S*AREG8-24S/-24D/-81S/-81D/-81WS/-81WD or with R&S*FE44Sup to 8 with individual azimuth/elevation, distance, RCS, Dopplerwith R&S*AREG8-24S/-24D/-81S/-81D/-81WS/-81WD or with R&S*FE44Sup to 32 (up to 8 per frontend (up to 4 objects between 17 m and 3000 m) up to 28 objects between 17 m and 3000 m)artificial object distance < 4 m to 3000 m + air gapup to 32 (up to 8 per frontend (up to 4 objects between 17 m and 3000 m) up to 32 (up to 8 per frontend) up to 32 (up to 8 per frontend)			
artificial object distance < 4 m to 3000 m + air gapdistance, RCS, Doppler (up to 4 objects between 4 m and 17 m and up to 4 objects between 17 m and 3000 m)artificial object distance > 17 m to 3000 m + air gapup to 8 with individual azimuth/elevation, distance, RCS, Dopplerartificial object distance > air gap to 3000 m with R&S®AREG8-24S/-24D/-81S/-81D/-81WS/-81WD or with R&S®FE44Sup to 8 with individual azimuth/elevation, distance, RCS, Dopplerartificial object distance < 4 m to 3000 m + air gapup to 32 (up to 8 per frontend (up to 4 objects between 17 m and 3000 m)artificial object distance < 17 m to 3000 m + air gapup to 32 (up to 8 per frontend (up to 4 objects between 17 m and 3000 m)		with R&S®QAT100	
+ air gapdistance, RCS, Dopplerartificial object distance ≥ air gap to 3000 mup to 8 with individual azimuth/elevation, distance, RCS, Dopplerwith R&S®AREG8-24S/-24D/-81S/-81D/-81WS/-81WD or with R&S®FE44Sup to 32 (up to 8 per frontend) (up to 4 objects between 4 m and 17 m and up to 28 objects between 17 m and 3000 m) + air gapartificial object distance > 17 m to 3000 m + air gapup to 32 (up to 8 per frontend) (up to 8 per frontend) up to 32 (up to 8 per frontend)			distance, RCS, Doppler (up to 4 objects between 4 m and 17 m and
artificial object distance ≥ air gap to 3000 m       distance, RCS, Doppler         with R&S®AREG8-24S/-24D/-81S/-81D/-81WS/-81WD or with R&S®FE44S         artificial object distance < 4 m to 3000 m		-	
artificial object distance < 4 m to 3000 m + air gapup to 32 (up to 8 per frontend (up to 4 objects between 4 m and 17 m and up to 28 objects between 17 m and 3000 m) 		artificial object distance $\geq$ air gap to 3000 m	
artificial object distance < 4 m to 3000 m + air gap(up to 4 objects between 4 m and 17 m and up to 28 objects between 17 m and 3000 m)artificial object distance > 17 m to 3000 m + air gapup to 32 (up to 8 per frontend)		with R&S®AREG8-24S/-24D/-81S/-81D/-81WS/-81	
artificial object distance > 17 m to 3000 m + air gap up to 32 (up to 8 per frontend)		-	
artificial object distance $\geq$ air gap to 3000 m up to 32 (up to 8 per frontend)			
			up to 32 (up to 8 per frontend)

Air gap     Sections will change according to the distance between frontend reference plane and DUT     to match far-field condition of radar under test to match far-field condition of radar under test       Radial belocity     ves       Individual Doppler frequency shift for each arti- ficial object     ves       RdS*AREG-B9     .500 km/h       Velocity setting range     RdS*AREG-B9     .001 km/h       RdS*AREG-DBP1/-DBP2/-DBP3 with RdS*AREG-DBP1/-DBP2/-DBP3 with RdS*AREG-DBP1/-DBP2/-DBP3 with RdS*AREG-245/-24D/.81S/.81D/.81WS/     90 dB       Option RCS range for all artificial objects     with RdS*AREG8-24S/-24D/.81S/.81D/.81WS/ 81WD     90 dB       Dynamic RCS range for multiple objects     with RdS*AREG8-24S/-24D/.81S/.81D/.81WS/ 81WD     90 dB       Dynamic RCS range for multiple objects     with RdS*AREG8-24S/-24D/.81S/.81D/.81WS/ 81WD     90 dB       Cynamic RCS range for multiple objects     with RdS*AREG8-24S/-24D/.81S/.81D/.81WS/ 81WD     90 dB       Cynamic RCS range for multiple objects     with RdS*AREG8-24S/-24D/.81S/.81D/.81WS/ 81WD     90 dB       Cynamic RCS range for multiple objects     with RdS*AREG8-24S/.24D/.81S/.81D/.81WS/ 81WD     90 dB       Dynamic RCS range for multiple objects     with RdS*AREG8-24S/.24D/.81S/.81D/.81WS/ 81WD     90 dB       Dynamic RCS range for multiple objects     with RdS*AREG8-24S/.24D/.81S/.81D/.81WS/ 81WD     90 dB       Dynamic RCS range for multiple objects     with RdS*AREG8-24S/.24D/.81S/.81D/.81WS/ 81WD <t< th=""><th>Specifications in brief</th><th></th><th></th></t<>	Specifications in brief		
Air gap     object distances and resulting object radar cross sections will change according to the distance between frontend reference plane and DUT     recommendation: air gap should be large enoug omatch far-field condition of radar under test between frontend reference plane and DUT       Radia Velocity     velocity       Individual Doppler frequency shift for each artificial object     velocity       Radia Velocity     stift arge should be large enoug omatch far-field condition of radar under test       Velocity setting range     R&S*AREG8-B9     ±500 km/h       Velocity step size     R&S*AREG8-B9     0.001 km/h       R&S*AREG-DBP1//DBP2//DBP3 with R&S*AREG-MEP/-BFP     0.001 km/h       Level     velocity     stift R&S*AREG8-24S/-24D/-81S/-81D/-81WS/     90 dB       Dynamic RCS range for nullitple objects     with R&S*AREG8-24S/-24D/-81S/-81D/-81WS/     90 dB       on a single IF path     with R&S*AREG8-24S/-24D/-81S/-81D/-81WS/     60 dB       Dynamic RCS range for multiple objects     with R&S*AREG8-24S/-24D/-81S/-81D/-81WS/     60 dB       Partific and test arge and analysis and     R&S*AREG8-K740     IF output savailable on base unit       IF input for radar signal analysis and     R&S*AREG8-K740     IF output savailable on base unit       IF input port for radar signal analysis and     R&S*AREG8-K740     IF output savailable on base unit       IF input port for radar signal analysis and     R&S*AREG8-K740     IF output savailable on base unit </td <td>Object distance accuracy</td> <td></td> <td>±5 cm (meas.)</td>	Object distance accuracy		±5 cm (meas.)
Air gap     sections will change according to the distance between frontend reference plane and DUT     incommendation: air gap should be large enoug to match far-field contine of radar under test between frontend reference plane and DUT       Radial velocity     velocity setting range     RaS*AREG8-B9     ±500 km/h       Velocity setting range     RaS*AREG8-B9     0.001 km/h       RaS*AREG-DBP1/DDP2/DBP3 with RaS*AREG-DBP1/DDP2/DBP3 with RaS*AREG-DBP1/DDP2/DBP3 with RaS*AREG-DBP1/DDP2/DBP3 with RaS*AREG-DBP1/DDP2/DBP3 with RaS*AREG-DBP1/DDP2/DBP3 with RaS*AREG8-245/240//81S/81D/81WS/ on a single IF path     90 dB       Level     with RaS*AREG8-245/240//81S/81D/81WS/ -81WD     90 dB       Dynamic RCS range for all artificial objects on a single IF path     with RaS*AREG8-245/240//81S/81D/81WS/ -81WD     90 dB       Dynamic RCS range for multiple objects per IF path     with RaS*AREG8-245/240//81S/81D/81WS/ -81WD     60 dB       Dynamic RCS range for multiple objects per IF path     with RaS*AREG8-245/240//81S/81D/81WS/ -81WD     60 dB       Dynamic RCS range for multiple objects per IF path     RaS*AREG8-8740     If outputs available on base unit       IF input/D tort for radar signal analysis and PI input/D tort for radar signal analysis and PI input/D tort for radar signal analysis and PI input port for superimosing interferes     RaS*AREG8-K740     IF outputs available on base unit       User interface PI input port for superimosing interferes     RaS*AREG8-K740     IF outputs available on base unit       User interface with touch controls     RaS*ARE	Object distance step size	I.	1 cm
Individual Doppler frequency shift for each arti- ficial objectyesIndividual Doppler frequency shift for each arti- ficial object#\$00 km/hVelocity setting rangeR&S*AREG8-B90.001 km/hVelocity step sizeR&S*AREG-MEP/-DBP2/-DBP3 with R&S*AREG-MFP/-BFP0.05 km/hLevel	Air gap	sections will change according to the distance	recommendation: air gap should be large enoug to match far-field condition of radar under test
Initial object         Yes           Velocity setting range         R&S*AREG8-B9         ±500 km/h           Velocity step size         R&S*AREG-DBP1/-DBP2/-DBP3 with R&S*AREG-DBP1/-DBP2/-DBP3 with R&S*AREG-MFP/-BFP         0.001 km/h           Level         ////////////////////////////////////	Radial velocity		
Velocity step size         R&S*AREG-BB91/-DBP2/-DBP3 with R&S*AREG-DBP1/-DBP3/-DBP3 with R&S*AREG-DBP1/-DBP3/-DBP3 with R&S*AREG-DBP1/-DBP3/-DBP3 with RS*AREG-DBP1/-DBP3/-DBP3 with RS*AREG-DBP1/-DBP3/-DBP3 with restricts and the step size         0.05 km/h           Level         vith R&S*AREG8-24S/-24D/-81S/-81D/-81WS/ -81WD         90 dB           Dynamic RCS range for all artificial objects on a single IF path         with R&S*AREG8-24S/-24D/-81S/-81D/-81WS/ -81WD         90 dB           Dynamic RCS range for multiple objects per IF path         with R&S*AREG8-24S/-24D/-81S/-81D/-81WS/ -81WD         60 dB           Control step size         0.1 dB         -           Amplitude flatness         R&S*0AT100         -           IF input/IF output interface         -         -           IF input/IF output interface         -         -           IF input port for radar signal analysis and EIRP measurements         R&S*AREG8-K740         IF outputs available on base unit           IF input port for superimposing interferers         R&S*AREG8-K740         IF outputs available on base unit           User interface and remote controls         -         -         -           Open standard protocol support         -         -         -           User interface and remote controls         -         -         -           Remote control interfaces         Ethermet         -         - <td>Individual Doppler frequency shift for each arti- ficial object</td> <td></td> <td>yes</td>	Individual Doppler frequency shift for each arti- ficial object		yes
R&S*AREG-DBP1/-DBP2/-DBP3 with R&S*AREG-MFP/-BFP0.05 km/hLevelDynamic RCS range for all artificial objects on a single IF pathwith R&S*AREG8-24S/-24D/-81S/-81D/-81WS/ 90 dB90 dBDynamic RCS range for multiple objects e1 IVDwith R&S*AREG8-24S/-24D/-81S/-81D/-81WS/ 81WD90 dBDynamic RCS range for multiple objects e1 IV pathwith R&S*AREG8-24S/-24D/-81S/-81D/-81WS/ 81WD60 dBDynamic RCS range for multiple objects e1 IV pathwith R&S*OAT100~ 60 dBRCS control step size0.1 dB88S*0AT100~RCS control step size0.1 dB41WD41WDIF input/IF output interfaceR&S*0AT100 standalone< ±5 dB in 4 GHz bandwidth (meas.)	Velocity setting range	R&S®AREG8-B9	±500 km/h
R&S*AREG-MFP/-BFP         0.06 km/h           Level	Velocity step size	R&S®AREG8-B9	0.001 km/h
Dynamic RCS range for all artificial objects on a single IF pathwith R&S*AREG8-24S/-24D/-81S/-81D/-81WS/ -81WD90 dBDynamic RCS range for multiple objects per IF pathwith R&S*AREG8-24S/-24D/-81S/-81D/-81WS/ -81WD60 dBDynamic RCS range for multiple objects -81WDwith R&S*AREG8-24S/-24D/-81S/-81D/-81WS/ -81WD60 dBCRS control step size0.1 dBAmplitude flatnessR&S*OAT100-IF input/IF output interface-IF input/IF output interface-IF output port for radar signal analysis and EIRP measurementsR&S*AREG8-K740IF outputs available on base unitIF input port for superimposing interferesR&S*AREG8-K740IF outputs available on base unitHardware-in-the-loop (HiL) interfaceDedicated HiL interfaceR&S*AREG8-K740IF ioputs available on base unitUser interface and remote controlsCraphical user interface with touch controlsCraphical user interface with touch controlsRemote control interfacesRemote control command setSCPIGeneral dataDimensions (W x H x D)base unitAsse and analysi and sing analysi and sing analysi and sing and and sing and sing and sing and si			0.05 km/h
on a single IF path-BTWDS0 dBDynamic RCS range for multiple objects per IF pathwith R&S*QAT100> 60 dBBWDwith R&S*QAT0060 dBmith R&S*QAT100-RCS control step size0.1 dBAmplitude flatnessR&S*QAT100 standalone< ±5 dB in 4 GHz bandwidth (meas.)	Level		
Dynamic RCS range for multiple objects per IF pathwith R&S*AREG8-24S/-24D/-81S/-81D/-81WS/ -81WD60 dBmuth R&S*QAT100–RCS control step size0.1 dBAmplitude flatnessR&S*QAT100 standalone< ± 5 dB in 4 GHz bandwidth (meas.)	Dynamic RCS range for all artificial objects on a single IF path		90 dB
per IF path-81WD60 dBwith R&S*QAT100-RCS control step size0.1 dBAmplitude flatnessR&S*QAT100 standaloneH input/IF output interface-IF input/IF output interface-IF output port for radar signal analysis and EIRP measurementsIF output savailable on base unitIF input port for superimposing interferersR&S*AREG8-K740IF outputs available on base unitIF input port for superimposing interferersR&S*AREG8-K740IF outputs available on base unitIF output port for superimposing interferersR&S*AREG8-K740IF input savailable on base unitIF output port for superimposing interferersR&S*AREG8-K740IF input savailable on base unitUser interfaceR&S*AREG8-K109HiL co-processorOpen standard protocol supportopen simulation interface (OSI)User interface with touch controlsyesRemote control interfacesEthernetRemote control command setSCPIGeneral dataSCPIDimensions (W × H × D)base unit $462  mm \times 240  mm \times 504  mm$ (18.15 in × 9.44 in x 19.81 in) 5 HU, 19" width		with R&S®QAT100	> 60 dB
RCS control step size0.1 dBAmplitude flatnessR&S*QAT100 standalone< ±5 dB in 4 GHz bandwidth (meas.)	Dynamic RCS range for multiple objects per IF path		60 dB
Amplitude flatnessR&S°QAT100 standalone< ± 5 dB in 4 GHz bandwidth (meas.)IF input/IF output interfaceIF output port for radar signal analysis and EIRP measurementsR&S°AREG8-K740IF outputs available on base unitIF input port for superimposing interferersR&S°AREG8-K740IF inputs available on base unitHardware-in-the-loop (HiL) interfaceR&S°AREG8-K740HiL co-processorDedicated HiL interfaceR&S°AREG8-K109HiL co-processorOpen standard protocol supportopen simulation interface (OSI)User interface and remote controlsyesRemote control interfacesEthernetRemote control command setSCPIGeneral dataSCPIDimensions (W × H × D)base unit462 mm × 240 mm × 504 mm (18.15 in × 9.44 in x 19.81 in) 5 HU, 19" width		with R&S®QAT100	-
IF input/IF output interface       IF output port for radar signal analysis and EIRP measurements       IF outputs available on base unit         IF input port for radar signal analysis and EIRP measurements       R&S*AREG8-K740       IF outputs available on base unit         IF input port for superimposing interferers       R&S*AREG8-K741       IF inputs available on base unit         Hardware-in-the-loop (HiL) interface       R&S*AREG8-K741       IF inputs available on base unit         Dedicated HiL interface       R&S*AREG8-K109       HiL co-processor         Open standard protocol support       open simulation interface (OSI)         User interface and remote controls       yes         Remote control interfaces       Ethernet         Remote control command set       SCPI         General data       SCPI         Dimensions (W × H × D)       base unit       462 mm × 240 mm × 504 mm (18.15 in × 9.44 in × 19.81 in) 5 HU, 19" width	RCS control step size		0.1 dB
IF output port for radar signal analysis and EIRP measurements       R&S*AREG8-K740       IF outputs available on base unit         IF input port for superimposing interferers       R&S*AREG8-K741       IF inputs available on base unit         Hardware-in-the-loop (HiL) interface       R&S*AREG8-K709       HiL co-processor         Dedicated HiL interface       R&S*AREG8-K109       HiL co-processor         Open standard protocol support       open simulation interface (OSI)         User interface and remote controls       yes         Remote control interfaces       Ethernet         Remote control command set       S*AREG8-K986       GPIB         Remote control command set       SCPI         General data       State unit       462 mm × 240 mm × 504 mm (18.15 in × 9.44 in × 19.81 in) 5 HU, 19" width	Amplitude flatness	R&S®QAT100 standalone	$< \pm 5$ dB in 4 GHz bandwidth (meas.)
EIRP measurementsH&S*AREG8-K740IF outputs available on base unitIF input port for superimposing interferersR&S*AREG8-K741IF inputs available on base unitHardware-in-the-loop (HiL) interfaceR&S*AREG8-K741IF inputs available on base unitDedicated HiL interfaceR&S*AREG8-K109HiL co-processorOpen standard protocol supportopen simulation interface (OSI)User interface and remote controlsyesGraphical user interfaces with touch controlsyesRemote control interfacesEthernetRemote control command setSCPIGeneral dataSCPIDimensions (W × H × D)base unitbase unit462 mm × 240 mm × 504 mm (18.15 in × 9.44 in × 19.81 in) 5 HU, 19" width	IF input/IF output interface		
Hardware-in-the-loop (HiL) interfaceDedicated HiL interfaceR&S®AREG8-K109HiL co-processorOpen standard protocol supportopen simulation interface (OSI)User interface and remote controlsyesGraphical user interface with touch controlsyesRemote control interfacesEthernetRemote control command setSCPIGeneral data462 mm × 240 mm × 504 mm (18.15 in × 9.44 in × 19.81 in) 5 HU, 19" width	IF output port for radar signal analysis and EIRP measurements	R&S®AREG8-K740	IF outputs available on base unit
Dedicated HiL interfaceR&S*AREG8-K109HiL co-processorOpen standard protocol supportopen simulation interface (OSI)User interface and remote controlsGraphical user interface with touch controlsyesRemote control interfacesEthernetRemote control command setSCPIGeneral dataDimensions (W × H × D)base unitMarked S462 mm × 240 mm × 504 mm (18.15 in × 9.44 in × 19.81 in) 5 HU, 19" width	IF input port for superimposing interferers	R&S®AREG8-K741	IF inputs available on base unit
Open standard protocol supportopen simulation interface (OSI)User interface and remote controlsvesGraphical user interface with touch controlsyesRemote control interfacesEthernetRemote control command setGPIBRemote control command setSCPIGeneral dataDimensions (W × H × D)base unitdata462 mm × 240 mm × 504 mm (18.15 in × 9.44 in × 19.81 in) 5 HU, 19" width	Hardware-in-the-loop (HiL) interface		
User interface and remote controls       yes         Graphical user interface with touch controls       Ethernet         Remote control interfaces       Ethernet         Remote control command set       SCPI         General data       ScPI         Dimensions (W × H × D)       base unit       462 mm × 240 mm × 504 mm (18.15 in × 9.44 in × 19.81 in) 5 HU, 19" width	Dedicated HiL interface	R&S®AREG8-K109	HiL co-processor
Graphical user interface with touch controls       yes         Remote control interfaces       Ethernet         R&S*AREG8-K986       GPIB         Remote control command set       SCPI         General data       462 mm × 240 mm × 504 mm (18.15 in × 9.44 in × 19.81 in) 5 HU, 19" width	Open standard protocol support		open simulation interface (OSI)
Remote control interfaces     Ethernet       R&S*AREG8-K986     GPIB       Remote control command set     SCPI       General data     462 mm × 240 mm × 504 mm (18.15 in × 9.44 in × 19.81 in) 5 HU, 19" width	User interface and remote controls		
R&S®AREG8-K986     GPIB       Remote control command set     SCPI       General data     462 mm × 240 mm × 504 mm (18.15 in × 9.44 in × 19.81 in) 5 HU, 19" width	Graphical user interface with touch controls		yes
Remote control command set     SCPI       General data     462 mm × 240 mm × 504 mm       Dimensions (W × H × D)     base unit     462 mm × 240 mm × 504 mm       5 HU, 19" width     5 HU, 19" width	Remote control interfaces		Ethernet
General data         462 mm × 240 mm × 504 mm           Dimensions (W × H × D)         base unit         (18.15 in × 9.44 in × 19.81 in)           5 HU, 19" width         5 HU, 19" width		R&S®AREG8-K986	GPIB
Dimensions (W × H × D)         base unit         462 mm × 240 mm × 504 mm           5 HU, 19" width	Remote control command set		SCPI
Dimensions (W × H × D)         base unit         (18.15 in × 9.44 in × 19.81 in)         5 HU, 19" width	General data		
Weight base unit (depends on options) 15 kg to 26 kg (33.07 lb to 57.32 lb)	Dimensions (W $\times$ H $\times$ D)	base unit	(18.15 in × 9.44 in × 19.81 in)
	Weight	base unit (depends on options)	15 kg to 26 kg (33.07 lb to 57.32 lb)

# **ORDERING INFORMATION**

R&S®AREG8-Bxxx = hardware option; R&S®AREG-Kxxx = software/keycode option

Designation	Туре	Order No.
Base unit		
Automotive radar echo generator,	AREG800A	1437.4400.02
including power cable, quick start guide		
Hardware options		
Baseband		
Digital baseband with 1 GHz IF bandwidth, 1 IF path and 1 individual artificial object	R&S®AREG8-B9	1437.8011.02
Analog stepped delay line, for short object generation with 1 IF path and 1 individual artificial object $% \left( 1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,$	R&S®AREG8-B63	1437.8205.02
Software options		
Bandwidth upgrade		
Baseband extension from 1 GHz to 2 GHz IF bandwidth, for 1 IF path	R&S®AREG8-K527	1437.9882.02
Baseband extension from 2 GHz to 5 GHz IF bandwidth, for 1 IF path	R&S®AREG8-K528	1437.9799.02
Baseband enhancements		
Activation of second IF path for one AREG8-B9 baseband with 1 GHz bandwidth and 1 individual object	R&S®AREG8-K570	1437.9899.02
One additional artificial object, for all IF paths	R&S®AREG8-K812	1437.9853.02
Extended Doppler frequency shift up to 10 MHz	R&S®AREG8-K813	1437.9901.02
Near object range for FMCW	R&S®AREG8-K814	1437.9776.02
Intermediate frequency ports and control interfaces		
Analog IF output interfaces	R&S®AREG8-K740	1437.9830.02
Analog IF input interface	R&S®AREG8-K741	1437.9847.02
Hardware-in-the-loop control interface	R&S®AREG8-K109	1437.9860.02
Synchronization interface, for multiple AREG800A generators	R&S®AREG8-K549	1437.9876.02
Remote control GPIB	R&S®AREG8-K986	1437.9818.02
System alignment backend		
System alignment	R&S®AREG8-B97	1437.9001.02
Production base units		
R&S®AREG-P1 radar mini	R&S®AREG-DBP1	1437.9676P02
R&S®AREG-P2 radar golden	R&S®AREG-DBP2	1437.9682P02
R&S®AREG-P3 radar pro	R&S®AREG-DBP3	1437.9699P02
Rackmount kit backend		
Rackmount kit backend	R&S <sup>®</sup> ZZA-KNP51	1177.8855.00
Remote frontends		
mmWave remote frontends		
24 GHz to 24.25 GHz, single antenna, 250 MHz RF bandwidth	R&S®AREG8-24S	1437.8611K02
24 GHz to 24.25 GHz, two antennas, 250 MHz RF bandwidth	R&S®AREG8-24D	1437.8640K02
76 GHz to 81 GHz, single antenna, 4 GHz RF bandwidth	R&S®AREG8-81S	1437.8734K02
System alignment, for R&S®AREG8-81S	R&S®AR81S-B97	1437.9053.02
76 GHz to 81 GHz, two antennas, 4 GHz RF bandwidth	R&S®AREG8-81D	1437.8763K02
System alignment, for R&S®AREG8-81D	R&S®AR81D-B97	1437.9060.02
76 GHz to 81 GHz, single antenna, 5 GHz RF bandwidth	R&S®AREG8-81WS	1437.9153K02
System alignment, for R&S®AREG8-81WS	R&S®AR81WS-B97	1437.9247.02
76 GHz to 81 GHz, two antennas, 5 GHz RF bandwidth	R&S®AREG8-81WD	1437.9160K02
System alignment, for R&S®AREG8-81WD	R&S®AR81WD-B97	1437.9230.02
24 GHz to 44 GHz, single antenna, 1 GHz RF bandwidth	R&S <sup>®</sup> FE44S	1338.7001K02
Frontend control, for R&S <sup>®</sup> FE44S	R&S®AREG8-K553	1437.9782.02
R&S®OAT100 advanced antenna array		
Advanced antenna array, from 76 GHz to 81 GHz	R&S®QAT100	1341.0004.02
Second line of 96 transmit antennas, for the R&S®QAT100	R&S®QAT-B2	1341.0162.02
Shielding system, for one R&S®QAT100, length: 50 cm	R&S®QAT-Z50	1341.0156.02
Production frontends		
Monostatic frontend production	R&S®AREG-MFP	1437.9701P02
Bistatic frontend production	R&S®AREG-BFP	1437.9718P02

Warranty		
Base unit and all frontends (mmWave remote frontends and R&S®QAT100)		3 years
All other items <sup>1)</sup>		1 year
Service options		
Extended warranty, one year	R&S®WE1	
Extended warranty, two years	R&S®WE2	
Extended warranty with calibration coverage, one year	R&S <sup>®</sup> CW1	Contact your local Rohde&Schwarz
Extended warranty with calibration coverage, two years	R&S°CW2	sales office.
Extended warranty with accredited calibration coverage, one year	R&S®AW1	
Extended warranty with accredited calibration coverage, two years	R&S®AW2	

<sup>1)</sup> For options installed, the remaining base unit warranty applies if longer than 1 year. Exception: all batteries have a 1 year warranty.

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