

# Automotive Ethernet 1000Base-T1 TC9 measurement using VNA Application Note

## Products:

- R&S®ZNB4
- R&S®ZN-Z51
- R&S®ZV-Z135
- R&S®ZV-Z192

This application note is a systematic guide to help test engineers configure the Vector Network Analyzer in order to perform compliance test on Automotive Ethernet cables according to the Open Alliance TC9 standard.

## Note:

Please find the most up-to-date document on our homepage

<https://www.rohde-schwarz.com/appnote/GFM323>

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# 1 Introduction

The evolution towards higher connectivity & electrification in the automotive industry is faster than ever before. More and more sensors are added to vehicles as the future of transportation moves towards higher level of automation. Reliability and quality of time critical communications between different systems are nowadays under the spotlight, and Ethernet cables have become the industry standard to support the network within the car.

The [Open Alliance TC9 compliance specification](#) is regarded as a qualification benchmark for unshielded twisted pair (UTP) cables for Automotive Ethernet [1].

This document contain electrical requirements and measurement specifications on 1000BASE-T1 channel and components link segment type A (UTP). It shall be used as a standardized common scale for the evaluation of the RF properties for physical layer communication channels to enable 1000BASE-T1 technology.

The focus of this application note is to describe the method of performing compliance tests according to the TC9 specification for Ethernet cable testing. Chapter 2 describes the test setup required to perform measurements on 1000BASE-T1 coaxial cables using the four-port ZNB4 Vector Network Analyzer (VNA) from Rohde & Schwarz. Chapter 3 explains the procedure of calibrating the VNA and checking the VNA calibration accuracy. Finally, in chapter 4, measurement examples from the Open Alliance TC9 compliance specification are shown.

## Abbreviations

The following abbreviations are used in this application note for Rohde & Schwarz products:

- The R&S®ZNB4 Vector Network Analyzer is referred to as ZNB
- The R&S®ZN-Z51 Automatic Calibration Unit is referred to as ZN-Z51
- The R&S®ZV-Z135 Calibration Kit is referred to as ZV-Z135
- Device Under Test is referred to as DUT

## 2 Test Setup

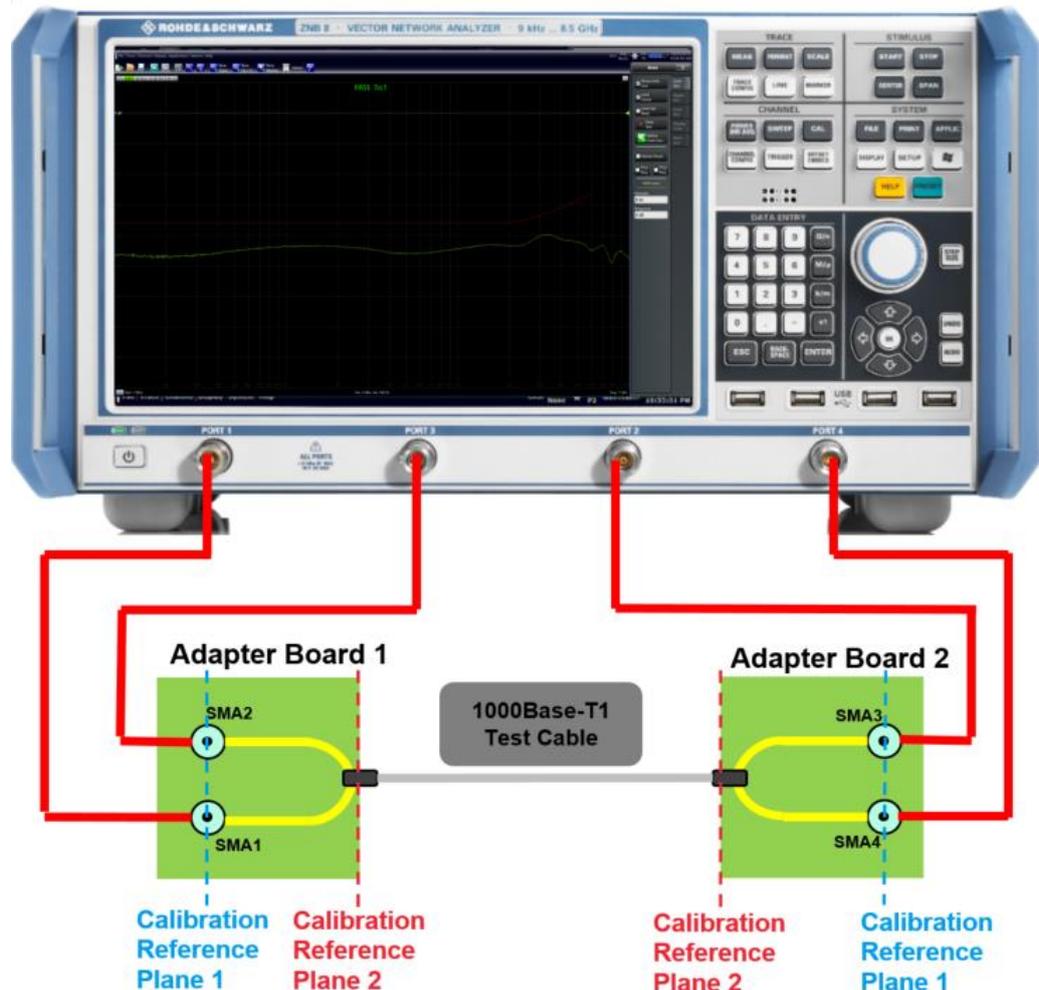


Fig. 2-1: Test setup for performing TC9 measurement

Fig. 2-1 shows the measurement setup required to test 1000Base-T1 Automotive Ethernet cables. The Ethernet cables are unshielded coaxial twisted pair cables and in order to perform measurements, a PCB based measurement fixture (adapter board) is used to adapt to the connectors of the Rohde & Schwarz ZNB4 Vector Network Analyzer to the test cables.

To start a measurement, the test setup needs to be calibrated. A full 4-port system error correction would ensure calibration up to the reference planes 1. A measurement between these two planes (marked in blue in Fig. 2-1) would include an undesired RF response of the adapter boards. The compensation of this effect is optional according to the Open Alliance specification. This application note shows a method to "de-embed" the adapter boards, in order to obtain a reference plane calibrated at the Ethernet cable ends (marked in red in Fig. 2-1).

The VNA configuration and measurement parameters are documented in the Open Alliance TC9 specification, while a systematic guide on how to calibrate and configure the ZNB4 is described in the next chapters of this document.

## 3 Calibrating and Configuring the VNA for Measurement

The first step of any test performed with a VNA consists in calibrating the instrument. As a measure of good practice, let the VNA and the calibration unit warm up about one hour to gain stable characterization data. To obtain the required VNA calibration accuracy a manual calibration is usually performed but automatic calibration units can be used with the method described in the next paragraph as well. If a manual calibration is preferred, you can ignore paragraph 3.1.

The VNA needs to be configured to the settings defined in table: 4.2-2 of the Open Alliance TC9 test specification [1].

### 3.1 Characterization of the Calibration Unit

In order to obtain optimal calibration accuracy with an automatic calibration unit (e.g. ZN-Z51) the generation of specific characterization data of the unit is recommended. In order to do this, the user needs perform a calibration with a manual calibration kit (e.g. ZV-Z135) first. This will ensure a full system error corrected VNA and enable precise characterization of the calibration unit. Use the setting from [1] table 4.2-2. Fig. 3-1 shows the port connections of ZNB4 with the automatic calibration unit ZN-Z51.

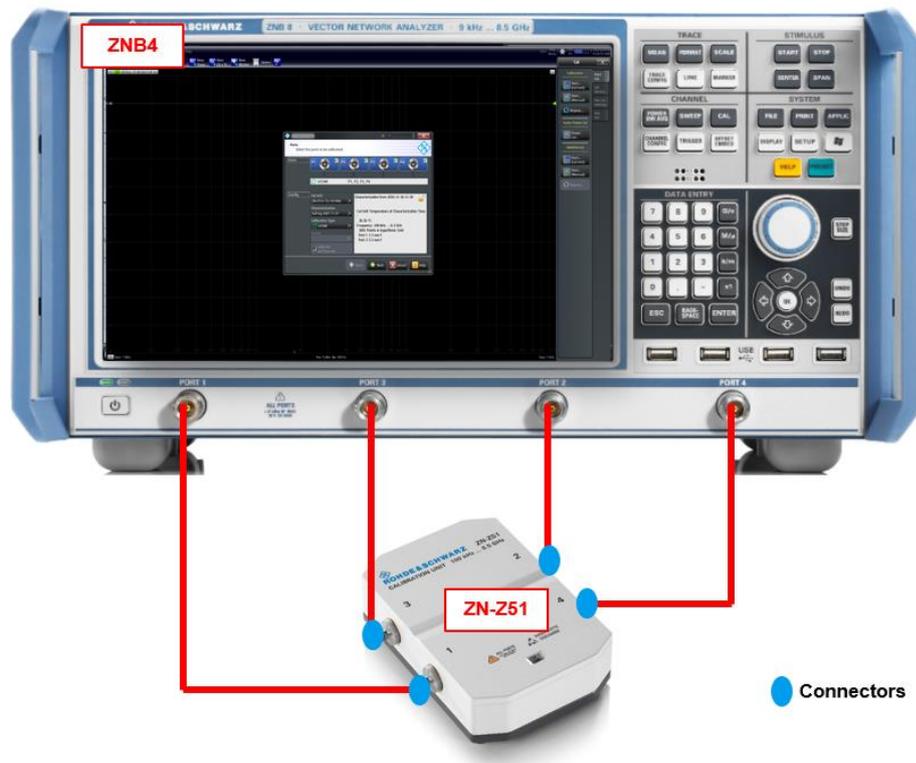
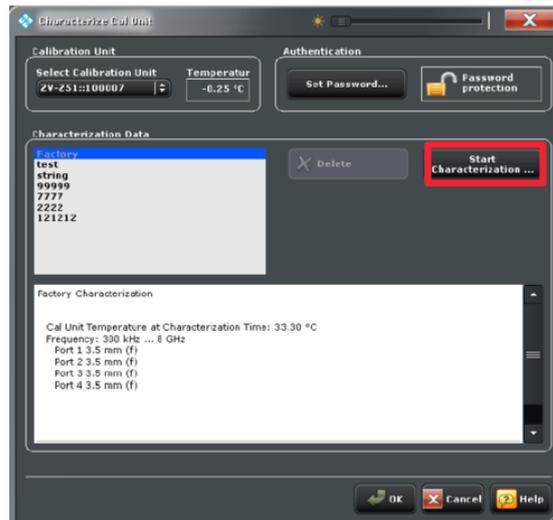


Fig. 3-1: Setup for a Full 4-Port automatic system error calibration of the ZNB4 using ZN-Z51

Then start the characterization step by disconnecting the manual calibration kit and connecting the automatic one as shown in Fig. 3-1

- To start the characterization step, press
  - CHANNEL > Calibration > Cal Devices > Characterize Cal Unit
  - Select *Start Characterization as shown in Fig. 3-2*



**Fig. 3-2: Calibration unit Characterization configuration**

A list of all the saved characterization datasets can be found on the left of the window as shown above

- Press *Test Port Assignment > Automatic*
- Select *Take all OSM and Through*
- Save the characterization data file on the unit
  - In this example, the name "full log 2001 11.37" was used
- Afterwards, the ZN-Z51 can be used for future calibrations as follows:
  - Use the same settings as described in the standard
  - Select Channel > Cal > Start (Cal Unit)
  - Select all 4 ports P1, P2, P3 and P4 as shown in Fig. 3-3
  - Use the characterization data generated and saved before (in this example "full log 2001 11.37")
  - Select Next and follow the instructions on the screen



Fig. 3-3: Configuration for calibrating all four ports of the ZNB4

At this point, the instrument is calibrated up to the calibration reference plane 1 in Fig. 3-4. This step needs to be done only once for a calibration unit. For every new calibration from this point onwards, the same characterization data can be used.

### 3.2 Optional de-embedding of fixture boards

When the adapter boards are connected to the ZNB, the influence of the two microstrip lines up to calibration reference plane 2 can be eliminated, to obtain a measurement of the Ethernet cable only.

In order to do that, connect the adapter board to the ZNB4 as shown in Fig. 3-4

- Connect P1 and P3 to adapter board 1
- Connect P2 and P4 to adapter board 2

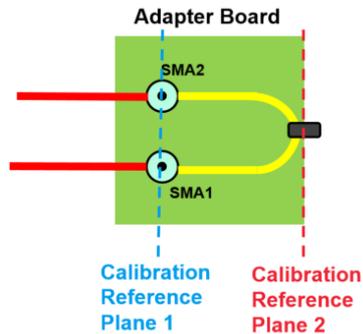


Fig. 3-4: Different calibration planes on the adapter board

To compensate for the influence of the fixture on the measurement result, the de-embedding functionality of the ZNB can be used. The de-embedding is done in balanced mode.

- Select Measurement > Balanced Ports > (D) 2 x Balanced
- Trace > Measurement > Sdc11
- Trace Config > Add Trace
- Trace > Measurement > Sdc22
- Offset Embed > Offset > Fixture Compensation...
- Select all four ports
- Choose Offset correction: "Direct Compensation"
- Press Measurement Type: "Open"
- Press "Take" and close the dialog once the process ended

"Direct Compensation" provides a frequency-dependent transmission factor. "Auto Length and Loss" uses a global electrical length and loss, so compensation is based on a transmission line model.

Depending on the fixture itself, additional measures can be taken to improve the compensation result. See the R&S® ZNB/ZNBT Vector Network Analyzer User Manual for further information on the compensation approaches of the ZNB.

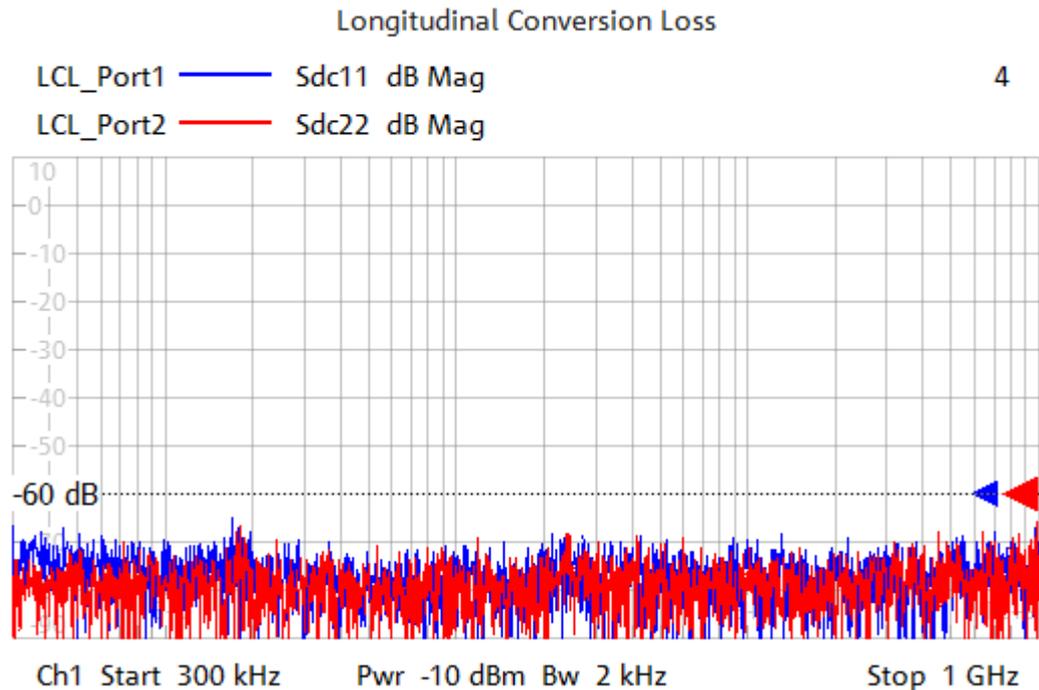


Fig. 3-5: Mode Conversion Sdc11 and Sdc22 with open fixture after Fixture Compensation with "Direct Compensation"

The microstrip lines on the adapter boards are now compensated and Fig. 3-5 shows the conversion loss values after the process. The calibration is now shifted up to calibration reference plane 2.

### 3.3 Verification of VNA Calibration Accuracy

After the calibration procedure, the ZNB4 needs to be configured to balanced port testing mode. The ZNB4 port P1 and port P3 are configured as logical port L1 and port P2 and port P4 are configured as logical port L2.

- Click Trace > Measure > Balanced Ports
- Select the configuration as shown in Fig. 3-6
- Choose reference impedance and change common mode impedance to 200Ohm as indicated in the Open Alliance specification, then hit ok

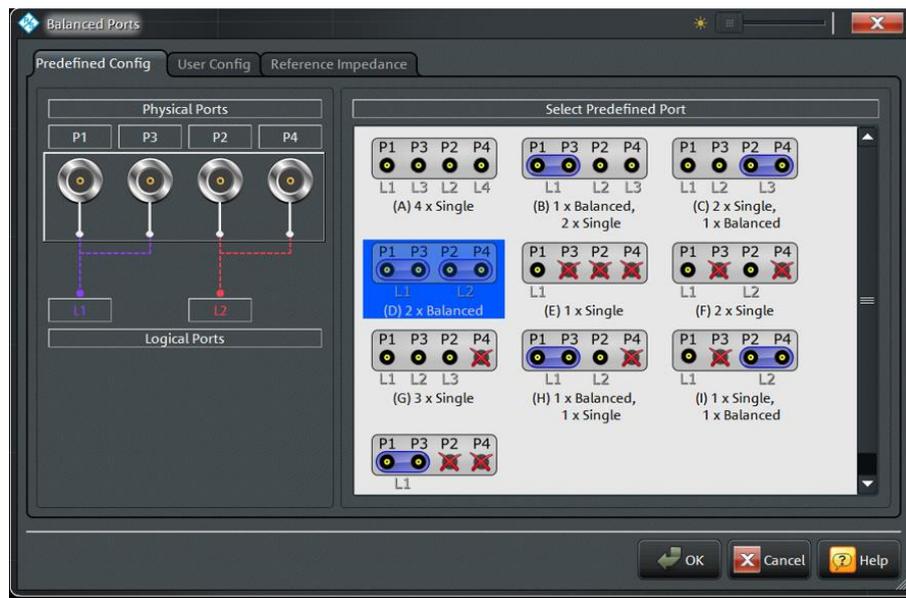


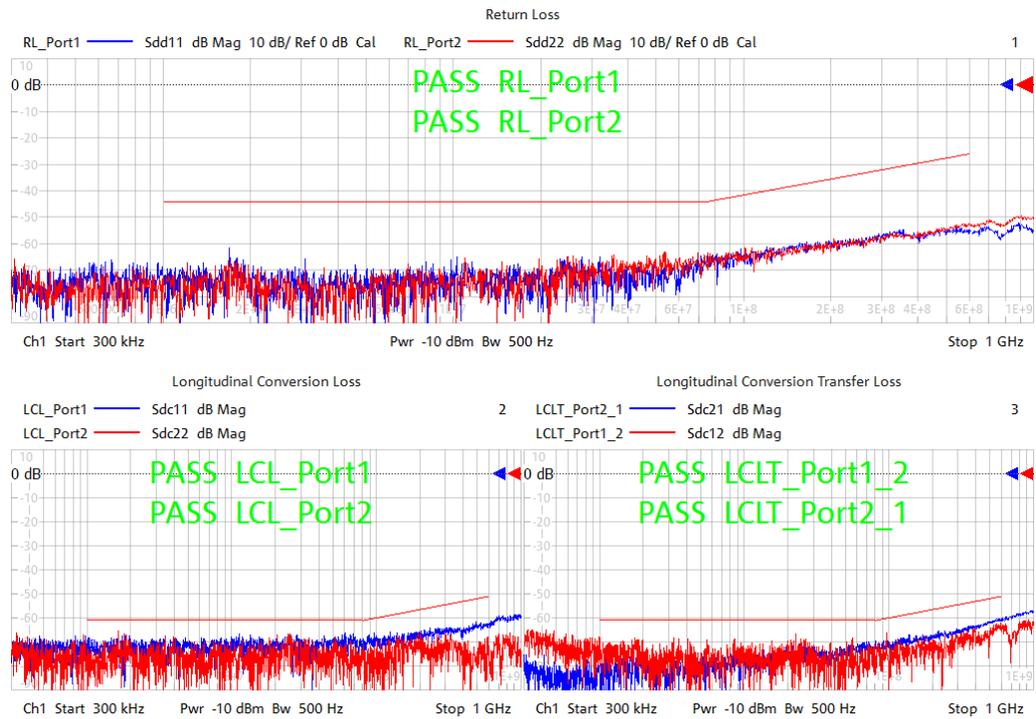
Fig. 3-6: Balanced port configuration for the ZNB4

Now the VNA calculates the mixed-mode S-parameters from the measured single-ended S-parameters and shows them in the diagram areas.

At this point, a verification step needs to be performed to check the calibration accuracy of the VNA. The verification of VNA calibration accuracy is performed with two "THRU" connectors as per Open Alliance specification.

Fig. 3-7 shows the calibration accuracy verification of the ZNB4 for return loss, longitudinal conversion loss and longitudinal conversion transfer loss. All values are within the limits defined in the specification.

The option ZNB4-B54 "Extended Dynamic Range" improves the dynamic range of the instrument by circa 10 dB. The VNA accuracy verification test will show 5 dB lower conversion loss in this case. The result shown in Fig. 3-7 is measured without this option.



**Fig. 3-7: Verification of calibration accuracy of return loss, longitudinal conversion loss and longitudinal conversion transfer loss**

## 4 Measurement and Results

As an example of measurement, the return loss and insertion loss of an Ethernet cable are taken into consideration. The measurement of CIDM (Characteristic Impedance Differential Mode) is also explained in the following paragraphs. The fixtures used in the following example meet the requirements of [1].

### 4.1 Measurement of Mixed-Mode S-Parameters

If all the steps in the previous chapters have been correctly performed, the setup is fully calibrated and configured to measure as described in Open Alliance specifications.

First, connect the Cable Under Test (CUT) as shown in Fig. 2-1.

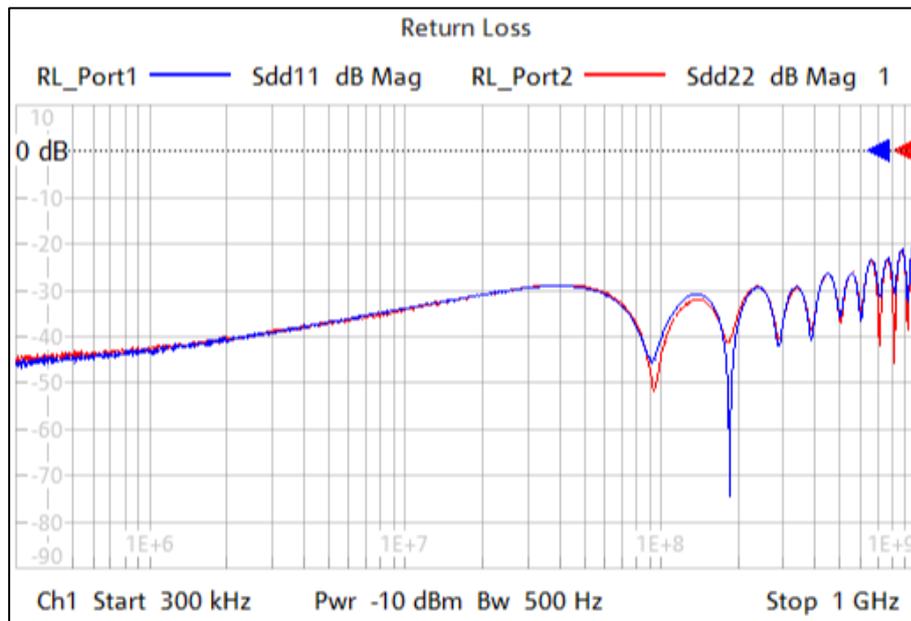


Fig. 4-1: Return loss measurement of 1000BASE-T1 according to TC9 spec

In order to measure return loss or insertion loss,

- Select the corresponding S-parameter from Trace > Measurement > S-parameter

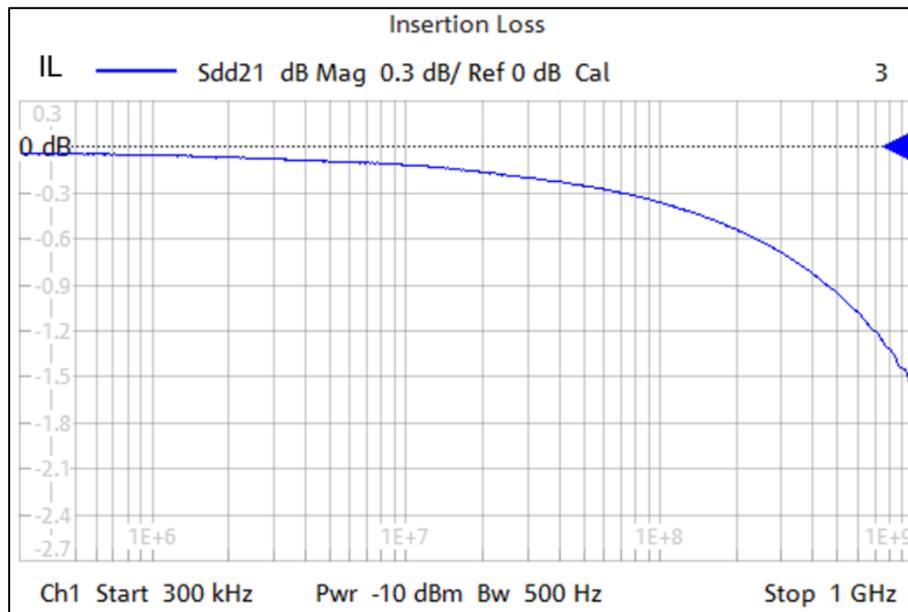


Fig. 4-2: Insertion loss measurement of a 1000BASE-T1 Automotive Ethernet cable

Fig. 4-1 and Fig. 4-2 show the return loss and insertion loss measurement of a 1000BASE-T1 Automotive Ethernet cable using the ZNB4.

## 4.2 Measurement of TDR based CIDM (Characteristic Impedance Differential Mode)

To carry out impedance measurements, the recommended VNA configuration according to [1] is different than the one used for the S-parameter measurements. One reason is that a linear frequency sweep is needed for converting the measurement result from frequency domain into time domain with the Inverse Fourier Transform, while for the S-parameter measurement described above, a logarithmic sweep is used. Additionally, a higher stop frequency is advantageous for a higher resolution (shorter rise time) in the TDR.

A second measurement channel can be calibrated and used to see TDR results on the VNA screen in parallel to the S-parameters. The second channel (Ch2) can be configured with different settings.

To do this

- Select Channel > Channel Config > Add Ch+Tr+Diag
  - Ch2 is now indicated in the lower left corner of the diagram area
  - Configure the VNA according to the specification of [1]
  - Perform calibration (if an automatic cal unit is used, use "factory" from the characterization pool)

The two channels will run sequentially.

While using the active trace in Ch2 set up an impedance trace in time domain to perform the CIDM measurement by

- Meas > Z←Sdd11, choose Sdd11 from the drop down menu
- Trace > Trace Config > Time Domain and check box "Time Domain"

- Choose Type "low pass step" from the drop down menu
- Press "Low Pass Settings..." and check box DC Value "Continuous extrapolation"
- Stimulus > Stop to adapt the stop time to the DUT. Electrically long DUTs need a longer analysis time

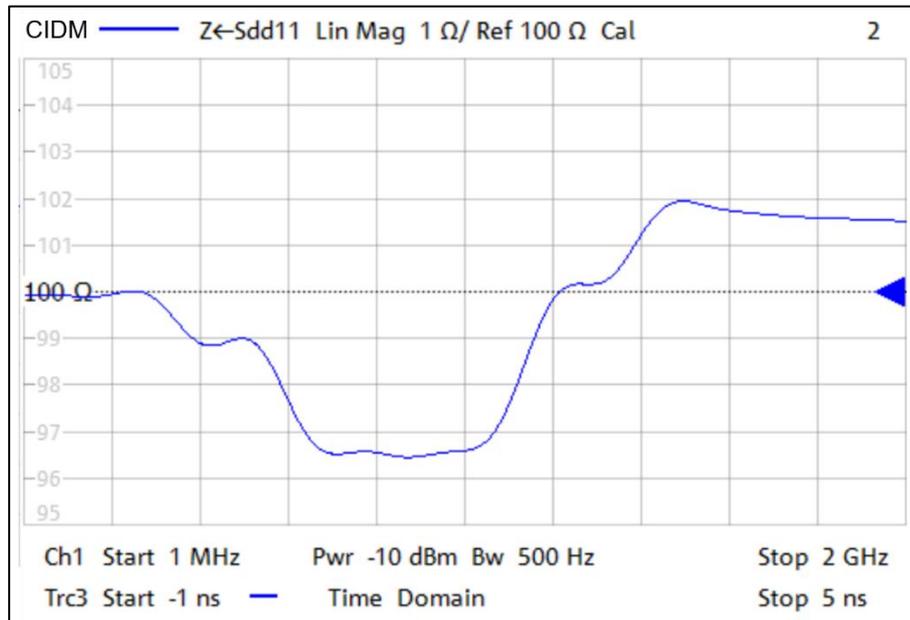


Fig. 4-3: Typical CIDM measurement based on time domain measurement of an automotive Ethernet cable

In Fig. 4-3, a typical result of the impedance measurement of an automotive Ethernet cable is shown. The differential reference impedance of 100 Ω is seen up to 0 ns. Then a segment with around 99 Ω corresponds to the left fixture. The cable impedance of around 96.5 Ω can be seen in the section between 2.5 ns to 3 ns followed by the right fixture with an impedance of about 100Ω.

## 5 Reference

[1] Link Segment Type A (UTP) 1000BASE-T1 Ethernet Channel and Components Specification - TC9, Open Alliance, Weblink: <http://www.opensig.org/tech-committees/tc9/>

## 6 Ordering Information

Designation	Type	Order No.
Vector Network Analyzer, Four Ports, 4.5 GHz, N	R&S@ZNB4	1311.6010K24
Extended Dynamic Range for Four-Port R&S@ZNB4	R&SZNB4-B54	1319.4981.02
Time Domain Analysis	R&S@ZNB-K2	1316.0156.02
RF Cable 50 Ohm, N(m) to 3.5mm(m), DC-18 GHz, 610mm	R&S@ZV-Z192	1306.4513.24
Calibration Kit (up to 15 GHz, 3.5 mm female)	R&S@ZV-Z135	1317.7677.03
Calibration Unit (Four ports, 100 kHz to 8.5 GHz, 3.5mm female)	R&S@ZN-Z51	1319.5507.34

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## Sustainable product design

- Environmental compatibility and eco-footprint
- Energy efficiency and low emissions
- Longevity and optimized total cost of ownership



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