

Application Note

# MILLIMETER WAVE MEASUREMENTS

with Vector Network Analyzer ZNA and Option K8

## Products:

- ▶ R&S®ZNA<xx>
- ▶ R&S®ZC<xxx>

J. Simon | 1EP201\_0e | Version 2e | 03.2026

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# 1 Overview

RF engineers are increasingly confronted with the task of characterizing devices operating in the mmWave range. The vector network analyzer (VNA) R&S ZNA, along with R&S or RPG ZC<xxx> mmWave converters, provides a broad range of measurement solutions fulfilling this task. This application note is intended to provide help for choosing the right measuring instruments and accessories, interconnecting them correctly, setting up the instruments, calibrating them and finally obtaining measurement results.

Both linear and nonlinear measurement quantities are covered. In both categories, one further distinguishes between devices that do not change the frequency of the input signal (e.g. transmission lines, attenuators, amplifiers) and those that do (e.g. mixers, frequency multipliers). Generally, the complexity of setup and calibration is higher in the latter case.

The ZNA user interface is designed to assist the user with defining the wanted measurement quantities and their associated parameters like source power, LO frequency, and tone distance for two-tone measurements. It shows the needed setup schematically and proposes how to calibrate this setup including all necessary steps. Many common pitfalls lurking when calibration is completely done manually are avoided by automatic compilation of the calibration.

Following this concept, the chapters of this application note first give a brief description of the characterization quantities treated in the chapter, then outline the measurement setup, take a look at calibration and provide examples of measurement results as they appear on the ZNA display.

# 2 System Setup and Calibration of mmWave Converters

This chapter refers to the setup of mmWave measurements in general. In the context of the application note at hand, mmWave applications are understood as measurements that require one or more banded mmWave frequency converters in addition to the basic ZNA. For the sake of simplicity, only converters of the ZC family are considered here. In principle, older ZVA-Zxxx or converters from other suppliers are operated in the same way as ZCxxx, except for the features enabled by the USB interface of the ZCxxx. Neither can they be automatically recognized by ZNA software nor do they autonomously monitor their vital functions.

## 2.1 Fundamentals of converter operation

We begin with the fundamentals of mmWave converter operation. This can usually be skipped by readers who are familiar with mmWave converter operation.

mmWave converters are frequency extenders for vector network analyzers (VNAs). Similar to the VNA itself, they incorporate three sub-units: A frequency multiplier, which converts the VNA source signal to the mmWave range, a test set for the separation of outgoing and incoming waves, and a receiver unit with one or two downconverters, which translate one or both of the separated wave quantities to a frequency range receivable by the VNA. Fig. 1 shows a schematic of the mmWave converter R&S ZC110 for the band 75 GHz – 110 GHz (WM-2540<sup>1</sup>, also known as WR10<sup>2</sup>).

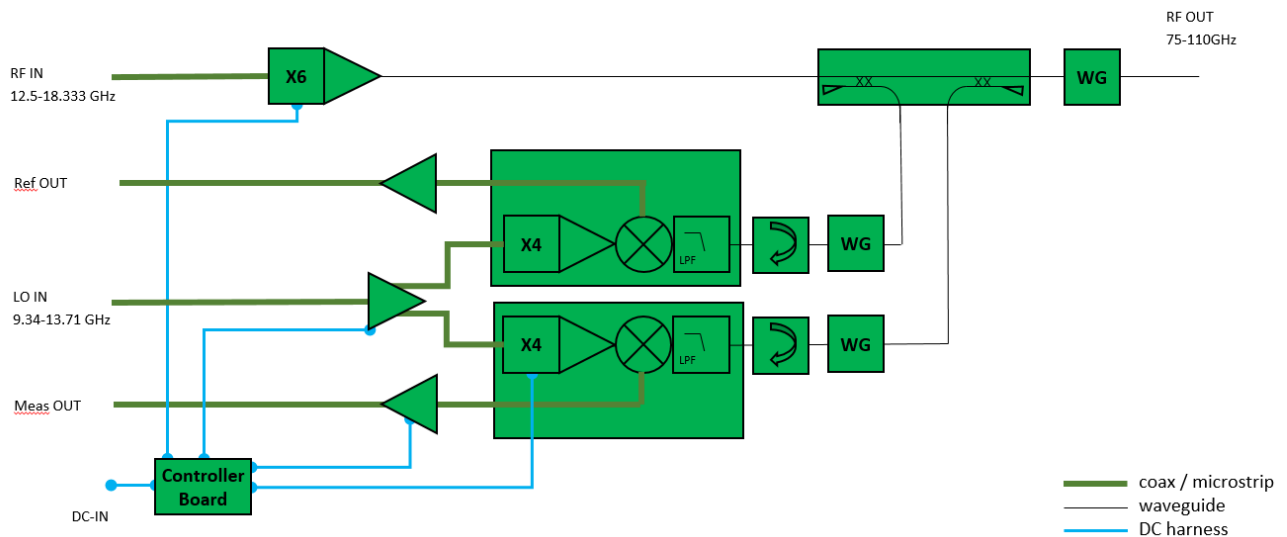


Fig. 1: ZC110 Schematic

The frequency of the stimulus signal fed into the converter via connector RF In is multiplied by a factor of 6. Then the signal enters the main branch of a dual directional coupler. Outgoing and incoming waves (from the converter's perspective) are coupled out and routed to the reference and the measurement receiver, respectively. Isolators and filters in front of the receiver inputs prevent higher-order mixing products from leaving the mixers and subsequently the test port, thereby causing unwanted measurement artifacts. The LO signal entering the converter via LO In is split and amplified, in some cases also multiplied, before being

<sup>1</sup> Band designation according to IEEE 1785

<sup>2</sup> Band designation according to EIA

applied to the mixers. The IF signal, typically at some 100 MHz, is amplified and conveyed to the IF outputs Ref Out and Meas Out.

With RF In, LO In and the two receiver outputs, a ZC110 features four RF connectors on its rear panel. There are two ways to connect the corresponding signal lines to the base ZNA. Fig. 2 shows the recommended one using inputs IF Reference <i> and IF Meas <i> of the ZNA, where i is the port number. These rear panel connectors come along with option ZNA-B26. Furthermore, as shown in Fig. 3, the converter IF can also be fed into the front panel inputs of option ZNA-B16 (direct source and receiver access). This corresponds to the connection scheme used for the R&S ZVA, which was the predecessor of the ZNA.

With both connection methods, the source signal is provided by the ZNA test port to which the converter has been assigned. Basically, it would also be possible to use the associated source output on the front panel, if option ZNA-B16 (direct source and receiver access) is installed, but usually this does not offer an advantage. The power available at the test port is normally sufficient for converter operation, and one must take care not to overload a converter input (10 dBm max).

The LO can be provided either by rear panel output Conv LO (if option ZNA-B8 is installed) or by any ZNA source yet unused in the current converter configuration. When a source has been selected as LO for a particular port, it becomes unavailable for other purposes in the setup. For example, test ports 1 and 2 have a common signal source, unless option R&S ZNA-B3 is installed. If a converter has been assigned to port 1, this source provides the RF signal for the converter and cannot simultaneously supply the LO. In this case, use e.g. port 3 or 4, if the R&S ZNA has 4 ports. Or install option R&S ZNA<xx>-B3 (3rd and 4th internal source). The converter setup dialog (see Fig. 4) tracks the usage of the available sources and does not allow for using a source twice within the converter configuration. However, source assignment conflicts arising from the operation of the device under test (DUT) itself are not detected.

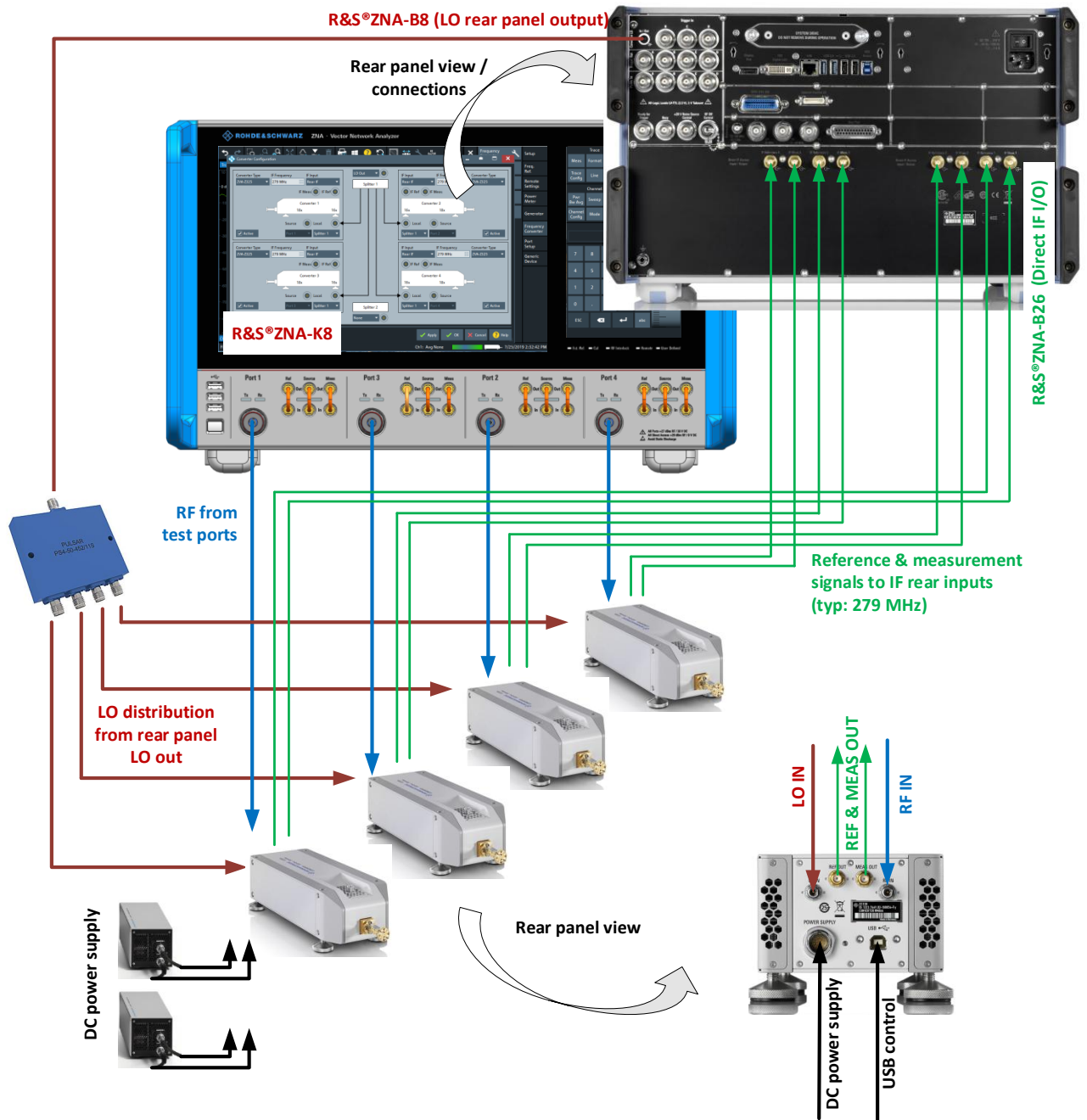


Fig. 2: Converter configuration with rear panel IF inputs

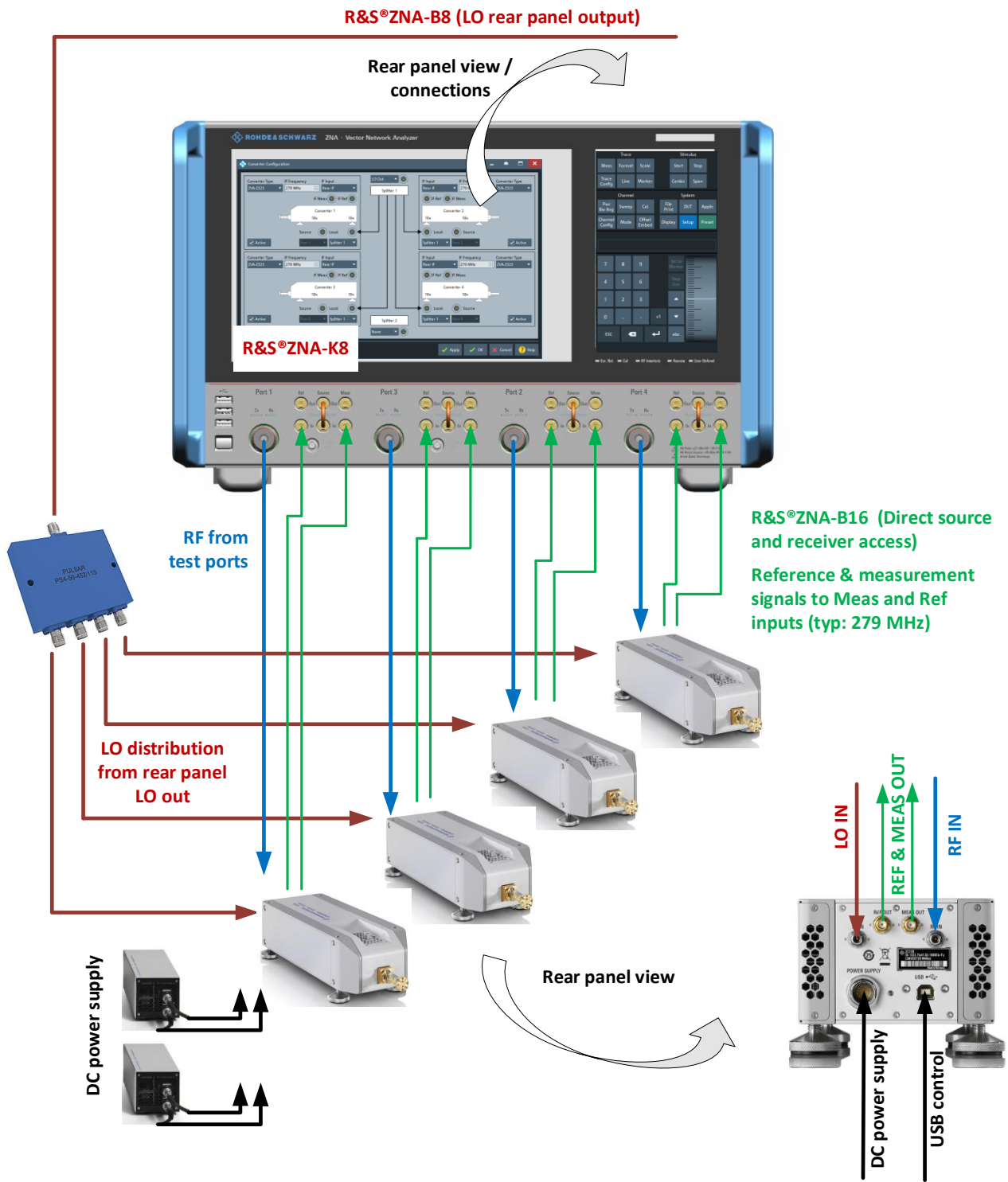


Fig. 3: Converter configuration with front panel direct source and receiver access inputs

## 2.2 Converter configuration via ZNA user interface

While the USB interface of ZCxxx converters allows the ZNA software to load the characteristic data of a converter, like source and LO multiplication factors, it cannot detect whether this converter is actually used in the current setup. Consequently, it cannot determine to which ZNA test port a particular converter has been connected. Therefore, the assignment of converters to ZNA test ports must be done manually via **Setup** → **Frequency Converter** → **Frequency Converter**.

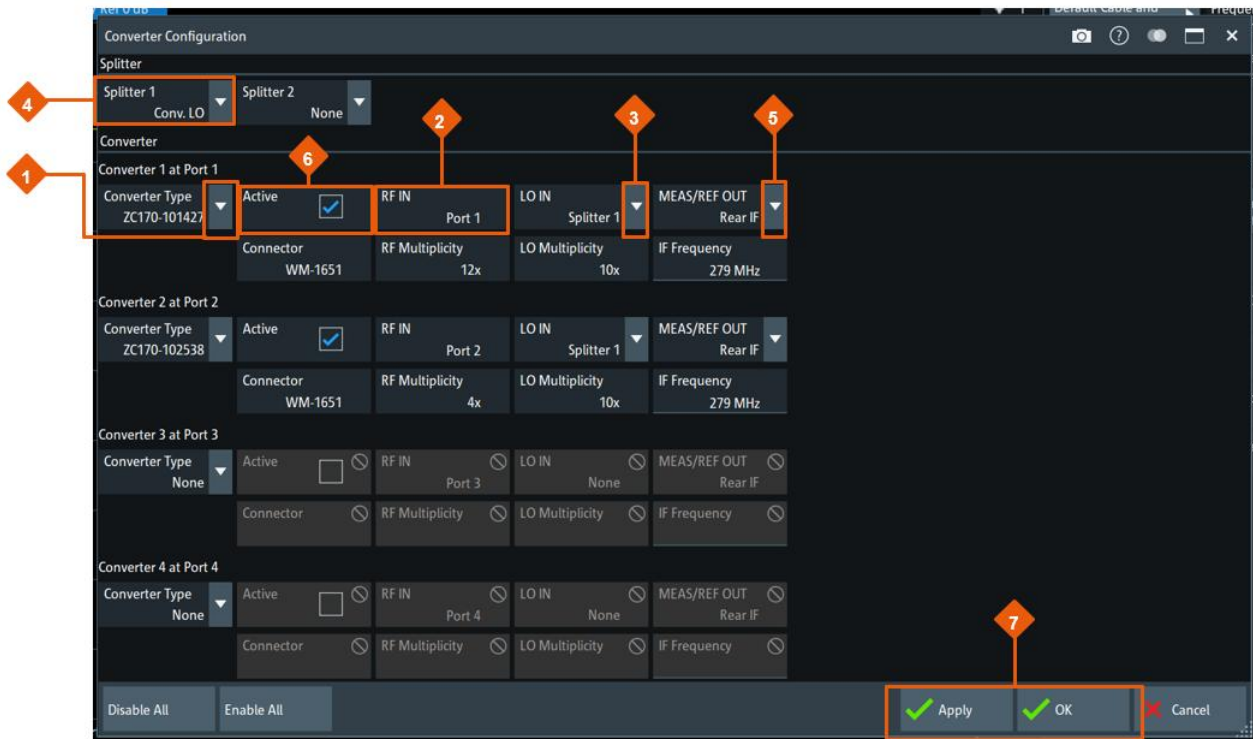


Fig. 4: Converter configuration dialog

1. For each port, dropdown list **Converter Type** offers all individual ZCxxx converters that have been connected via USB to the ZNA after the last factory preset. Note that resetting the ZNA to factory state also resets this list. Converters of the same type can be distinguished by their serial numbers. Furthermore, ZVA-Zxxx (1<sup>st</sup> converter generation from R&S) and types defined via **Configure Converter Types** can be selected.
2. The source signal for the converter must be provided by the source of the port to which the converter has been assigned. Therefore, field **RF IN** cannot be edited.
3. Dropdown field **LO IN**, however, offers all LO source options that are available.
4. If option ZNA-B8 is installed, output **Conv LO** in the **Splitter** field on the rear panel will be the preferred choice in many cases, since a) this does not “sacrifice” a complete port with all the valuable components not needed for a LO source (like coupler and receivers) and b) frequency (up to 26.5 GHz) and power (up to 20 dBm) ranges of this output optimally match the requirements of a R&S mmWave converter. In addition to the frequency sources of the ZNA that have not yet been assigned to an active converter port, all configured external generators are selectable. Furthermore, if the LO source feeds more than one converter, a n-way splitter ( $2 \leq n \leq 4$ ) can be inserted between source and converter. Dialog **Converter Configuration** offers two splitters, named **Splitter 1** and **Splitter 2**, which are associated with different LO sources.
5. Dropdown field **MEAS/REF OUT** allows the user to determine how the IF output signals of the respective converter are fed into the ZNA. If option ZNA-B26 is installed, one can feed them into the

rear panel IF inputs of the ZNA (option **Rear IF**) or, if option ZNA-B16 is installed, into the front panel connectors **Ref In** and **Meas In** (option ZNA<xxx>-B16 Direct Access).

6. If checkmark **Active** is set for a particular port, the respective converter will be activated when pressing **OK** or **Apply** (see below). Activating a converter means that the associated RF and LO sources are set to the frequency and power needed for proper operation of this converter. In this context, losses of cables and LO splitters can be taken into consideration, see chapter 2.3.1.1.
7. After having completed converter configuration, it can be activated by pressing either **OK**, which closes the dialog, or converters **Apply**, which leaves it open. This will only have a visible effect if at least one port has a converter assigned to it and if checkmark **Active** of this port has been set. Then the existing channels are replaced by a single one covering the highest frequency band among the active converters with default settings. This frequency range may not fit for all activated converter types, which possibly causes error messages.

ZNA firmware needs information about some basic characteristics of converters in order to be able to handle them correctly. Information e.g. about source multiplication factor and order of the harmonic of the mixers is obtained from data that is either individually assigned to and shipped with each converter (ZCxxx family) or integrated into the ZNA firmware (ZVA-Zxxx family). Subdialog **Converter Types** shown in Fig. 5 opens via **Setup → Frequency Converter → Configure Converter Types**.

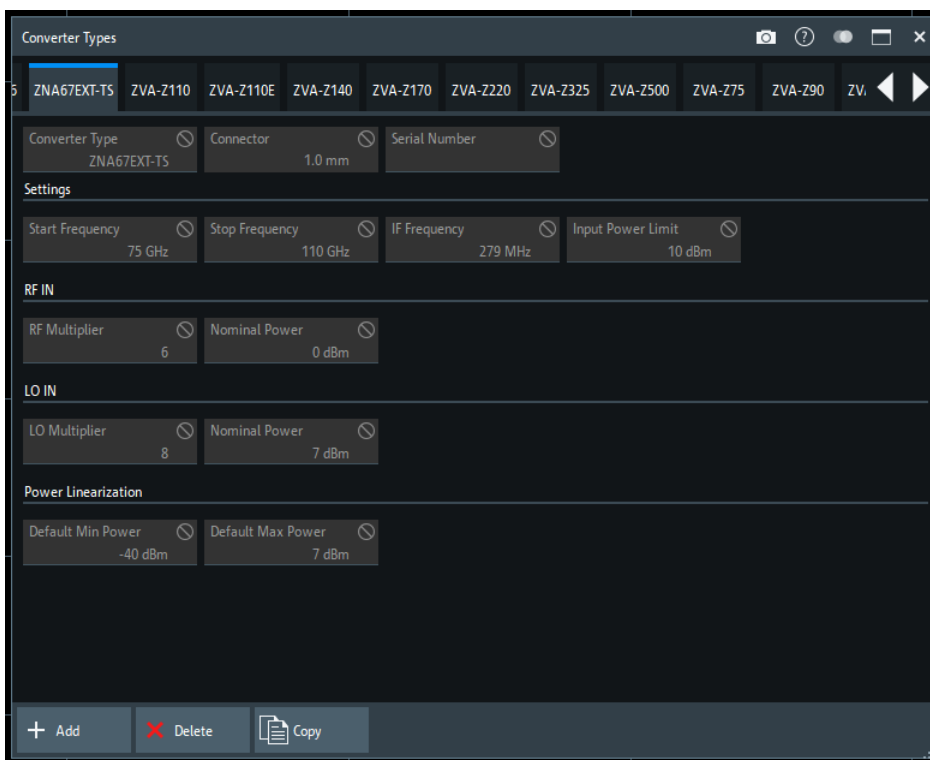


Fig. 5: Converter type configuration

Here, all converter types known to the ZNA are listed as tabs. For each type, frequency range, test port connector type, RF and LO multiplication factors and required input powers are displayed. The settings of converters that have been read from their built-in memory (e.g. ZCxxx) or those of predefined types (e.g. ZVA-Zxxx) cannot be edited. To change parameters for experimental purposes, create a copy of this converter first, edit the parameters, and select the copy. Or create a new type via **+ Add**.

Note that converter configuration and – if existing – related power linearization data are not only valid for the currently active channel or preset. This global setting is valid for all channels and will not be deleted by **System → Preset**, except in case that option **Normal, GUI, Ext. Setup** has been selected in the **Preset** menu.

## 2.3 Calibration

Since the hardware components of mmWave converters, as well as those of VNAs, cannot be assumed as ideal, their deviation from ideality must be mathematically corrected for to obtain accurate measurement results. For the fundamentals of system error and power calibration / correction, refer to the documentation of the ZNA. Nonlinear DUT behavior can be described by quantities like compression or intercept point. In this case, exact knowledge of the absolute powers of the waves incident on or coming from the DUT is required. For this purpose, one must perform a power calibration. The combination of system error and power calibration is called smarter calibration.

### 2.3.1 Ensuring proper power levels on the cables between ZNA and converter

Before looking at the various ways offered by ZNA firmware to calibrate the converter test ports, it will be discussed how the user can establish proper power levels in the signal lines connecting converter and base ZNA.

R&S mmWave converters are remote front ends of a complete VNA system, connected to the base ZNA via cables. Providing sufficient RF and LO input power to the converter is mandatory to obtain the specified output power and transmission dynamic range at the waveguide test port. R&S converters are designed for +7 dBm input power at both RF In and LO In, with a small tolerance region of few dBs below and above that value. Cable losses may compromise system operation severely if they exceed a certain amount. The following two chapters explain how to make sure that the required input power is available at the RF In and LO In connectors of the converter.

#### 2.3.1.1 Specifying cabling losses

Often ZNA and converters are set up on a table with minimum distances between the components. In a typical setup, source signal is fed to the converters via R&S ZV-Z19<x> cables with a maximum length of 1 m. To provide the LO signal, two cables of this type are connected in series with the power splitter in between. In such a scenario, it is sufficient to use the predefined cable loss model. The losses assumed by this model can be set via **Setup → Frequency Converter → Default Cable and Splitter Losses**. This opens the table shown in Fig. 6, here shown with default entries for the frequency-independent losses of cables and LO splitter. Regardless of the number of converters fed by a splitter, its default loss is set to 6 dB. This is a pretty good estimate for a configuration with two converters, in case a two-way splitter is used. For other numbers of converters, the value should be adapted to the actual number of splitter outputs. For longer LO cables, frequency-dependent loss can be modeled by a simple linear slope.

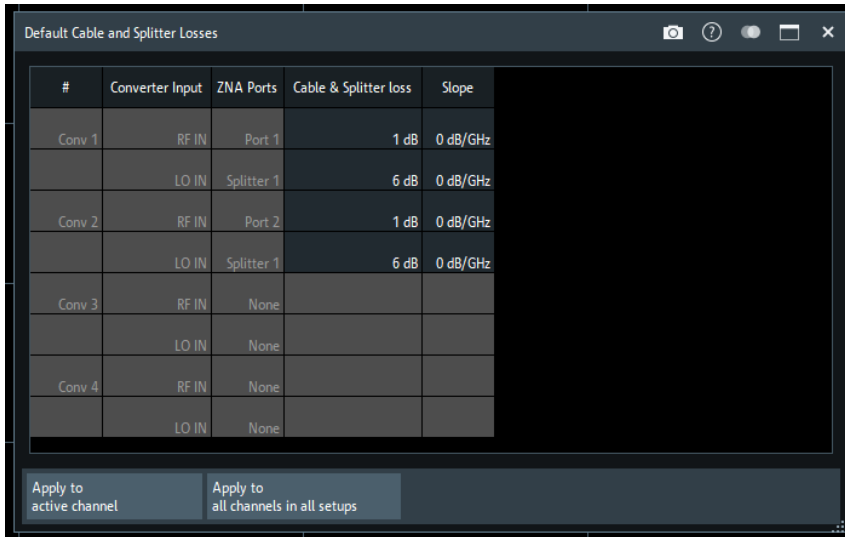


Fig. 6: Dialog Default Cable and Splitter Losses

Note that the losses set in dialog **Default Cable and Splitter Losses** become effective in the port configuration (**Channel Config** → **Port Config** → **Port Settings**) as soon as a converter configuration is activated via **Apply** or **OK** in the **Converter Configuration** dialog. Hence, the default losses should be set before activating a converter configuration. If converters have already been activated, however, losses can be belatedly corrected by changing the default loss values and pressing **Apply to active channel** or **Apply to all channels in all setups**.

### 2.3.1.2 LO input power calibration

In case transmission loss between LO source(s) and converter input(s) is not well known or does not increase linearly with frequency, it may be advisable to perform a power flatness calibration for the respective source(s). This flatness cal can be initiated via **Cal** → **Scalar Power Cal**, which makes the dialog appear that is shown in Fig. 7.

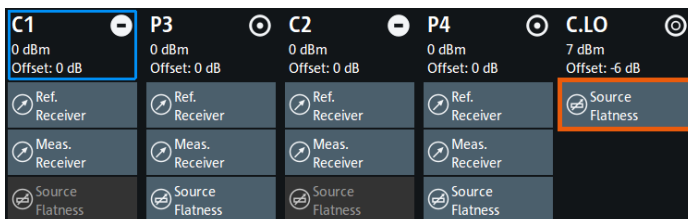


Fig. 7: Power flatness cal for LO source

Here, pressing **Source Flatness** in the rightmost column **C.LO** initiates a power flatness calibration of ZNA rear panel output Converter LO Out. Power flatness calibration is an iterative process, which loops through the two steps of measuring actual power and adjusting it by the difference wanted power - actual power, until this difference is within a user-defined tolerance window. For details of power flatness calibration, in particular with respect to its user-definable parameters, refer to ZNA documentation.

### 2.3.1.3 IF power considerations

In contrast to RF and LO power, IF power is usually of minor concern. By default, converters are operated at an IF frequency of 279 MHz, where cable losses are pretty low. Unless the IF signal path exhibits significant attenuation and / or IF frequency is considerably increased, IF losses will not lead to noticeable degradation of system characteristics, for example of dynamic range.

On the other hand, note that excessive IF power may drive the ZNA receivers in compression, which can lead to unexpected error-corrected measurement results. R&S converters are individually adjusted to provide -10 dBm at most. This is well below the 0.1 dB compression point of the IF inputs on the ZNA rear panel (option ZNA-B26), which amounts to -4 dBm. When feeding the IF into the front panel inputs of option ZNA-B16, it might be necessary to add external pads, since the 0.1 dB compression point is already reached around -8 dBm.

### 2.3.2 Test port scalar power calibration

This subchapter covers the simplest form of calibration, which is scalar power calibration. Only a power meter and through connections are required, except for measurement receiver self-calibration of a port. In the latter case an additional short circuit is needed.

**Cal** → **Scalar Power Cal** invokes the dialog already known from Fig. 7, here shown again in Fig. 8. Here, button **C1 Ref. Receiver** is marked, since this is the usual starting point for all power calibrations.

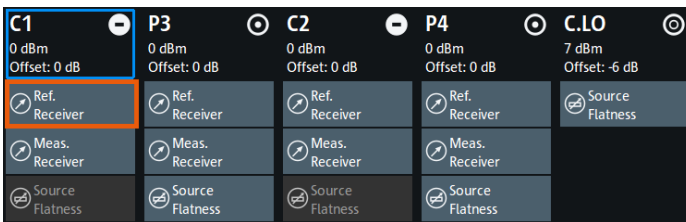


Fig. 8: Start dialog for power calibration

All ZNA ports are listed as columns of a table. Those to which a converter has been assigned are designated C<n>, where n is the port number, and marked with a waveguide flange symbol. Various calibration options are described in the following. The dialogs appearing during converter power calibration are the same as in ZNA baseband operation.

#### 2.3.2.1 Power meter configuration

Before being able to perform a power calibration at a converter test port, a suitable mmWave power meter must be configured. R&S NRP<xxx>TWG are thermocouple-based power meters with waveguide test port. They are available for frequencies up to 170 GHz. These power sensors just need to be connected to the USB bus, which is sufficient to have them configured automatically. For the widespread power meters PM4 and PM5 from VDI-Erickson, ZNA firmware includes pre-installed USB drivers. These instruments require one further step before being ready for use: Open the power meter configuration dialog via **Setup** → **Power Meter** → **Power Meters...** After having switched **Auto Config** off, The PM5 will appear in table **Known Devices** in the upper half of dialog **External Power Meters**, see Fig. 9. Then press the **+** button on the left side of this table entry.

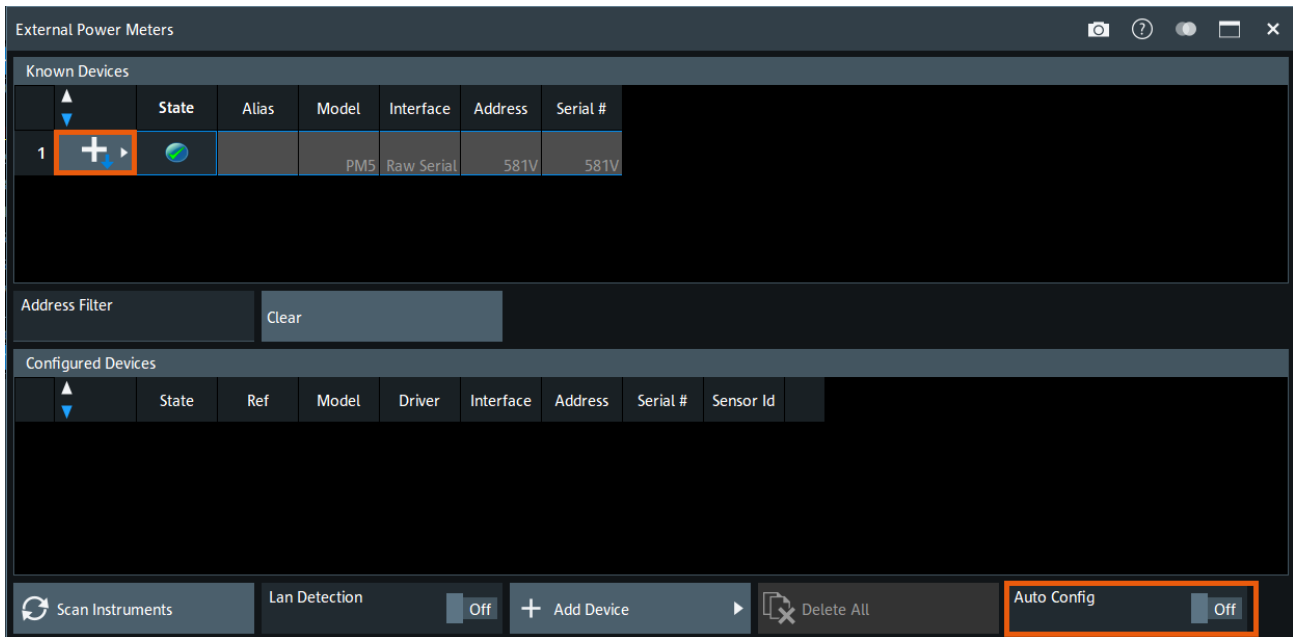


Fig. 9: Configuration of PM5: Step 1

This moves the PM5 to table **Configured Devices** in the lower half of the dialog, see Fig. 10:

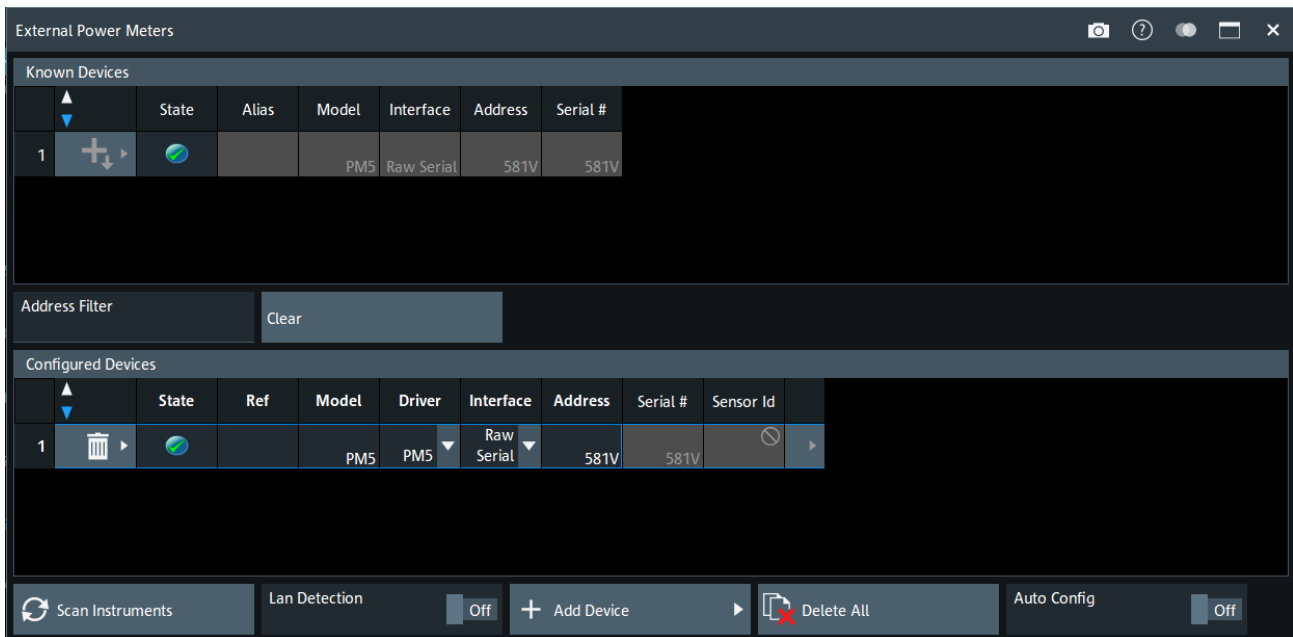


Fig. 10: Configuration of PM5: Step 2

Now the PM5 is available as Pmtr n, where n is the number in the first column of table **Configured Devices**.

### 2.3.2.2 Reference receiver calibration

Although it is possible to perform a pure source power flatness calibration by using only a power meter, it is recommended to start with a reference receiver calibration (button **Ref. Receiver** in Fig. 8). While power meters are able to measure the absolute power of a signal with high accuracy, they are inherently slow. This applies especially to those containing a thermocouple sensor or -even slower- that are based on the calorimeter principle, like the ones from VDI Erickson. In addition, power meters offer only limited dynamic range. In order to take advantage of the speed and measurement range of the heterodyne receivers of a

modern VNA, a transfer calibration from a power meter to one of the VNA receivers, typically the reference channel (a wave) receiver, can be performed. This transfer process, however, is afflicted with the drawback that most power meters are broadband and thus receive all spectral components of the signal, like harmonics, spurious and broadband noise. Total measured power is assigned to the signal amplitude detected by the narrowband reference receiver of the VNA. Since the latter signal carries only a part of the total spectral power, the calibrated reference receiver generally overestimates signal power. For converters, a discrepancy between broadband and narrowband power is mostly caused by subharmonics close to the stimulus frequency. For a ZC110 with a source multiplication factor of 6, for example, the 5<sup>th</sup> and 7<sup>th</sup> harmonic of the ZNA source frequency may appear within the waveguide band (here WM-2540) and can make the power measured by the meter differ by 2-3 dB from the a wave result. An obvious deviation, however, occurs only when power is changed after reference receiver cal, causing a change of the subharmonic content of the signal.

Clicking on button **Ref. Receiver** opens the dialog shown in Fig. 11

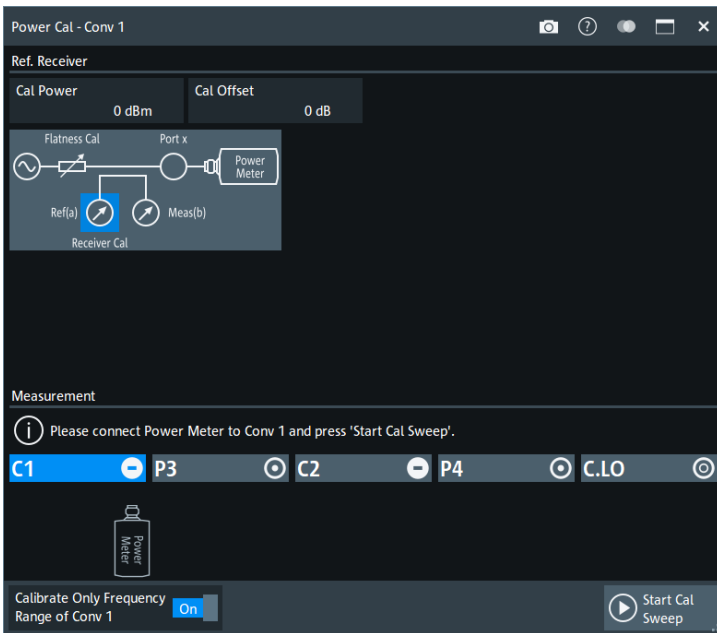


Fig. 11: Reference receiver calibration for converter power linearization

The calibration sweep can be started via **Start Cal Sweep**. Note that two traces are displayed: Power measured by the power meter and the a trace of the converter port to be calibrated. During the first sweep, these traces will differ, but from the second one on they will be congruent - if both measurements are stable. The congruence of the traces proves that the transfer calibration was successful, with the abovementioned accuracy restrictions caused by broadband reception of the power meter

### 2.3.2.3 Reference plane shift of power meter

For mmWave frequencies, only power meters with waveguide or coaxial connectors are available. Converters, however, are often used for on-wafer measurements. In this case, the wanted reference plane of the power calibration is probably located on wafer. Since a power meter can only be connected directly to the waveguide test port flange of the converter, the reference plane must be shifted to the wanted location. ZNA firmware provides this feature, if the two-port between waveguide flange of the probe tip and ref plane on wafer is known. **Cal → Power Cal Settings → Calibration (De-)Embedding** open the dialog shown in Fig. 12:

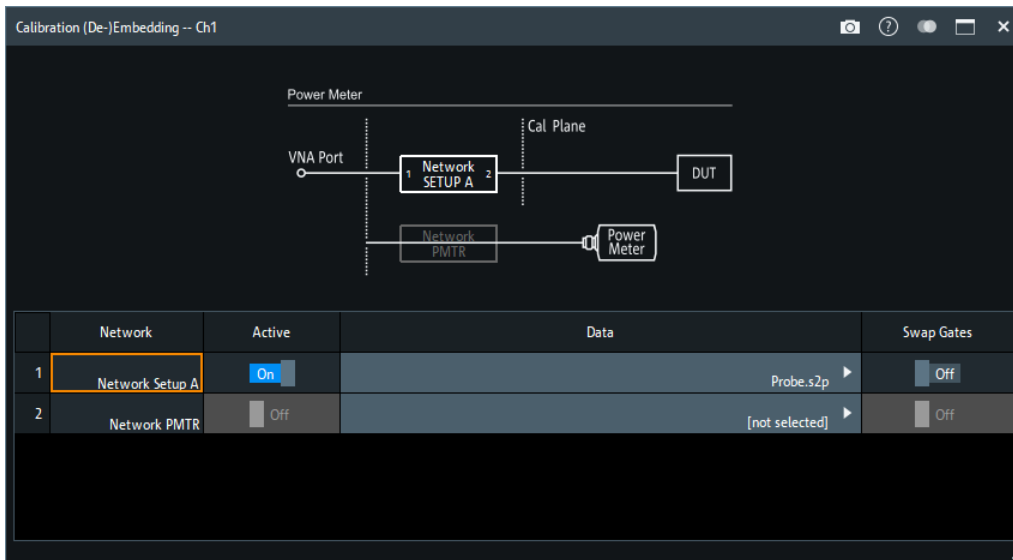


Fig. 12: Shifting the reference plane of a power calibration

The schematic shown in the dialog includes two scenarios that commonly require a shift of the reference plane:

1. The upper part of the schematic depicts the situation mentioned above: The power meter can only be connected to the waveguide port of the converter. After power meter measurement, the reference plane must be shifted. In this case, the two-port will comprise the probe itself, adapters between converter and probe, if applicable, and usually a piece of planar line between probe tips and on-wafer reference plane.
2. The lower part of the schematic addresses the case that a two port is placed between converter and power meter during power meter measurement. The power meter may, for example, be connected to the coupled arm of a coupler, thus enabling permanent converter output power measurement. In this case, measured power must be corrected by coupling loss. Another motivation for placing a coupler between converter and power meter could arise from the fact that the converter provides more output power than the meter can tolerate. Similarly, an attenuator could be placed in between. In these cases, the meter readings must be corrected accordingly.

Please note that both scenarios may apply in conjunction.

There are two approaches for obtaining the S-parameters of the two-port mentioned above:

1. Direct measurement: Since the connector types of the two-port are generally unequal (e.g. rectangular waveguide on one side and planar transmission line like microstrip or coplanar waveguide on the other), a calibration method allowing for this will be needed. This could be UOSM or adapter removal.
2. Indirect measurement: A so-called Delta Cal, which is invoked via **Cal: Cal Utilities: Delta Cal**, allows to determine the S-Parameters of Network Setup A or Network PMTR in Fig. 12 as difference between an "outer" and an "inner" calibration. For details, refer to the documentation of the ZNA.

### 2.3.2.4 Measurement receiver calibration

After having performed a reference receiver calibration at one of the VNA ports, the measurement receiver of any test port can be power calibrated, too. Press button **Meas Receiver** (see Fig. 8) of the port to be calibrated. If the ports of reference and measurement receiver calibrations are different, simply establish a through connection between the ports. In case the measurement receiver of the same port is to be calibrated, connect a flush short to the test port. ZNA firmware prompts the user to perform the correct action.

### 2.3.3 Source power linearization

Source power linearization (formerly called "leveling") designates the recording of a correction table that allows the user to set the wanted source power at the converter test port directly via the user interface of the ZNA. Due to the multiplier chain in the converter source path,  $P_{TPout}$  as a function of  $P_{RFIn}$  is nonlinear. The correction table represents the inverse of this nonlinear function, which means that it is used to determine the power  $P_{RFIn}$  the ZNA must provide to input RFIn to obtain a wanted  $P_{TPout}$ .  $P_{TPout}$  vs  $P_{RFIn}$  may be nonlinear but should be monotonically increasing to avoid ambiguities. This is the case for almost all ZC converters. Some converters exhibit a maximum of  $P_{TPout}$ , beyond which the output power decreases. But such behavior is recognized upon recording the table and  $P_{RFIn}$  will be limited.

After connecting a power meter to the converter test port (see 2.3.2.1), launch the linearization workflow via **Set-Up → Frequency Converter → Start Power Linearization**, which opens the dialog **Linearization Settings** shown in Fig. 13.

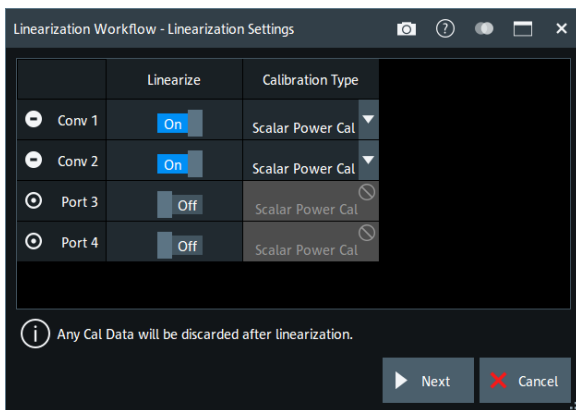


Fig. 13: Linearization Settings

Frequency converters that were configured as described in chapter 2.2 are automatically listed and enabled for linearization (field **Linearize** is **On**).

Drop-down **Calibration Type** influences the accuracy with which the absolute power is measured during initial reference receiver calibration. With default setting **Scalar Power Cal**, the unmodified reading of the power meter is assumed to represent the true power value. **Vector Power Cal**, on the other hand, applies a so-called smarter correction to the power meter reading. This removes power measurement uncertainties caused by mismatch between waveguide test port and power meter. For details, see chapter 2.3.5.2. However, since mmWave power meters, like all power meters, are generally well-matched, these uncertainties in most practical situations are small compared to the uncertainty due to harmonics and subharmonics, as explained in chapter 2.3.2.2. Thus, letting **Calibration Type** = **Scalar Power Cal** will provide satisfactory results in most cases.

Click **Next** to proceed to the **Grid Settings** (see Fig. 14).

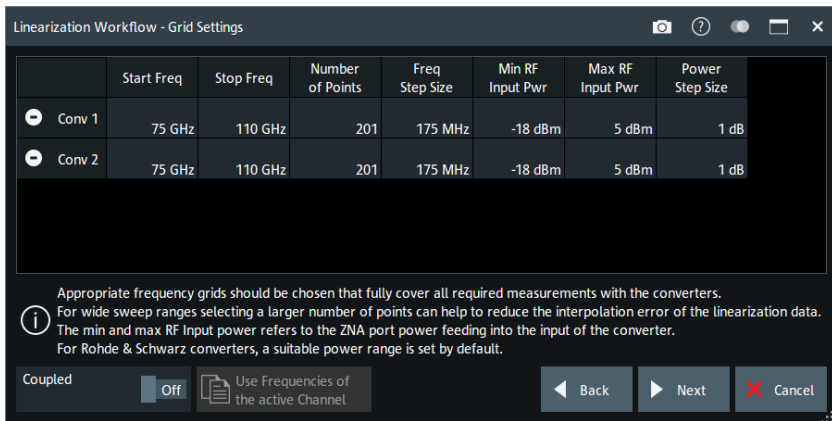


Fig. 14: Grid Settings

Entry fields **Start Freq**, **Stop Freq**, **Number of Points** and **Freq Step Size** allow the user to specify the frequency grid over which linearization data is to be recorded. If all configured converters operate in the same mmWave band, and if the measurement application does not imply frequency conversion, it is generally sufficient to define a common frequency grid for all converters. The default setting for this grid corresponds to the nominal full waveguide band, with 201 frequency points. In case converters for different bands have been configured, the default grid for each converter equals its respective band. For higher linearization accuracy and if the converter exhibits significant frequency response of the function  $P_{TPout}$  vs.  $P_{RFIn}$ , increasing the number of points will reduce interpolation error.

If measurements that require two-tone stimulus are to be performed, linearization frequency range should be chosen somewhat larger than the actual frequency range in order to accommodate for some margin. Calibration of intermodulation measurements, for example, is performed from **Start Freq** - 4  $\Delta f$  to **Stop Freq** + 5  $\Delta f$ , where  $\Delta f$  equals the **Delta Frequency** defined in **Meas** → **Intermodulation** → **Measurement Setup**. The asymmetry is caused by the fact that for intermodulation measurement, the lower tone equals the nominal frequency of a point, whereas for two-tone group delay measurements (option ZNA-K9) the two actual measurement frequencies are located symmetrically around the nominal frequency: **Delta Frequency/2** below and above.

For applications implying frequency conversion, e.g. with converters for different mmWave bands, it may be necessary to define individual linearization frequency ranges for each converter.

Note that entry fields **Number of Points** and **Freq Step Size**, like in the **Sweep** menu, represent a single internal parameter and thus mutually align to each other.

**Min** and **Max RF Input Power**, together with **Power Step Size**, determine the grid of power values applied to input RF In. For ZVA-Zxxx and older ZCxxx converters, the default ranges are provided by ZNA firmware, whereas newer ZCxxx come with their individual range stored in their internal flash memories. The default value of 1 dB for **Power Step Size** is appropriate for most converter types, if the slope of  $P_{TPout}$  vs  $P_{RFIn}$  is not too large. In former firmware versions (before 3.1) automatic level control (ALC) could only be activated if linearization had been performed with **Power Step Size** set to 1 dB, but this restriction is not valid any longer.

Clicking **Next** opens the **Grid Overview** (see Fig. 15), where one can finally check the frequency and power grids that will be used for power linearization:

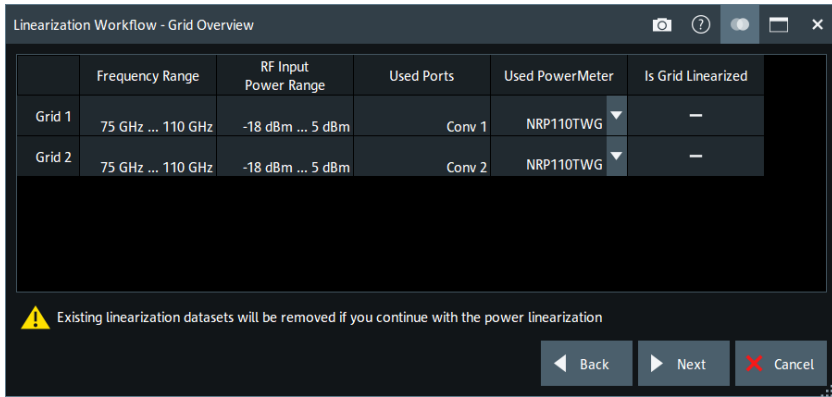


Fig. 15: Grid Overview

Note that proceeding to the next wizard dialog will delete any existing linearization data sets. If you want to keep this data, cancel now or save/export before continuing.

**Next** proceeds to the dialog shown in Fig. 16, from where the linearization can actually be initiated.

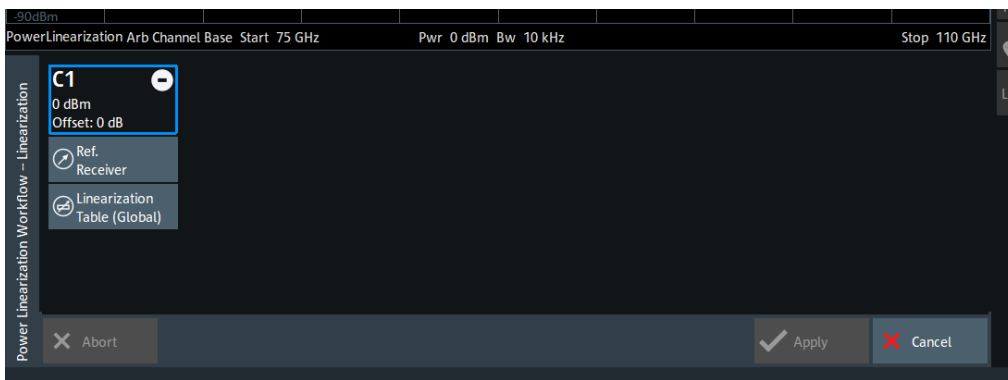


Fig. 16: Action buttons for performing the linearization

Since converter power linearization comprises a two-dimensional sweep over frequency and input power, a means is required for measuring the actual output power of the test port with high speed and over a large dynamic range. This is provided by a reference receiver calibration described previously in chapter 2.3.2.2. For linearization, the advantages mentioned there count for even more. Clicking button **Ref. Receiver** opens the same dialog as shown in Fig. 11, and the calibration process is identical to the one described there.

**Linearization Table (Global)** starts the two-dimensional sweep over frequency and power fed into RFIn. The measured converter output power at the test port is displayed as a family of traces with RFIn power as parameter (see Fig. 17.)

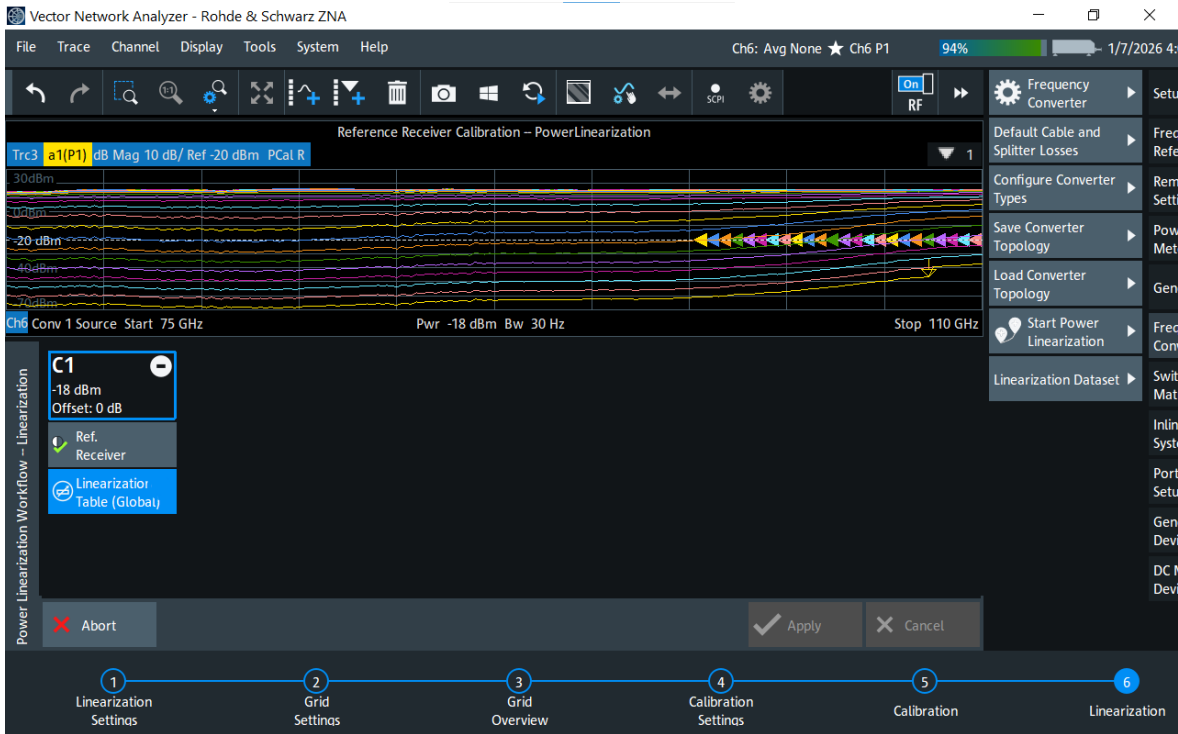


Fig. 17: Family of test port output power traces with RFIn power as parameter

**Setup: Frequency Converter: Linearization Dataset** opens the table shown in Fig. 18. A checkmark in column **Available** indicates that power linearization data is available. In this case, column **Power Control** allows activating or deactivating the use of the linearization data. If activated, the desired output power can directly be set via **Power Bw Avg: Power. Decimal Places** specifies the number of valid digits of frequency and power values in case that linearization data is exported as an ASCII file. When viewing the a wave of a linearized converter, one may note that the power may not be as flat over frequency as expected. These deviations are caused by interpolation errors. In order to obtain flatter converter output power, an additional power flatness calibration can be performed.

	Power Control	Available	Load	Save	Export	Remove
Converter/ Port 1	On	✓	📁	💾	📄	✖
Converter/ Port 2	On	✓	📁	💾	📄	✖
Converter/ Port 3	Off	—	📁	💾	📄	✖
Converter/ Port 4	Off	—	📁	💾	📄	✖

Decimal Places:  Apply OK Cancel

Fig. 18: Overview of available linearization datasets

### 2.3.4 Source power flatness calibration

Like for coaxial ports, a source power flatness calibration can be performed for converters, too. For details of this iterative calibration process, especially for the meaning of the parameters available in **Cal: Power Cal Settings**, refer to ZNA documentation. While for flatness calibration of a coaxial port, entry **Convergence** should be kept at its default value 1, a significantly smaller value (e.g. 0.1 to 0.3) will be appropriate for converters that have not been linearized previously. Keeping **Convergence** = 1 for an unlinearized converter will cause the iteration process to oscillate.

## 2.3.5 System error and smarter calibration

As mentioned previously, the fundamental concepts of system error calibration and correction are assumed to be known to the reader. Therefore, this chapter will focus on the peculiarities related to converters.

### 2.3.5.1 Preferred calibration method

One of these specifics is the availability of calibration standards and the resulting preference for particular calibration procedures. When working with converters, the transmission line type at the reference plane to be calibrated will in most cases be either a rectangular waveguide or a planar line type like coplanar waveguide (in case of on-wafer measurements). The open circuit is one of the standards frequently used in the coaxial world - and thus to be found in each commercial calibration kit. In waveguide, an Open cannot be built, since an open waveguide acts as a badly matched antenna with a return loss is about -13 dB. Such a device is unusable as calibration standard, especially since the exact value of its reflection coefficient depends on the free-space environment around the test port. Therefore, the open is replaced by an offset short, physically consisting of a zero-length Short ("flush" Short) offset by a  $\lambda/4$  offset line ("shim"). While the phase of the reflection coefficient is ideal ( $-180^\circ$ ) only close to the center of the respective waveguide band, this does not matter since deviations from ideality at the band edges are smaller than  $\pm 180^\circ$  and therefore do not cause singularities due to phase zeros. In terms of calibration method terminology, all methods containing an O for open keep their name (e.g. OSM or TOSM) with a shift in the meaning of letter "O": When referring to waveguide calibration, O stands for an "Offset Short" instead of an "Open".

When working with waveguides, OSM is mostly chosen for precise one-port calibrations like in the coaxial world, TOSM is not that widely used. The main reason for this is the fact that there is a better alternative: TRL: In coaxial, TRL is used almost exclusively in metrology, due to two reasons: 1. it is band-limited and 2. manipulation of a coaxial airline is tedious, especially at higher frequencies. These disadvantages do not apply to waveguide: A waveguide band is band-limited as well (less than an octave and thus more limiting than the 1:8 band usually assumed for TRL) and the line standard is very simple: In fact, it is just the aforementioned  $\lambda/4$  shim, which is part of every waveguide calibration kit. The flush Short is an easy-to-use reflect standard, and a Through in waveguide is the simplest standard of all: just connect the two waveguide ports. In addition, TRL is far less stringent than TOSM in terms of standard characterization. While TOSM requires all standards to be fully characterized a priori, attenuation of the TRL line needs not to be known, its length only approximately. One must know the phase of the reflection coefficient of the Reflect standard only with an uncertainty of  $\pm 90^\circ$ . To sum up, ease of use and non-requirements in terms of standard characterization make TRL the preferred calibration method in waveguide, even in case that just a one-port calibration is needed – if a second converter is available.

The same advantages also hold for on-wafer calibration. Planar lines are generally not band-limited, thus the disadvantage of covering only a 1:8 frequency range may carry more weight. But this can be overcome by using NIST multiline TRL instead of simple TRL. At mmWave frequencies, lines can exhibit some attenuation. For the multiline TRL procedure, this is even advantageous, since it increases accuracy.

### 2.3.5.2 Smarter calibration

A full system error calibration establishes the error coefficients of all calibrated ports with the exception of a common scalar factor. This factor can be determined by a reference receiver calibration at an arbitrary port. Such a combined system error and power calibration is referred to as smarter calibration in the context of ZNA firmware. The dialog shown in Fig. 19 is invoked by **Cal: Start Cal: Configure/Start Calibration**. Two steps are required to start a smarter cal. Switch **Power Cal** on, this enables the switches in the previously greyed table lines **Source Flatness** and **Rcv Power Cal**. Then switch on **Rcv Power Cal** in the column of the port where the power meter is to be connected. If a power meter has been configured, button **Start Cal** is enabled, and the calibration wizard can be started. For fundamentals of system error calibration and for details of the calibration workflow, refer to ZNA documentation.

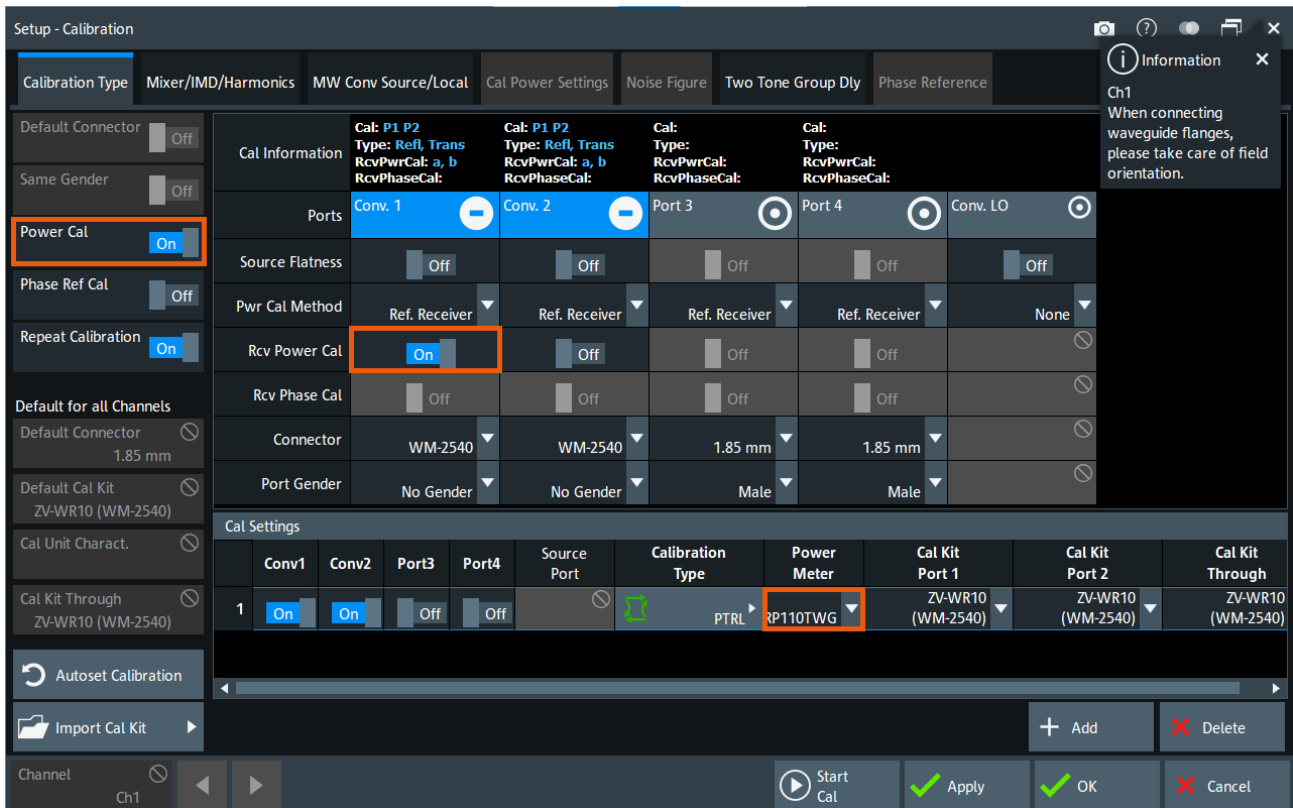


Fig. 19: Starting a smarter calibration

## 3 Linear Device Characteristics

A VNA system including converters, set up and calibrated according to chapter 2, is ready to measure the S-parameters of a non-frequency-converting DUT. After some initialization settings, which are described in chapter 3.2, a ZNA with converter can also measure match and conversion loss of a mixer. The fundamentals of these parameters, which describe the behavior of a linear circuit, will not be considered in the following. This chapter will focus on the specific features related to converter operation.

### 3.1 Non-converting DUT (amplifier)

When measuring an amplifier, care must be taken in order not to overload the measurement receiver of the VNA port connected to the output of the DUT. If a receiver overload is detected, a corresponding message appears on the ZNA display. Since there are no receiver step attenuators available for converters, either reduce DUT input power or place a waveguide attenuator between DUT output and associated converter test port. Attenuators with fixed attenuation as well as tunable ones are available e.g. from Radiometer Physics (WFA and WTA series). This method, however, is tainted with the disadvantage of decreased directivity of the converter connected to the output of the DUT. Lack of directivity may compromise the ability of this converter to measure the output reflection coefficient, which may induce ripple on the measured gain trace.

Some high-gain amplifiers (e.g. LNAs) require rather low source signal power when being measured. In addition to setting the source power electronically as described in chapter 2.3.3, source power can also be reduced with the help of the built-in waveguide tunable attenuator of the converter. ZC140 and all waveguide bands above are fitted with this feature, as well as the ZC75.

## 3.2 Frequency-converting DUT (mixer)

### 3.2.1 Mixer measurement setup

In principle, mmWave mixer measurements are set up in the same way as in the base ZNA. As an example, Fig. 20 shows how the measurement of a D-band harmonic mixer ( $n=10$ ) is set up via **Meas: Mixer Params: Setup Frequency Converting DUT...**

Parameter	Value
Input (RF) Freq	110 GHz ... 170 GHz
Input (RF) Base Freq	110 GHz ... 170 GHz
Input (RF) Power	0 dBm
Mixer 1 LO1 Mode	IF = RF - LO (Down)
Mixer 1 LO1 Freq	10.99 GHz ...
Mixer 1 LO1 Power	15 dB
Mixer 2 LO2 Mode	None
Output (IF) Freq	100 MHz
Output (IF) Power	0 dBm
DUT Multiplier	1 / 1
DUT LO1 Multiplier	10 / 1

Fig. 20: mmWave mixer measurement setup

This setup is based on a converter configuration with just a single converter assigned to port 1 (configuration not explicitly shown). All other ports remain with their coaxial base configuration. Port 2 receives the IF signal of the mixer, port 3 provides the LO, which is swept in parallel to the RF to provide a constant 100 MHz IF. The setup shown is only possible if option ZNA<xx>-B3 (third and fourth internal source) has been installed in the ZNA, since Port 1, 2 and 3 are all operated at different frequencies. Please note that Fig. 20 shows only the frequency conversion due to the DUT, whereas the port configuration depicted in Fig. 21 (**Channel Config: Port Config: Port Settings...**) also includes the RF and LO input frequencies of the converter. This provides a complete overview of the internal ZNA source and receiver frequencies.

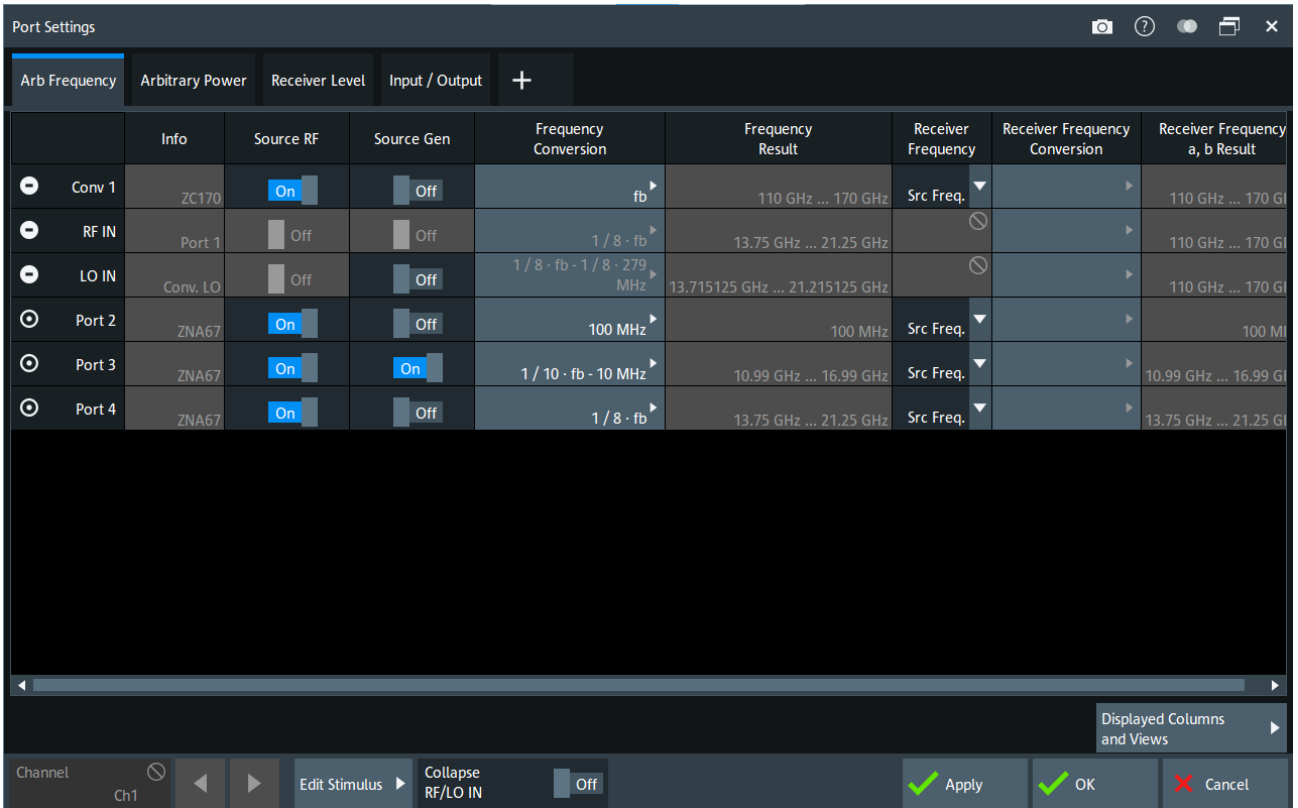


Fig. 21: Port configuration resulting from DUT frequency conversion settings of Fig. 20

### 3.2.2 Mixer measurement calibration

In case of a frequency converting measurement, conversion must be set up before starting calibration. By default, the setup from Fig. 20 results in the default calibration suggestion of Fig. 22.

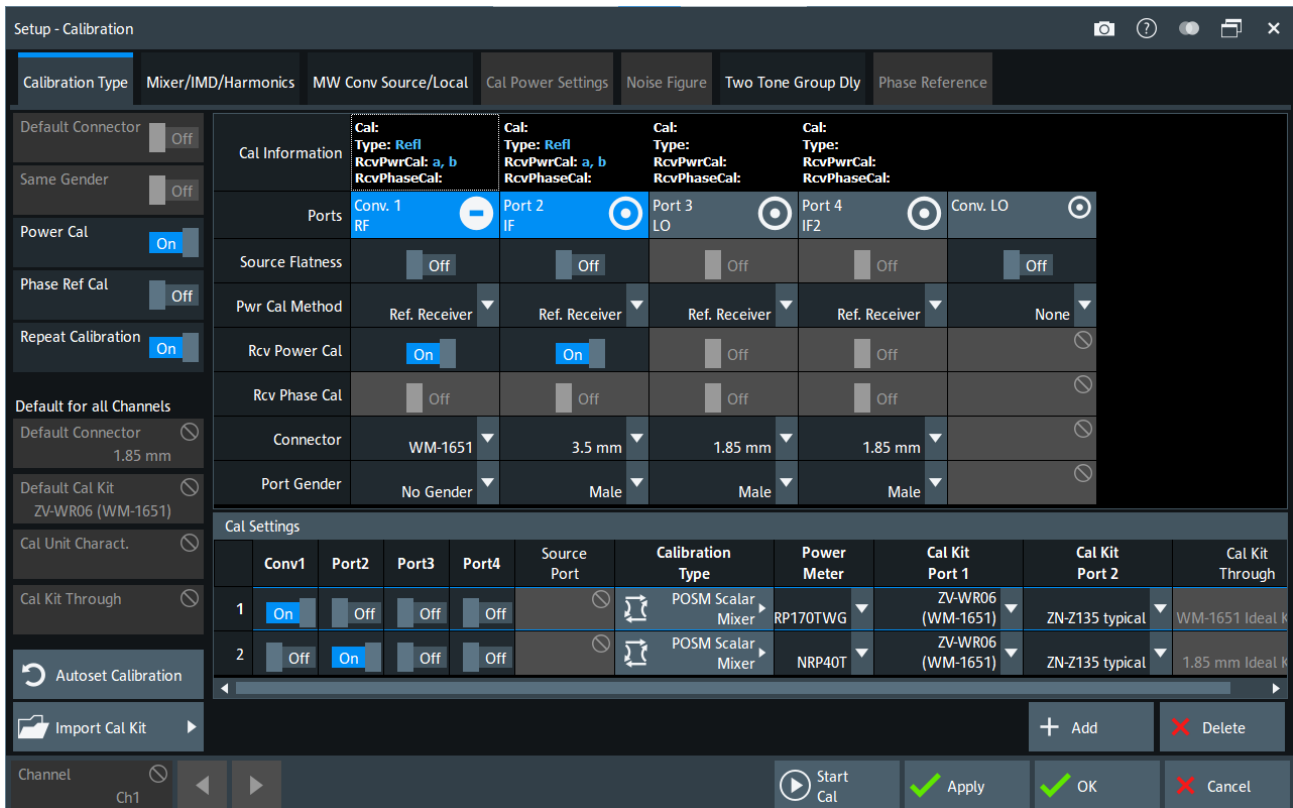


Fig. 22: Default suggestion for the calibration of mixer measurement of Fig. 20

Note that for both input and output ports of the mixer, a full one-port calibration is proposed. These will be performed at the frequencies associated with the RF and IF port frequency ranges of the mixer, respectively. The “P” in POSM, which stands for power, makes the ZNA conduct smarter calibrations in both frequency ranges. These smarter calibrations include absolute power calibrations for  $a_1$  and  $b_2$ , enabling the ZNA to measure the correct scalar value of conversion loss  $b_2/a_1$ . Although 2xPOSM is the most accurate calibration method for scalar mixer calibration, simple scalar power calibrations could do as well. Since the latter ones do not correct for multiple reflections between converter (test port 1) and RF port of DUT, the measured conversion loss might exhibit larger ripple. The IF is fixed at 100 MHz in this example, therefore multiple reflections between IF port of the DUT and ZNA test port 2 will not contribute to ripple. For typical measurement results with a scalar calibration, refer to Fig. 24 below.

### 3.2.3 Mixer group delay measurement

Group delay, which - in the case of a mixer - is the derivative of conversion loss phase vs frequency and a linear property of the mixer as well, cannot be measured with a simple scalar calibration as described in 0, because this does not provide any information about the conversion loss phase. Instead, a vector mixer calibration must be performed. For this type of calibration, basically the same requirements must be fulfilled as when operating the ZNA in its base frequency range. These are:

1. Option ZNA-K5 (Vector Mixer Measurement) is installed on the ZNA
2. The DUT mixer has an LO input that is accessible from outside (no embedded LO)
3. The LO signal for the DUT mixer is provided by an internal source of the ZNA, and the ZNA is operated in **Phase Mode = Coherence On** (preferably **Low Phase Noise**)
4. Either the DUT mixer itself must be reciprocal, or a reciprocal calibration mixer is available. Most passive mixers without amplifiers or isolators are sufficiently reciprocal by design. For group delay

measurement, even a constant phase offset between up- and down-conversion losses would be allowed

The process of vector mixer calibration, which is basically the same as in the base frequency range of the ZNA, is not exemplified here. For details, refer to ZNA documentation. Fig. 23 shows some linear characteristics – magnitude of conversion loss, RF and IF port match, conversion loss phase and group delay – obtained with vector mixer calibration. Besides the mixing diodes, this DUT does not contain potentially dispersive elements like filters or amplifiers. Therefore, group delay is rather flat, since it is mainly given by the lengths of the transmission lines inside the mixer. For comparison, the S-parameter magnitudes of the same mixer after a scalar mixer calibration are pictured in Fig. 24. Besides some minor ripple, the result is similar to the one obtained with vector mixer calibration. The latter screenshot also contains measurement results of the a-waves incident onto the RF and IF port, respectively. Not that  $a_2$  is a straight line since the IF frequency is constant in this example.

In case the mixer LO is not accessible from outside, a two-tone signal must be applied to the DUT. This requires a dual-source converter ZCDSxxx or two converters combined via a magic T. Furthermore, option ZNA-K9 (Group delay measurements on frequency converters without LO access) and a reference mixer with known group delay is needed. This reference mixer can be characterized e.g. via ZNA-K5 as sketched above. For details of option ZNA-K9, please refer to application note 1EZ81 from Rohde & Schwarz.



Fig. 23: D-band mixer measured with vector mixer calibration: Upper: Conversion loss, lower left: RF and IF port match, lower right: conversion phase and group delay



Fig. 24: Magnitudes of mixer S-parameters after scalar mixer calibration + incident waves of RF and IF port

# 4 Nonlinear Device Characteristics

Like the ZNA in its native frequency range, a ZNA with converter can also be used to determine quantities describing the nonlinear behavior of components. The most important figures to be mentioned in this context are compression point and intermodulation products.

## 4.1 Non-converting DUT (amplifier)

### 4.1.1 Compression point

To determine the compression point of an amplifier – with reference to the input or output of the DUT – a smarter calibration, as detailed in chapter 2.3.5, is sufficient. Here again, take care not to overload the measurement receiver of the converter connected to the DUT output. **Meas: Measurement Menu = S-Parameters: Gain Compression: Measurement Setup** calls the dialog shown in Fig. 25. The algorithm implemented in ZNA firmware performs a two-dimensional search for the wanted compression level of a transmission factor. The transmission factor can be selected via dropdown fields for source and receiver ports. In Fig. 25 Conv1 serves as source port is and Conv2 as receiver. Hence the compression of  $S_{21}$  is to be measured. At each frequency point of the grid given by **Start Frequency**, **Stop Frequency** and **Number of Points / Freq. Step Size**, source power is increased, beginning at **Start Power** with an increment defined by  $(\text{Stop Power} - \text{Start Power}) / (\text{Power Points} - 1)$ . As soon as  $S_{21}$  decreases by more than **Compression Value**, the power sweep stops. Depending on the quantity selected in the **Meas** menu (**Compression Point Power In** or **Compression Point Power Out**), the ZNA source or DUT output power at which the specified **Compression Value** is expected to be reached is determined by linear interpolation. If the wanted compression cannot be reached, e.g. because the source power of the converter is limited, a message appears. In this case, the measurement quantity **Compression Point Delta S-Param** indicates the degree of compression that can be reached at maximum source power.

Note that entry field **Step Att Receiving Port** has no effect if the DUT output signal is received by a mmWave converter.

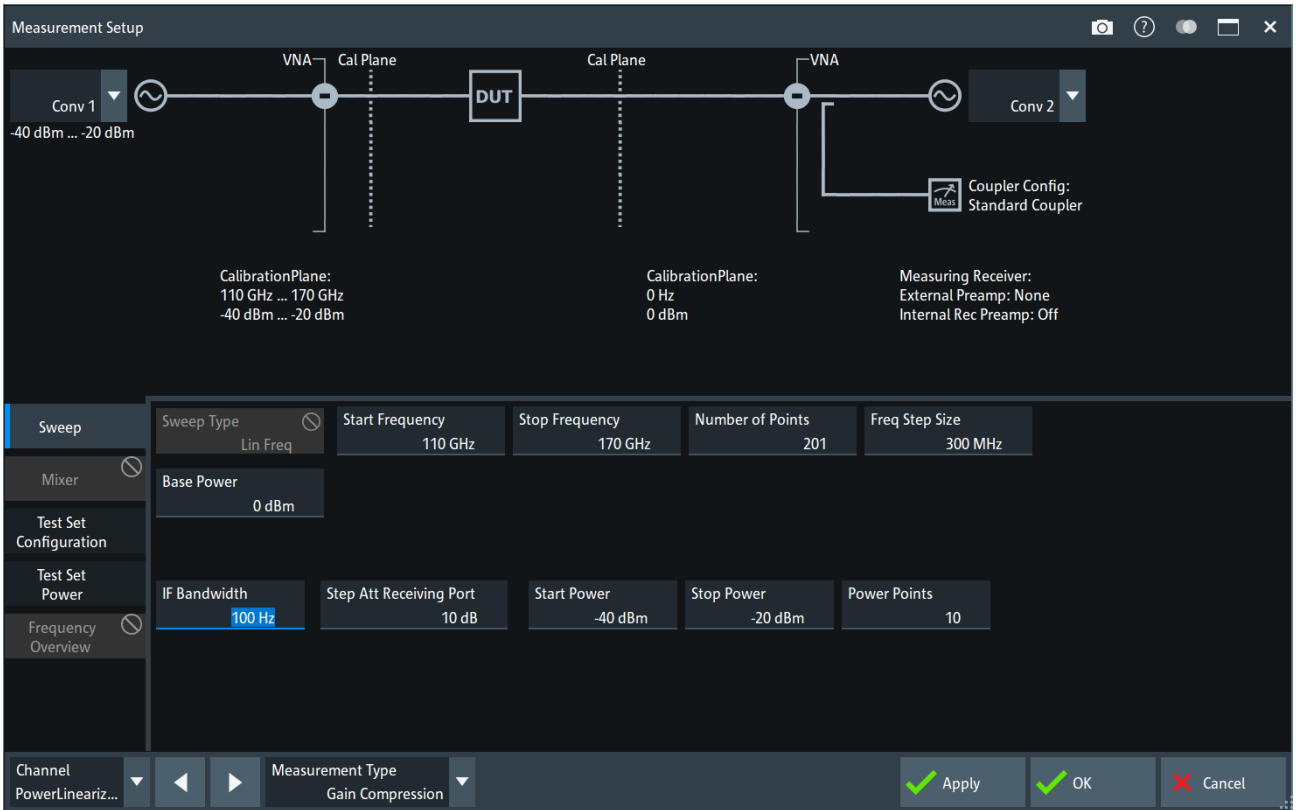


Fig. 25: Setup of compression point measurement of a D-band low noise amplifier

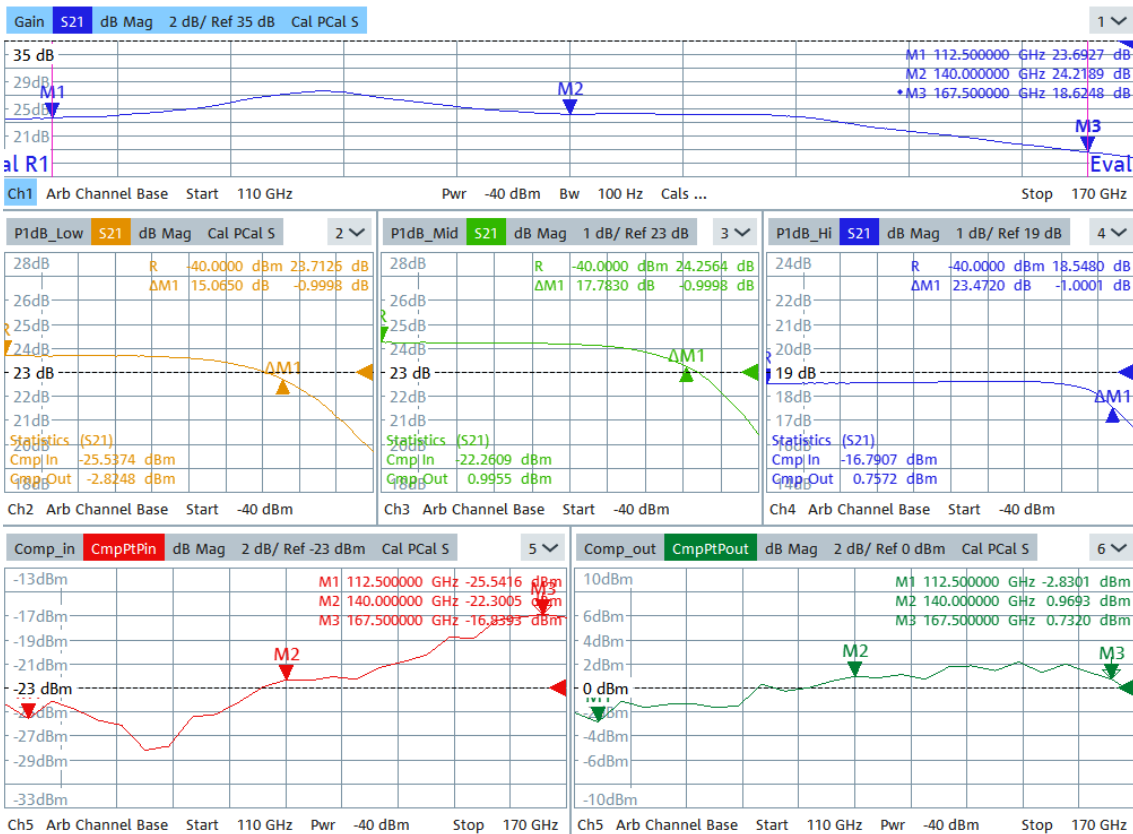


Fig. 26: D-band low noise amplifier: Upper: Gain vs frequency, middle: Gain vs power, lower: gain compression point vs frequency at input/output

The upper trace in Fig. 26 shows the small-signal gain of a D-band LNA when driven with a source power far below compression (-40 dBm). In the lower diagrams, one can see input (left) and output (right) 1 dB compression point vs frequency, measured in a 2D sweep as described above. To check the validity of the results, a power sweep was performed for each of the three frequencies labeled with marker M1 to M3 (middle row of diagrams). The corresponding 1 dB compression points at input and output of the DUT were determined with the help of **Trace Config: Trace Statistics: Compression Point**, showing good agreement with the 2D sweep.

### 4.1.2 Intermodulation

Intermodulation measurements require a two-tone stimulus signal. While it is possible to combine two normal ZC converters, for example with the help of a magic T, using a dual-source converter like e.g. the ZCDS170 is much easier and more convenient. In this case, the combined a-waves can be measured with a single reference receiver, which is not possible when an external combiner is used. **Fehler! Verweisquelle konnte nicht gefunden werden.** illustrates a typical converter configuration with port 1 and 3 as dual sources. This is the only port assignment allowed for dual-source converters. In case one selects a dual-source converter for port 1, port 3 automatically adopts the second source of the same converter, and its dropdown field becomes disabled.

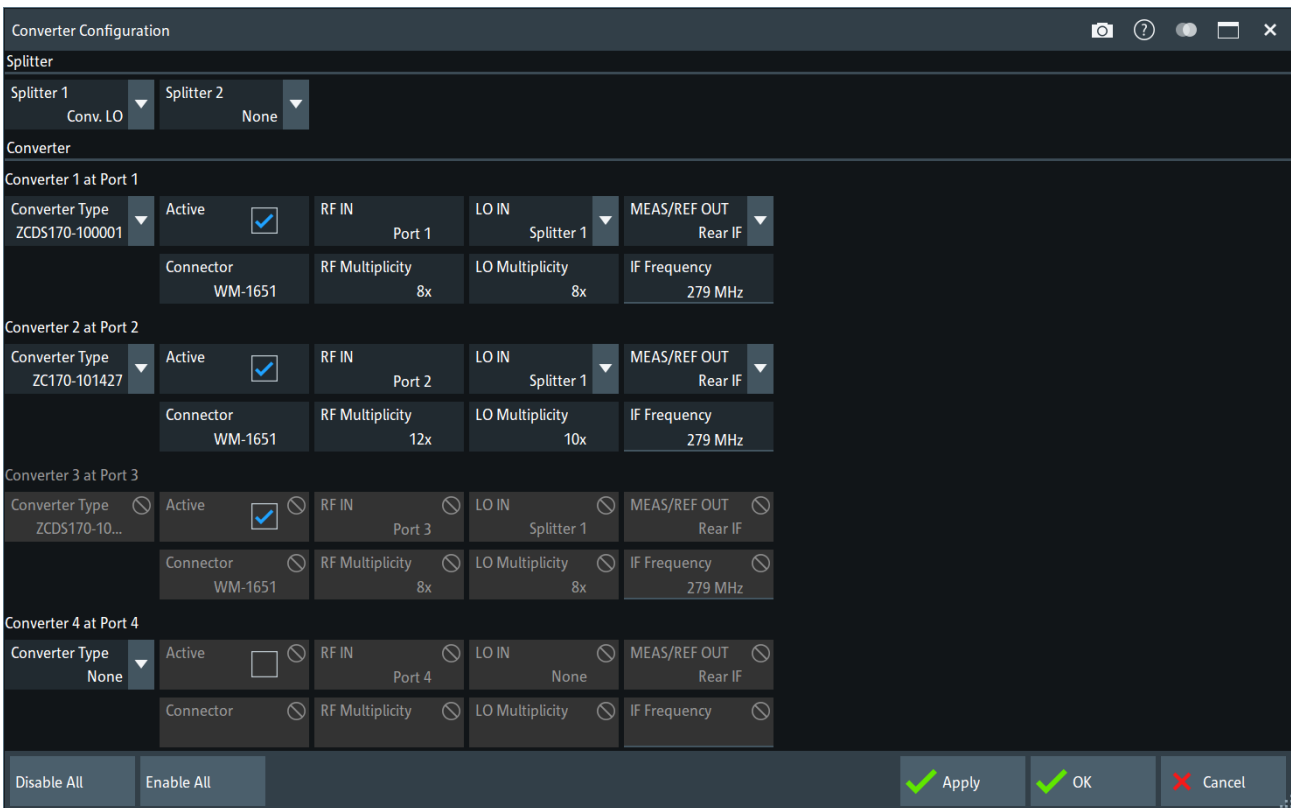


Fig. 27: Dual-source converter configuration for non-frequency-converting DUT

Currently (FW version 3.2) it is necessary to split the converter IF output signals Meas Out and Ref Out to ZNA rear panel inputs IF Meas and IF Reference, e.g. with the help of a SMA T junction and two additional IF cables.

Before starting calibration, the intermodulation measurement must be set up via **Meas: Intermodulation: Measurement Setup**. With the converter configuration of **Fehler! Verweisquelle konnte nicht gefunden werden.**, the setup of Fig. 28 and the default calibrations offered for this setup (Fig. 29), one obtains the result shown in Fig. 30. Previously, a source power linearization has been performed. For details of intermodulation calibration, refer to ZNA documentation.

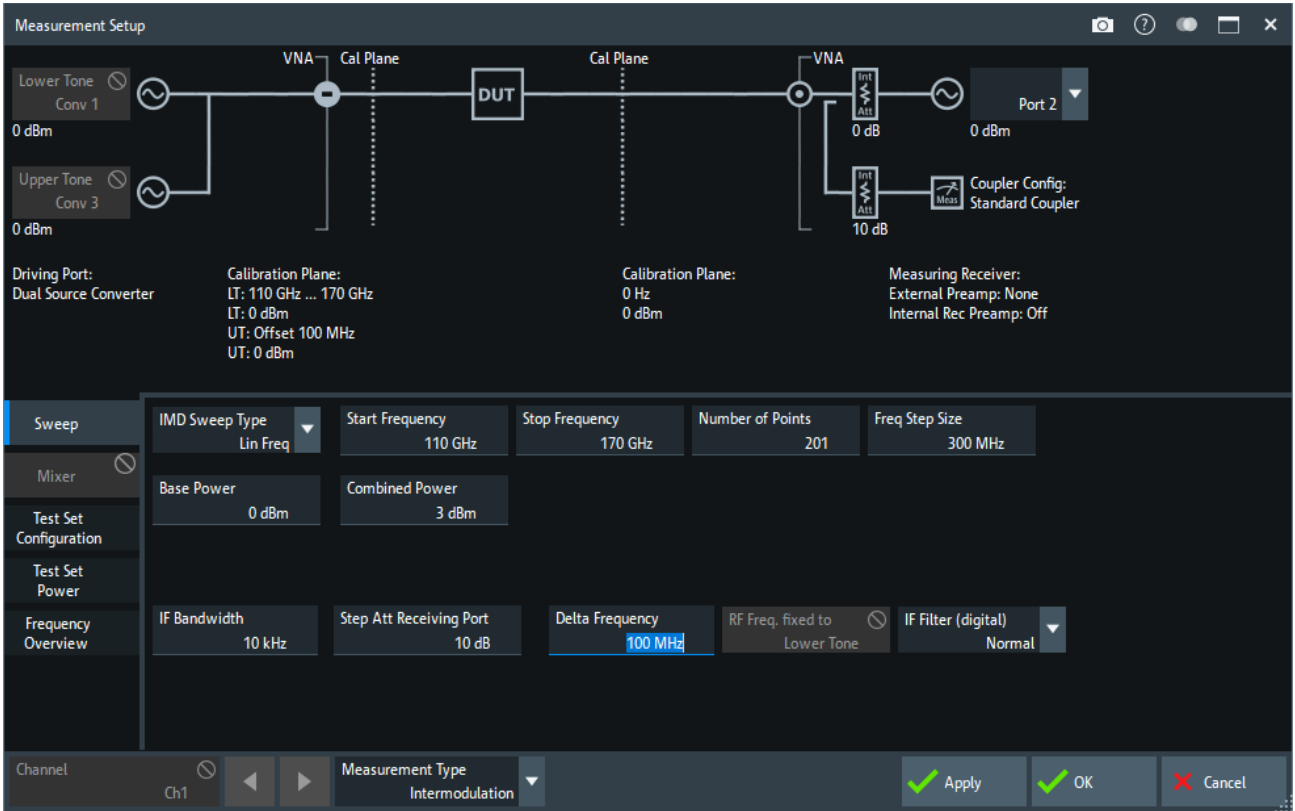


Fig. 28: Amplifier intermodulation measurement setup

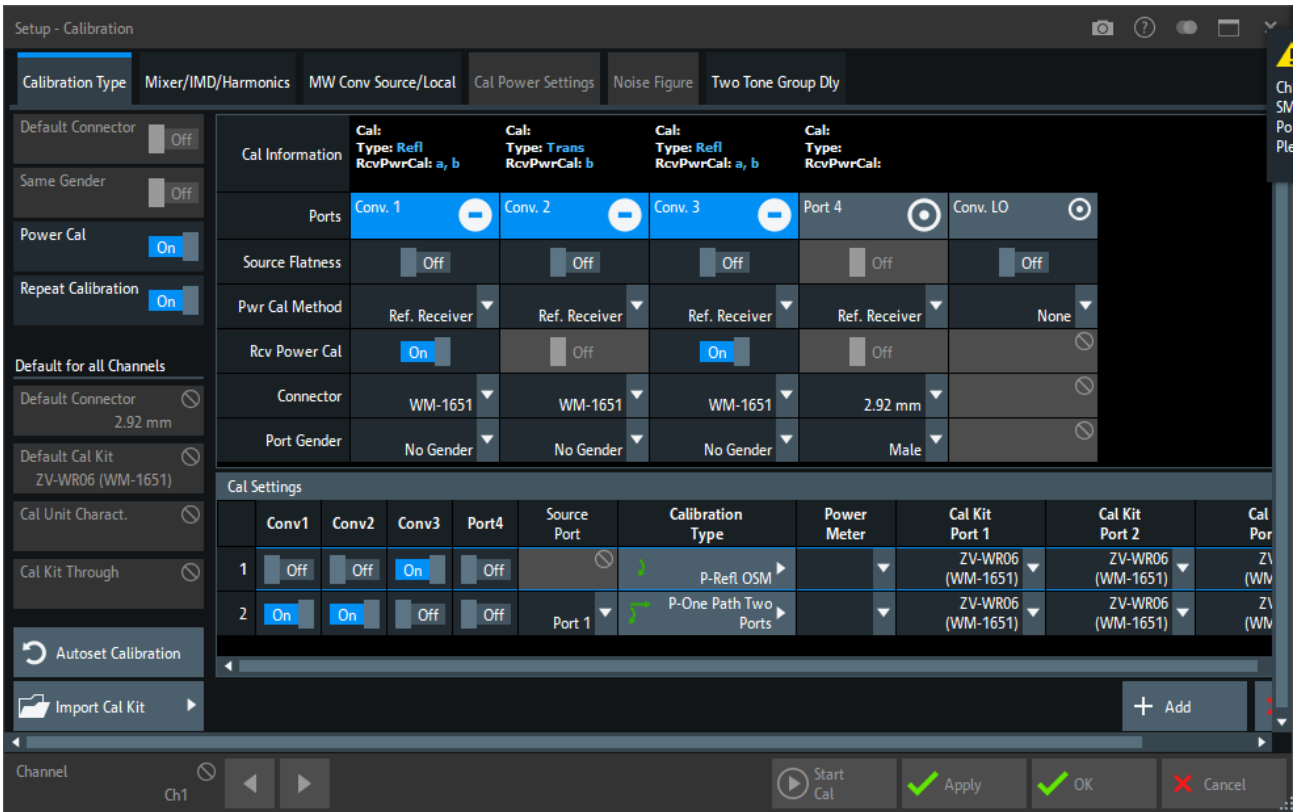


Fig. 29: Default calibration for intermodulation measurement



Fig. 30: Intermodulation measurement of a D-band LNA

The upper diagram shows the fundamental tones LTO and UTO, the upper and lower 3<sup>rd</sup> order intermodulation products IM3LO and IM3UO as well as the resulting 3<sup>rd</sup> order intercept point IP3MO. To make sure that the intermodulation products are real signals above noise floor, the noise floor NO is included, too. All measured quantities are related to the output of the DUT, indicated by an O in the name of the quantity.

The lower row of diagrams depicts spectrum views of fundamental tones and 3<sup>rd</sup> order intermodulation products, obtained with the help of **Spectrum = Marker**. This creates a new channel in which the two stimulus signals (fundamental tones) are kept constant, such that the frequency of the lower tone corresponds to the position of the active marker, and the receiver is swept in spectrum analysis mode as with option ZNA-K1.

Note that to obtain these graphs, the frequency grids of converter source linearization, calibration and IMD measurement were chosen in a way that all frequencies of interest (fundamental tones and intermodulation products) were placed on grid points, hence no interpolation was required. If interpolation is allowed, increased ripple on the measured traces may result.

## 4.2 Frequency-converting DUT (mixer)

### 4.2.1 Compression point

With the same harmonic mixer as used for chapter 3.2 in the same frequency conversion configuration and with the same smarter calibration, the compression behavior depicted in Fig. 31 was measured. As for the amplifier measurement (Fig. 26), the powers for 1 dB compression at the mixer's input and output were verified by explicit power sweeps at three frequency points. Again, the results agree well.

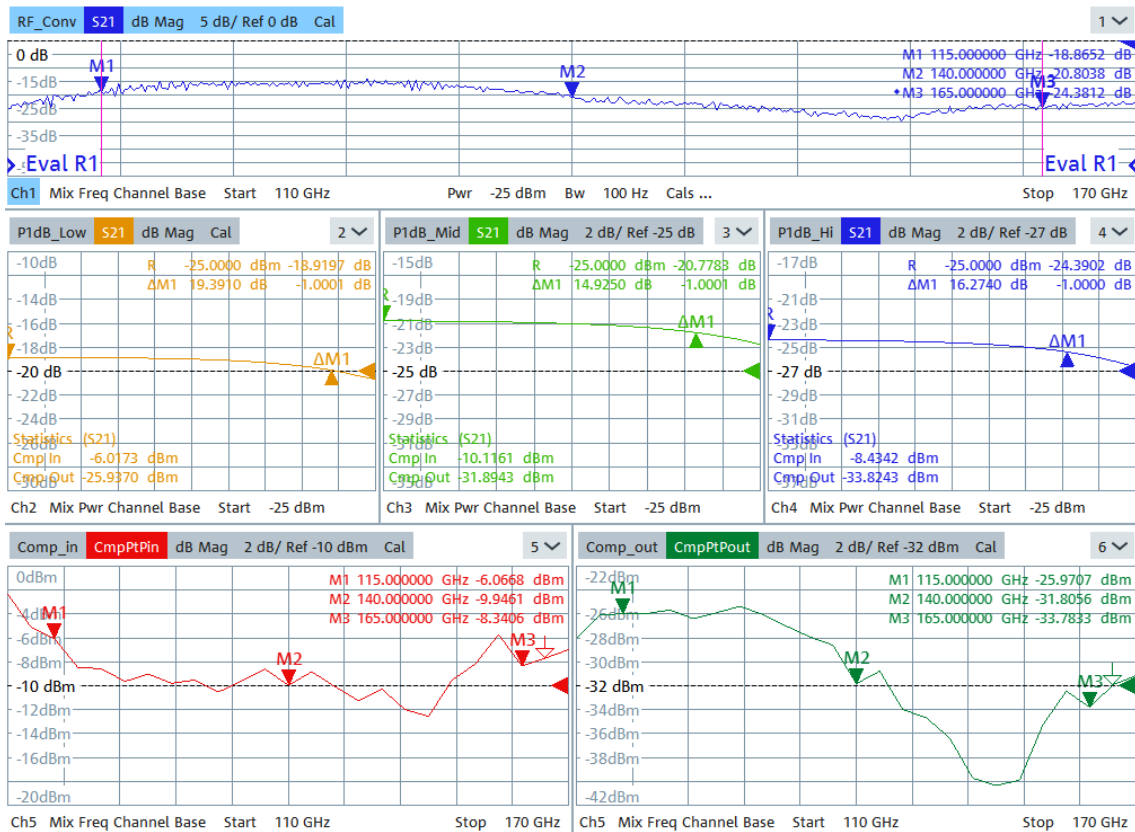


Fig. 31: D-band mixer compression measurement

## 4.2.2 Intermodulation

For the mixer, Fig. 32 shows the same intermodulation measurement quantities as Fig. 30 for the amplifier. And, as in this case, the spectral views confirm the swept-frequency results for selected frequency points. Again, source power linearization and smarter calibration were performed with frequency grids avoiding the need for interpolation.

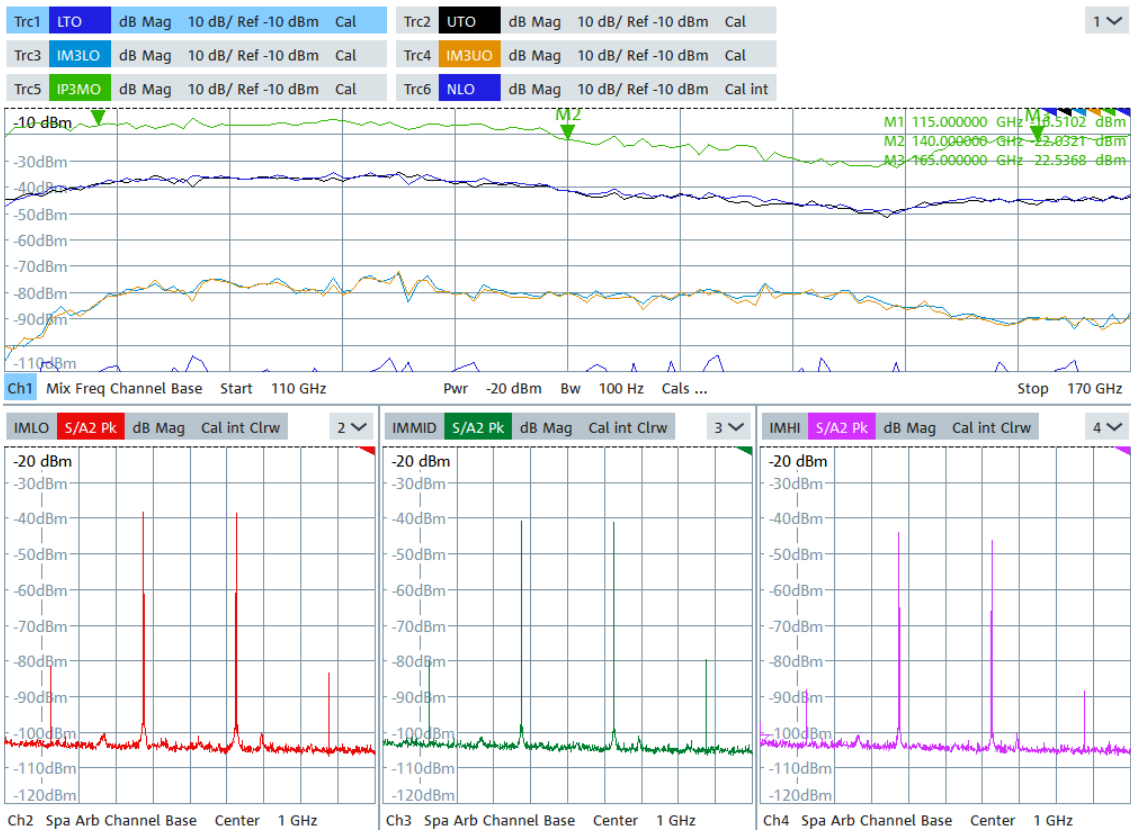


Fig. 32: Intermodulation measurement on D-band mixer

# 5 Ordering information

Designation	Type	Order No.
Vector Network Analyzer	R&S®ZNA<xx>	Refer to data sheet ZNA
mmWave Converters	R&S®ZC<xxx>	Refer to data sheet ZCxxx

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