Antennen für fliegende Netzknoten

Matthias Geissler & Team



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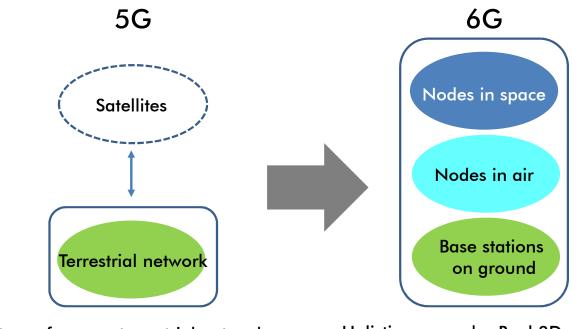
- The 3D network
- Flying network nodes
- Requirements for antennas
- Example: SANTANA IV
- Summary



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Whats new about the 3D network?



- Strong focus on terrestrial network
- Possibility of satellite integration
- Holistic approach: ,Real 3D network'
- Network architecture optimized for flying nodes



Potential of 3D networks

Intended functionality

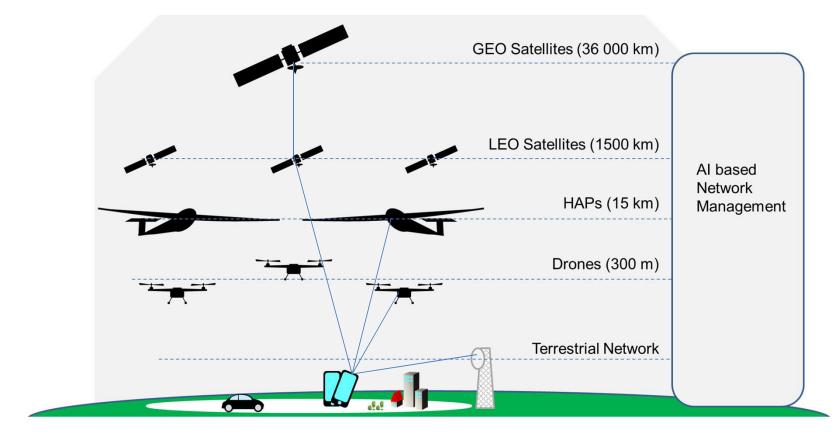
- ,Equal importance' of terrestrial base stations and flying nodes
- Automatic routing through the network based on availability, data rate, latency requirements, costs
- Seamless handover between nodes, terrestrial or flying

Potential

- Terrestrial network only needs to cover the basic capacity
- Peak capacity can be supported by flying nodes
- Fast recovery of network in case of desaster (e.g. Ahrtal)
- Filling of gaps in the network at low cost
- Basic coverage of rural areas at low cost
- Basic coverage of the **oceans**



The 6G vision





6G-TakeOff: Holistic 3D Communication Networks for 6G

Project idea: Combine terrestrial, air-borne and space-borne processing platforms in a holistic manner as infrastructure for communication network elements Bayerisches Rotes Kreuz Telefónica **Ontinental** JOHN DEERE **Consortium Partners:** SMART DSI Aerospace Technology AIRBUS **OTARIS** MOBILE ZENTRUM FÜR TELEMATIK E.V. TO UNIVERSITÄT TELEMATIK E.V. TO UNIVERSITÄT TELEMATIK E.V. TO UNIVERSITÄT TELEMATIK E.V. TO UNIVERSITÄT **Project coordinator:** Deutsche Telekom **Contact person:** Markus Breitbach Start | Duration: 2022/08/01 | 3 years Supported by: Volume: Federal Ministry of Education approx. 1000 person months / 13 mn € and Research 38% SME, 31.7% industry, 30.3% research institutes and universities



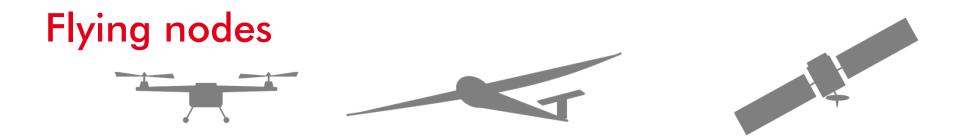
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of Education

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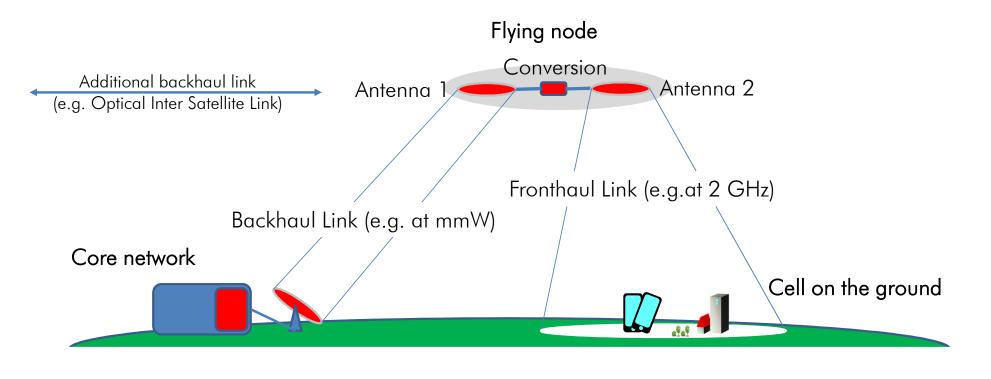




- GEO satellite: Satellite in geostationary orbit with defined (maybe reconfigurable) footprint on the earth surface
- MEO or LEO satellite: Satellite in low or medium orbit, relative movement vs ground, constellation needed
- HAPS: High Altitude Plattform Station e.g. stratospheric glider
- LAPS: Low Altitude Plattform Station, e.g. small drone or copter
 - > Nodes are very different in type and in potential application in the network!

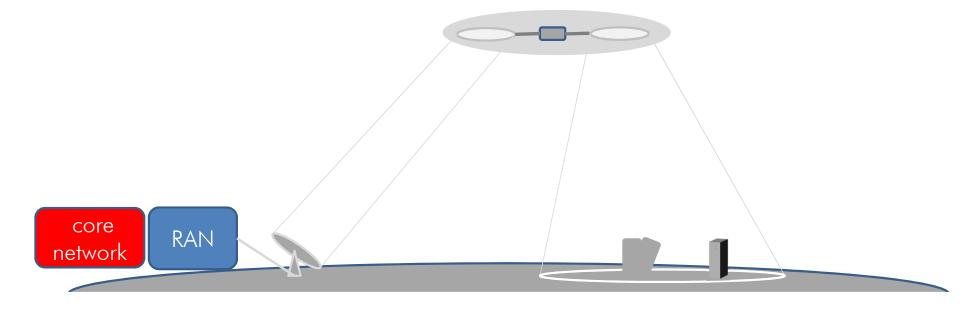


Linking the flying node to the network





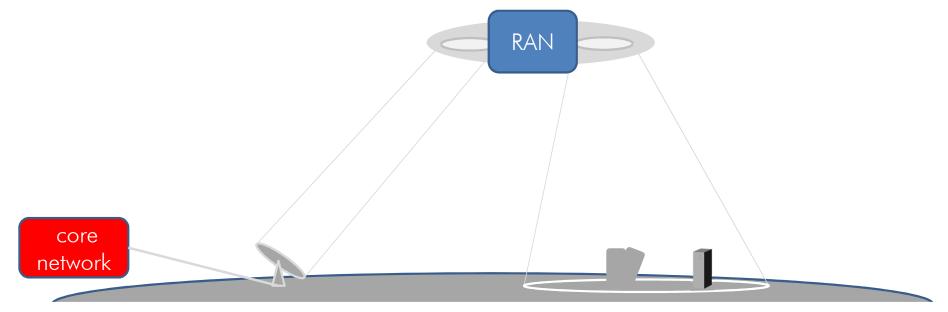
Extreme setup 1: Fully transparent link



- Base station is on the ground
- Flying node acts as repeater only
- Advantages: Central control and configuration in core network, Payload ist more simple, lower energy consumption
- Disadvanteges: High gross data rate required, very high latency requirements



Extreme setup 2: Flying base station



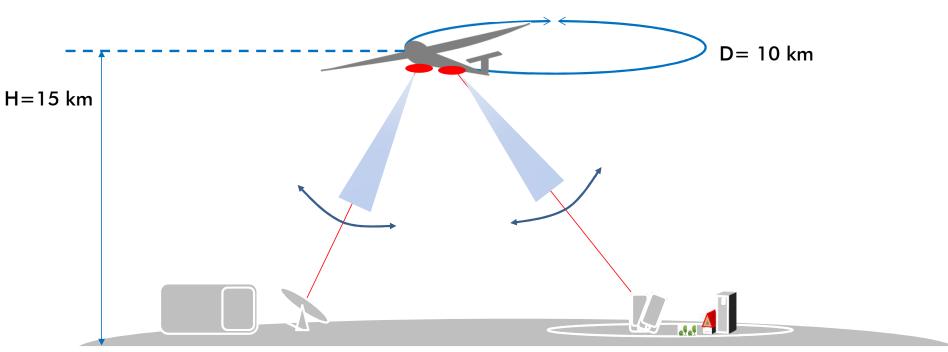
- Fully functional base station on the flying node
- Advantages: Backhaul link optimized for data transfer only, lower (net) data rate, specific protocol can be used
- Disadvantages: More complex functionality on the node, more power consumption

> Level of node transparency depends on network architecture: central vs distributed control



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Reliable and robust beam tracking

- Stratospheric glider in continuos circular movement above ground
- Both beams, backhaul and fronthaul beam, need to continuosly move to maintain the link
- Mechanical steering platform would suffer extremely
- Electronical steering allows for higher MTBF



Antenna size differs with node type

- LAPS vs HAPS: Very different requirements in terms of link budget, antenna weight and size
- Solution : Modular approach

Antenna module (e.g. 4 x 4 or 8 x 8 elements)

Antenna for LAPS

Antenna for HAPS

Modular approach

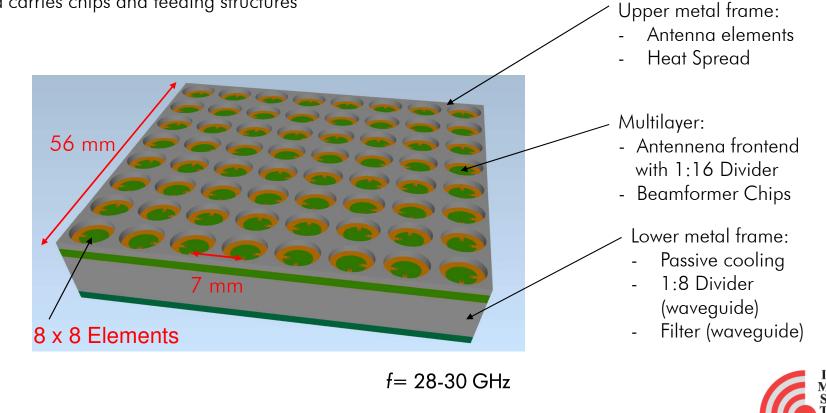
- Re-use of modules for several applications
- Higher production quantity for modules
- Fast prototyping for new applications

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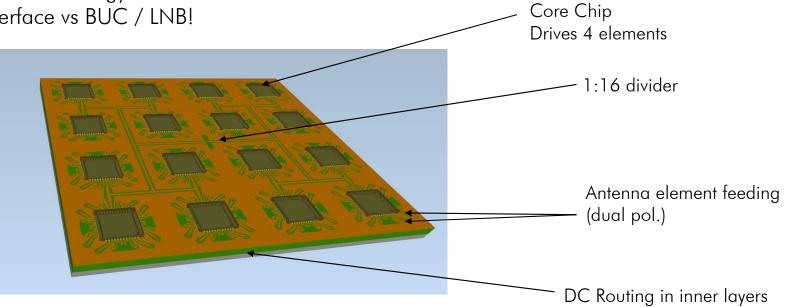
Module: Top view

- Small Horn-Antennas fed by circular polarization
- Separate apertures for Tx und Rx
- Multilayer-Board carries chips and feeding structures



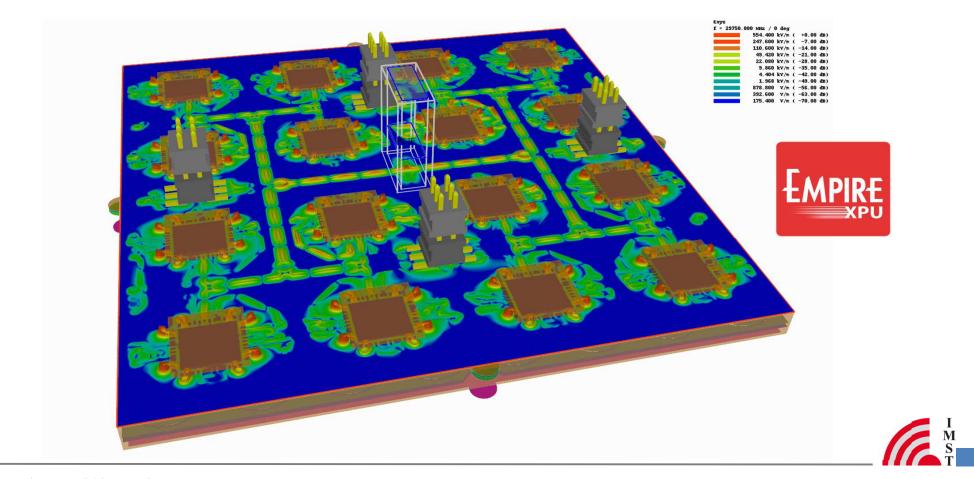
Module: Bottom View

- New generation of beamformer chips: One chip drives 4 elements times 2 polarisations •
- Any polarisation type possible ٠
- Board in standard technology ٠
- Only one RF interface vs BUC / LNB!





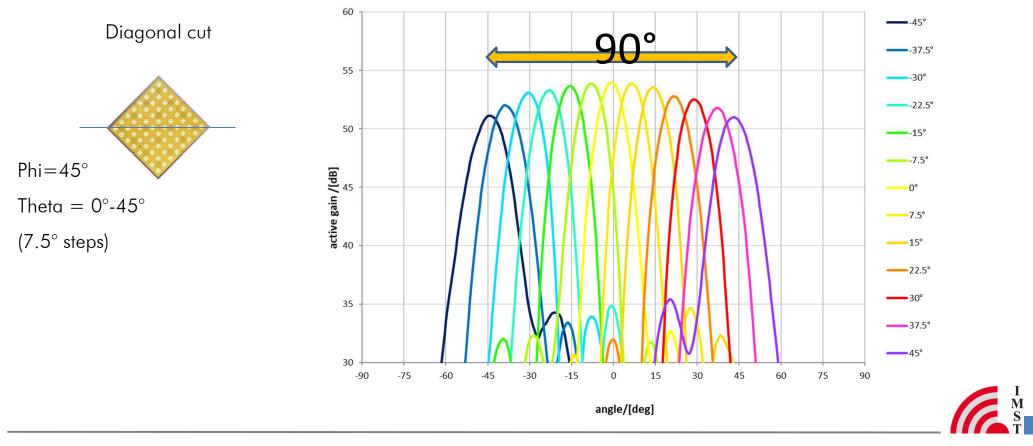
Frontend – Simulation: bottom view



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Measurements: Active Gain in farfield



SANTANA IV*: Phased array for aeronautic applications

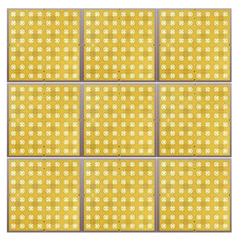
Single Module:

- 8 x 8 Elements
- Antenna Module Directivity: ca. 25dBi

Module can be combined to built large, powerful arrays

- Directivity scales with number of elements
- Output power also scales with number of elements
- Each doubling of array size increases EIRP by 6 dB!



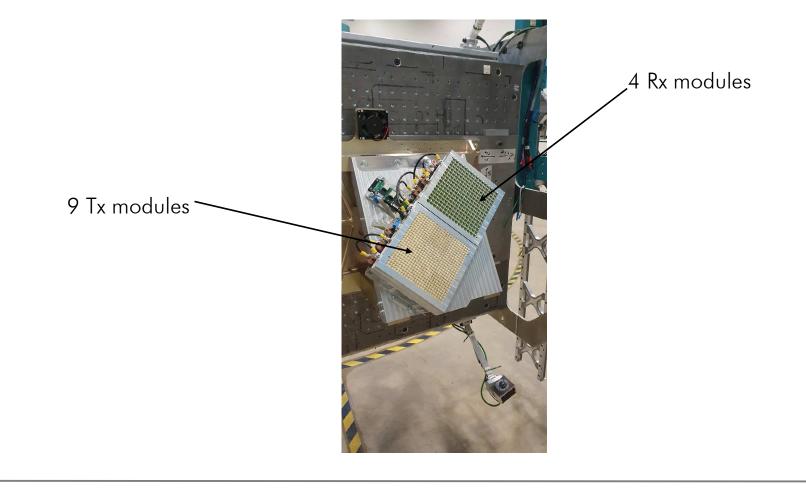




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*Funded by DLR Space administration, Bonn, Germany, FKZ 50RK1925

Fully assembled Rx/Tx-Array for test in flight





SANTANA flight test

In-flight Testing of a satcom link to a geostationary satellite: successful!



IMST experts at DLR Airport Braunschweig, Germany



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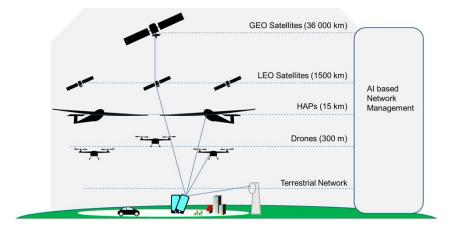


Summary

- **6G**: holistic network approach, real 3D network
- Equal importance of terrestrial and flying network nodes
- Demanding requirements on antennas:
 - High beam agility, continuos beam movement
 - Robust design
 - Size and weight adaptable to node capability

• Antenna solution

- Eletcronical beamsteering is well suited in terms of functionality and lifetime
- Modular approach allows easy adaptation
- Good candidate: SANTANA IV antenna
 - 8 x 8 antenna module using horn radiators and beamformer chips
 - Very good performance, standard production technologies
 - Antenna already successfully tested in flight







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